

Weak Measurements

From incompatible observables
measurement to contextuality tests

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FP7: BRISQ2

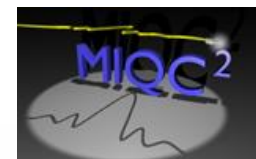


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Weak measurements

Weak measurements [Aharonov et al., PRL 60 (1988)]: little information is extracted from a single measurement, but the state does NOT collapse.

Weak value: $\langle \hat{A} \rangle_w = \frac{\langle \psi_f | \hat{A} | \psi_i \rangle}{\langle \psi_f | \psi_i \rangle}$

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\hat{X} and \hat{P}
canonically
conjugated

In the weak interaction
regime approximation:

$$\langle \hat{X} \rangle = \frac{\langle \phi_{out} | \hat{X} | \phi_{out} \rangle}{\langle \psi_i | \hat{\Pi}_f | \psi_i \rangle} = g \operatorname{Re}[\langle \hat{A} \rangle_w]$$

Weak measurements

Some interesting properties:

$\langle \hat{A} \rangle_w$ is a complex number

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- Expectation values as averages of weak values [Aharonov and Botero, PRA 72 (2005)]

$$\langle A \rangle_i = \sum_f |\langle \psi_i | \psi_f \rangle|^2 \langle \hat{A} \rangle_w$$

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$$\langle A \rangle_i = \sum_f |\langle \psi_i | \psi_f \rangle|^2 \langle \hat{A} \rangle_w$$
- POVMs can be realized as a sequence of weak values [Oreshkov and Brun, PRL 95 (2005)]

Possible applications

☐ **Metrology:**

☐ **Foundations of Quantum Mechanics:**



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➤ Amplification of measurement of coupling strength:

- Light beam displacement [Kwiat et al.]
- Angular deflection [Dixon et al.]
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- Hints on Quantum Mechanics interpretations [TSVF, Aharonov et al., ...]

“Sharp” measurement in QM

Standard "sharp" measurement:

$$\hat{A} = \sum_n \lambda_n \hat{\Pi}_n \quad \hat{\Pi}_n = |\psi_n\rangle\langle\psi_n| \quad \text{Tr}[\hat{A}\hat{\rho}] = \sum_n \lambda_n \text{Tr}[\hat{\Pi}_n\hat{\rho}]$$

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$$\hat{\rho} \xRightarrow{\hat{\Pi}_k} |\psi_k\rangle \quad \text{Prob}(\psi_n|\rho) = \text{Tr}[\hat{\Pi}_n\hat{\rho}]$$

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Joint/sequential projective measurements:

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**Wave function
collapse**



**Non-commuting
observables can't be
simultaneously
measured!**

$$\text{Tr} \left[\hat{\Pi}_n \left(\hat{\Pi}_k \hat{\rho} \hat{\Pi}_k \right) \right] = \text{Prob}(\psi_n|\psi_k) \text{Prob}(\psi_k|\rho)$$

Joint and sequential weak measurements

Weak values «*challenge one of the canonical dicta of QM: that non commuting observables cannot be simultaneously measured*»

«*the fact that one hardly disturbs the systems in making WM means that one can in principle measure different variables in succession*» [Mitchison, Jozsa and Popescu, PRA 76 (2007)]

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Joint weak measurement

Resch et al., PRL 92, 130402 (2004)

$$\hat{U} = \exp[-i(g_x \hat{A} \otimes \hat{P}_x + g_y \hat{B} \otimes \hat{P}_y)]$$

$$\langle \hat{X} \hat{Y} \rangle = \frac{1}{4} g_x g_y \text{Re} \left[\langle \hat{A} \hat{B} + \hat{B} \hat{A} \rangle_w + 2 \langle \hat{A} \rangle_w^* \langle \hat{B} \rangle_w \right]$$

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Sequential weak measurement

Mitchinson et al., PRA 76, 062105 (2007)

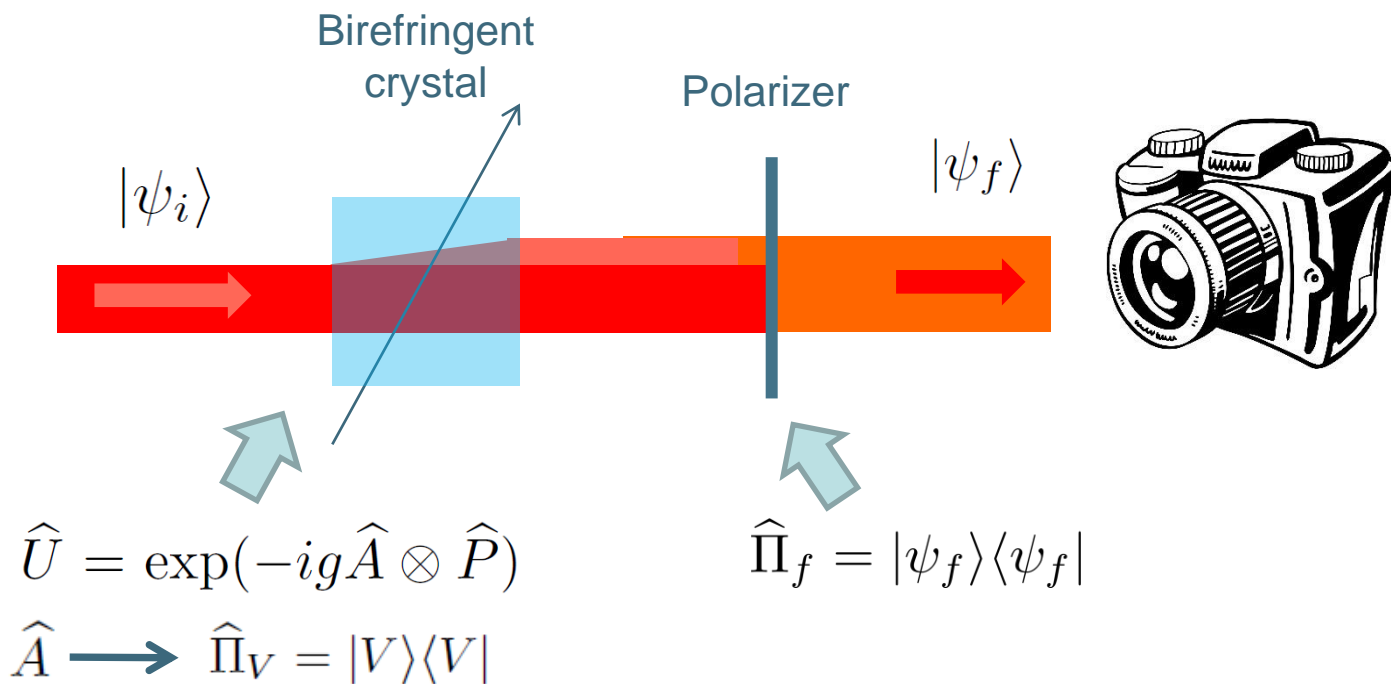
$$\hat{U}_y = \exp(-i g_y \hat{B} \otimes \hat{P}_y)$$



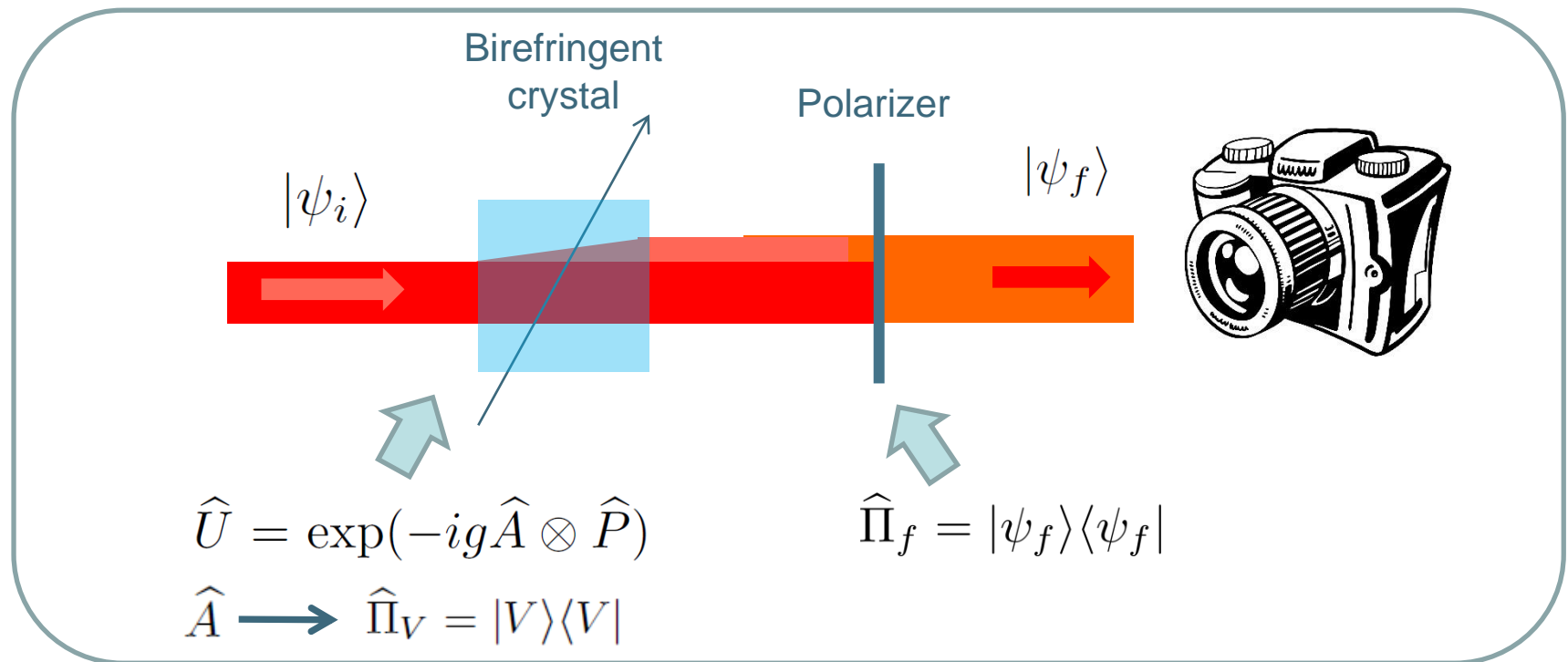
$$\hat{U}_x = \exp(-i g_x \hat{A} \otimes \hat{P}_x)$$

$$\langle \hat{X} \hat{Y} \rangle = \frac{1}{2} g_x g_y \text{Re} \left[\langle \hat{A} \hat{B} \rangle_w + \langle \hat{A} \rangle_w^* \langle \hat{B} \rangle_w \right]$$

Weak measurement implementation



Weak measurement implementation



We measure the position observable \hat{X} ,
canonically conjugated to the pointer observable \hat{P}

$$\langle \hat{X} \rangle = g \text{Re}[\langle \hat{\Pi}_V \rangle_w]$$

Sequential weak measurement

$$\hat{A} \longrightarrow \hat{\Pi}_V = |V\rangle\langle V|$$

$$\hat{B} \longrightarrow \hat{\Pi}_\psi = |\psi\rangle\langle\psi|$$

$$|\psi\rangle = \cos\theta|H\rangle + \sin\theta|V\rangle$$

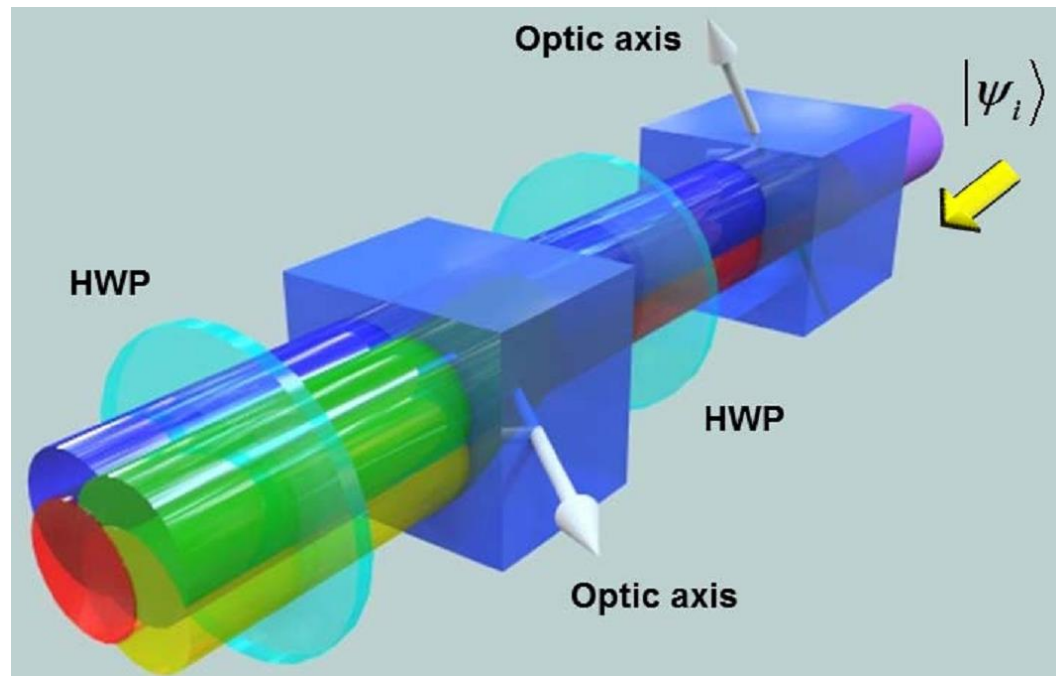


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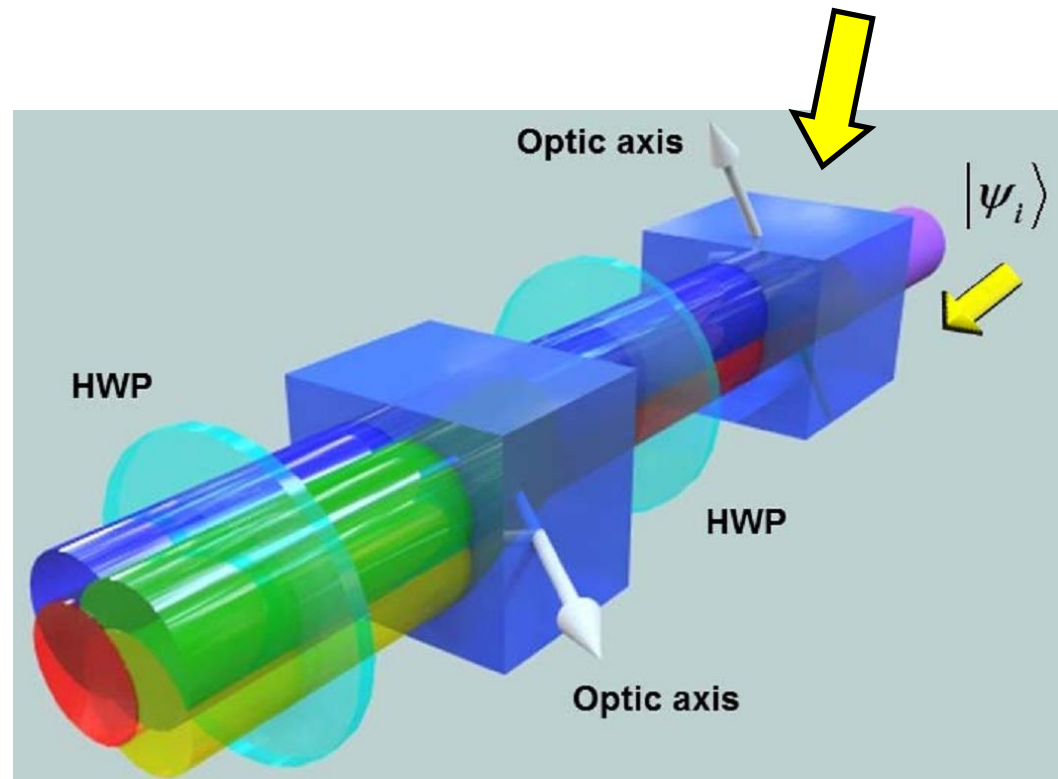
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$$\hat{U}_y = e^{-ig_y} \hat{\Pi}_V \otimes \hat{P}_y$$



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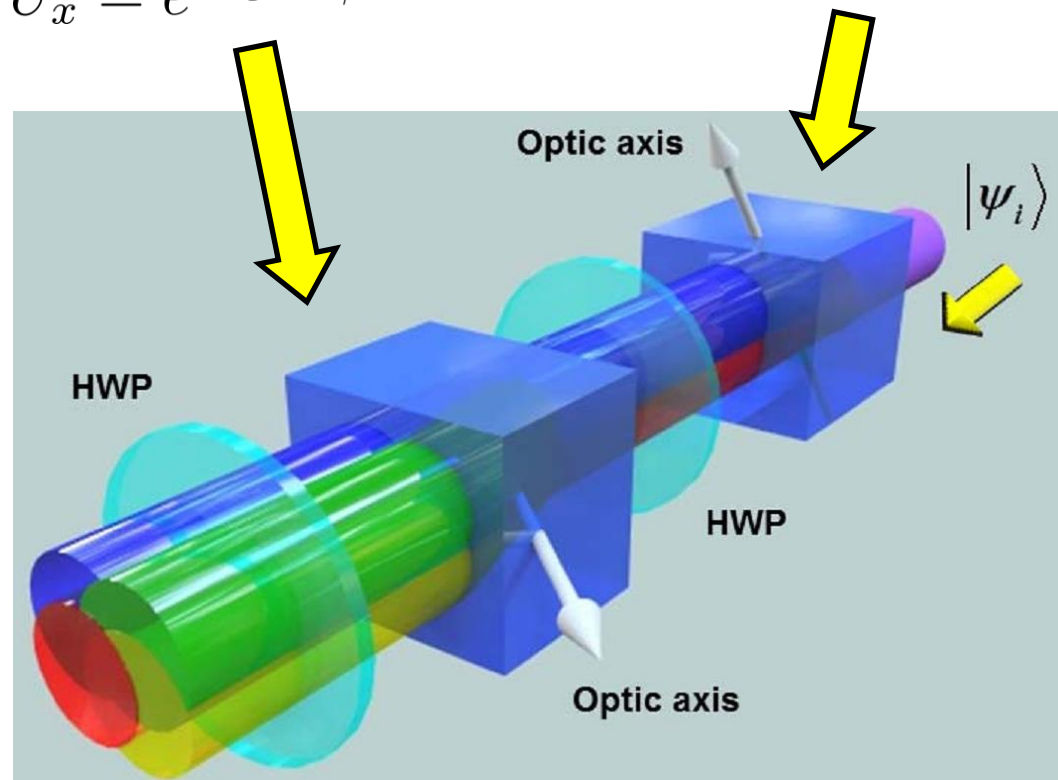
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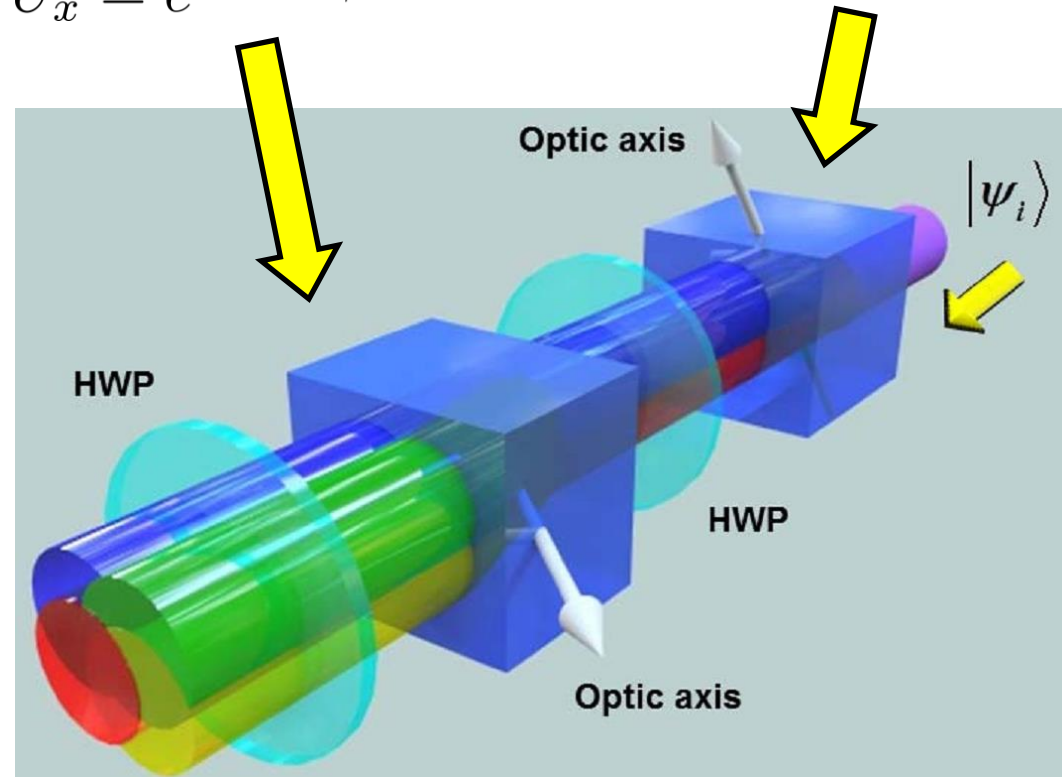
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Linearly polarized pre- and post-selection states $|\psi_i\rangle, |\psi_f\rangle$

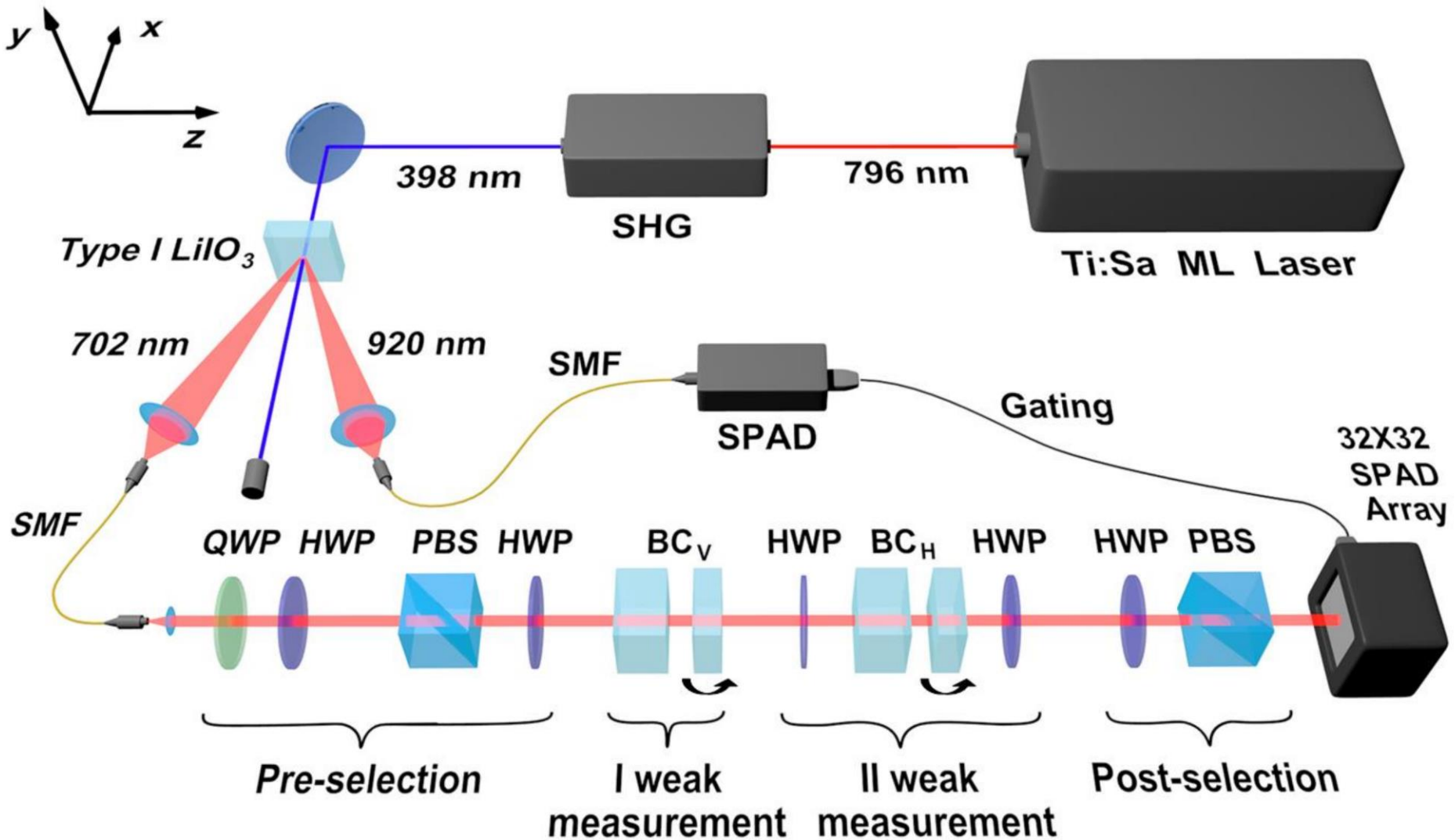
$$\left\{ \begin{array}{l} \langle \hat{X} \rangle = g_x \langle \hat{\Pi}_\psi \rangle_w \\ \langle \hat{Y} \rangle = g_y \langle \hat{\Pi}_V \rangle_w \\ \langle \hat{X} \hat{Y} \rangle = \frac{1}{2} g_x g_y \left(\langle \hat{\Pi}_\psi \hat{\Pi}_V \rangle_w + \langle \hat{\Pi}_\psi \rangle_w \langle \hat{\Pi}_V \rangle_w \right) \end{array} \right.$$

$$\hat{U}_x = e^{-ig_x \hat{\Pi}_\psi \otimes \hat{P}_x}$$

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SETUP





32x32 SPAD+TDC camera

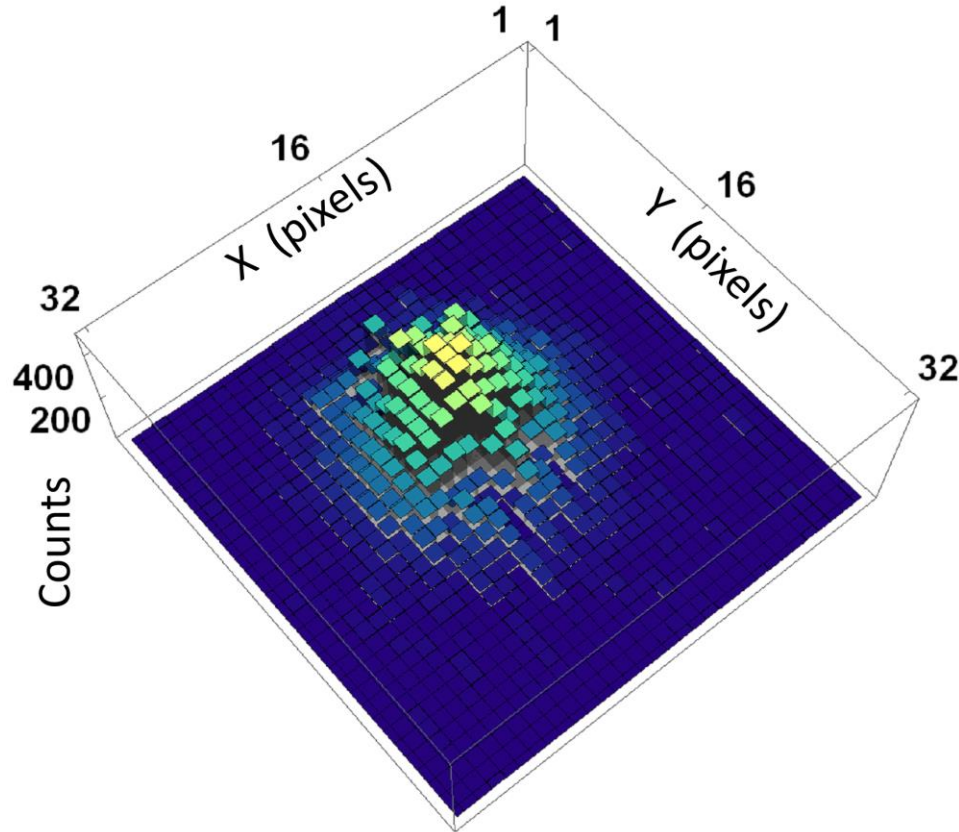
Features

- Multi-modality: photon-counting, 2D imaging, 3D time-of-flight ranging, TCSPC (time-correlated single-photon counting)
- Image dimension: 32x32 (1024) pixels
- In-pixel counter: 6 bit (photon-counting)
- In-pixel TDC: 10 bit (photon-timing)
- Max frame rate: 100,000 fps (burst) and 10,000 fps (continuous)
- Timing resolution: 312 ps – 0.9 ns
- Full scale range: 320 ns – 0.92 μ s
- Hardware interface: USB 2.0
- Software interface: Matlab



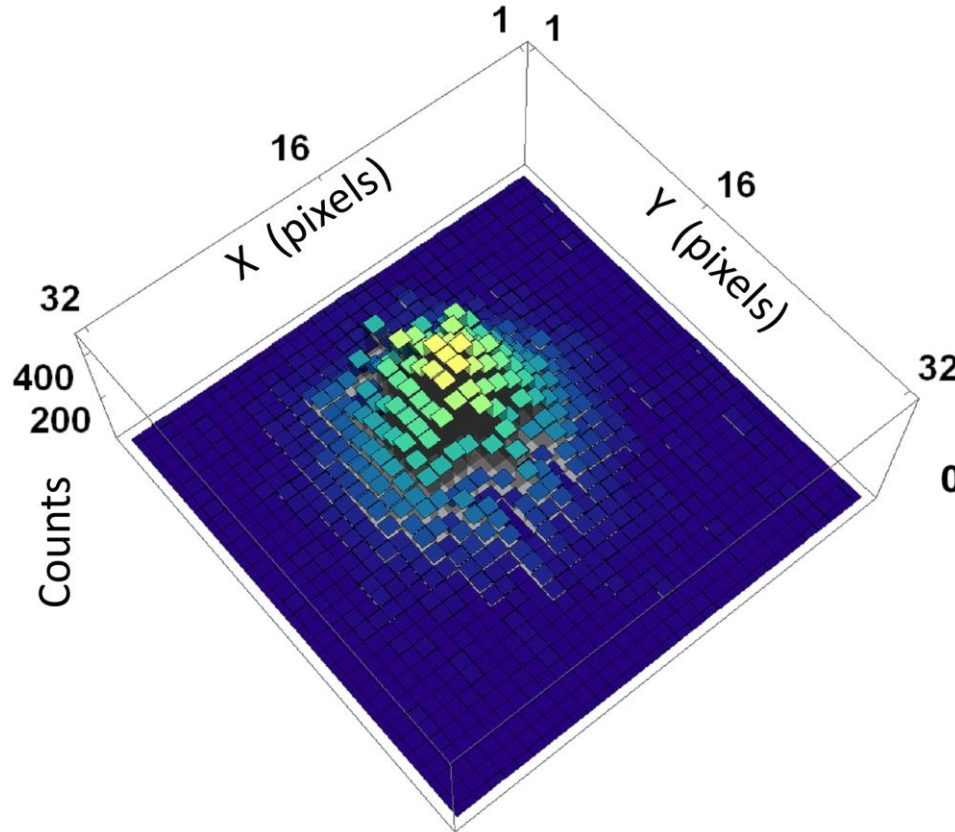
Fig. 1: SPAD camera for 2D imaging, 3D ranging and TCSPC photon-counting.

SPAD array output VS. theoretical prediction

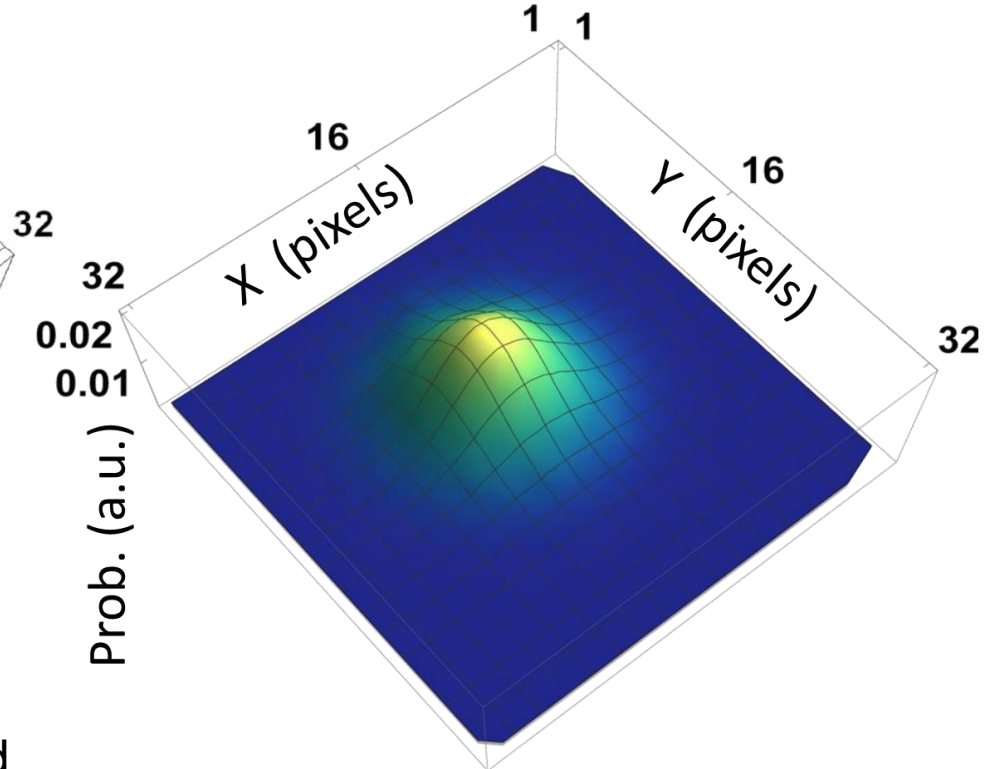


Typical single data acquisition obtained with our 32x32 SPAD camera (after noise subtraction)

SPAD array output VS. theoretical prediction



Typical single data acquisition obtained with our 32x32 SPAD camera (after noise subtraction)



Corresponding predicted probability distribution calculated according to the theory

Results

Measured weak values (data points) compared with the theoretical predictions

$$\hat{\Pi}_V = |V\rangle\langle V| \quad \hat{\Pi}_\psi = |\psi\rangle\langle\psi| \quad (|\psi\rangle = \cos\theta|H\rangle + \sin\theta|V\rangle)$$

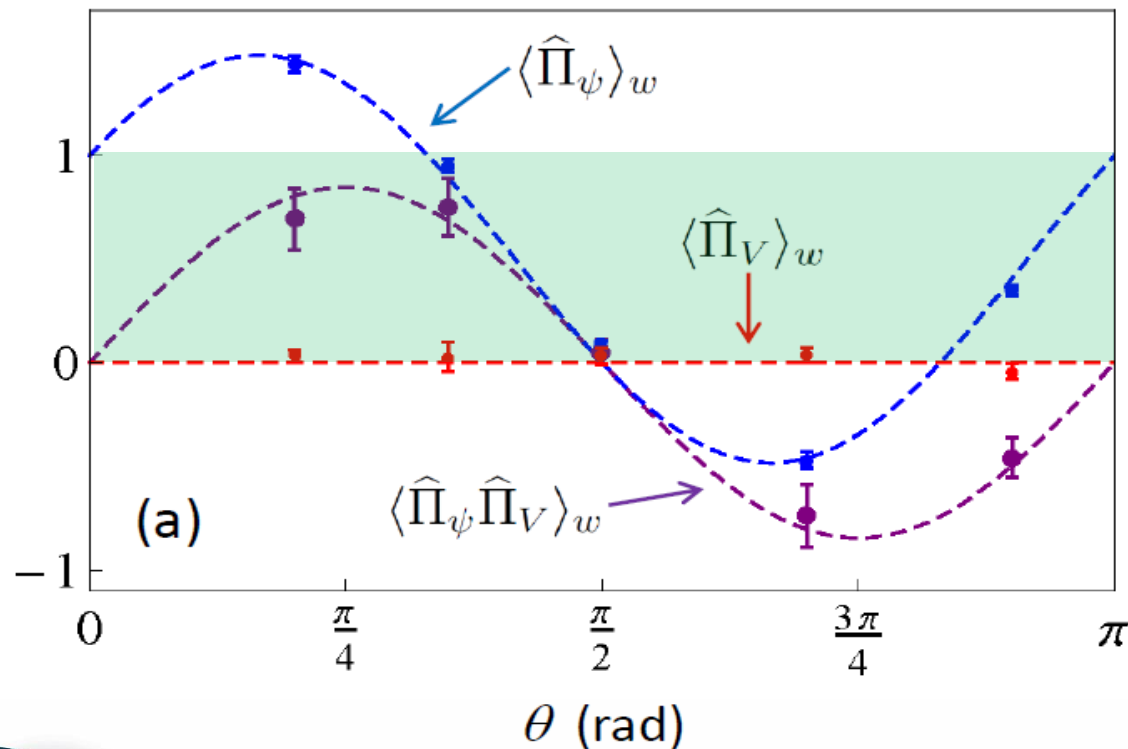
$$|\psi_i\rangle = 0.588|H\rangle + 0.809|V\rangle \quad |\psi_f\rangle = |H\rangle$$

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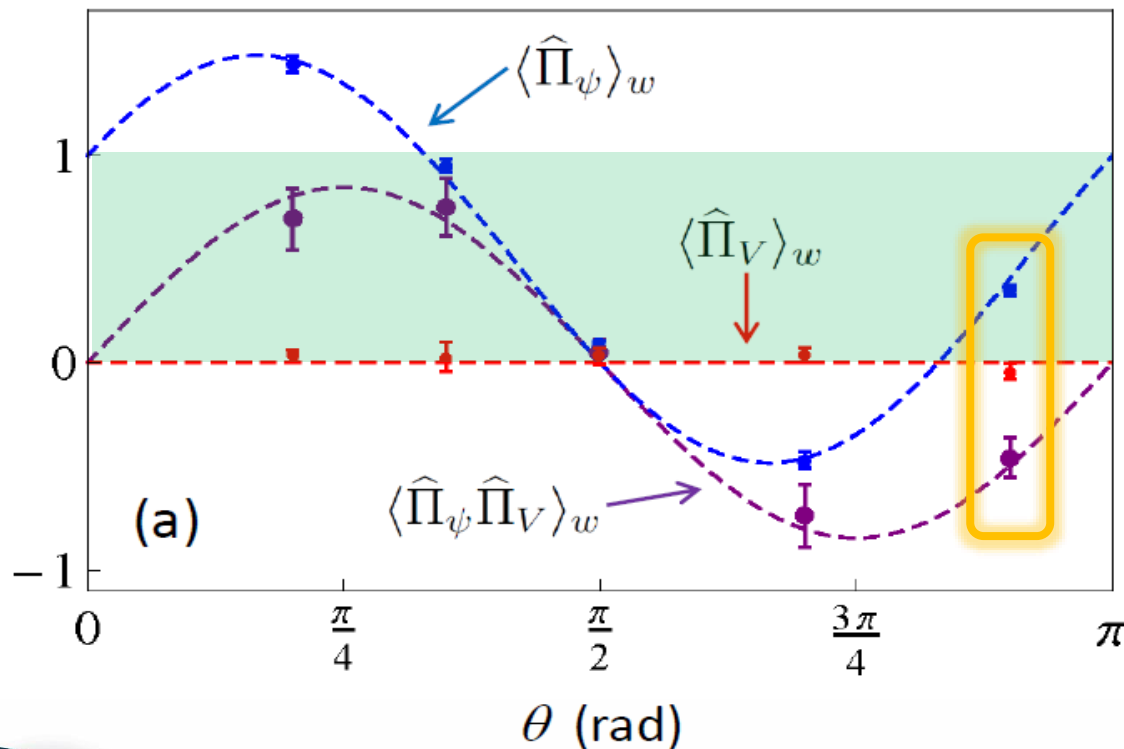
[arXiv:1508.03220](https://arxiv.org/abs/1508.03220)

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$$\begin{aligned} \langle \hat{\Pi}_V \rangle_w &= 0.04 \pm 0.03 \\ \langle \hat{\Pi}_\psi \rangle_w &= 0.35 \pm 0.04 \\ \langle \hat{\Pi}_\psi \hat{\Pi}_V \rangle_w &= -0.46 \pm 0.10 \end{aligned}$$

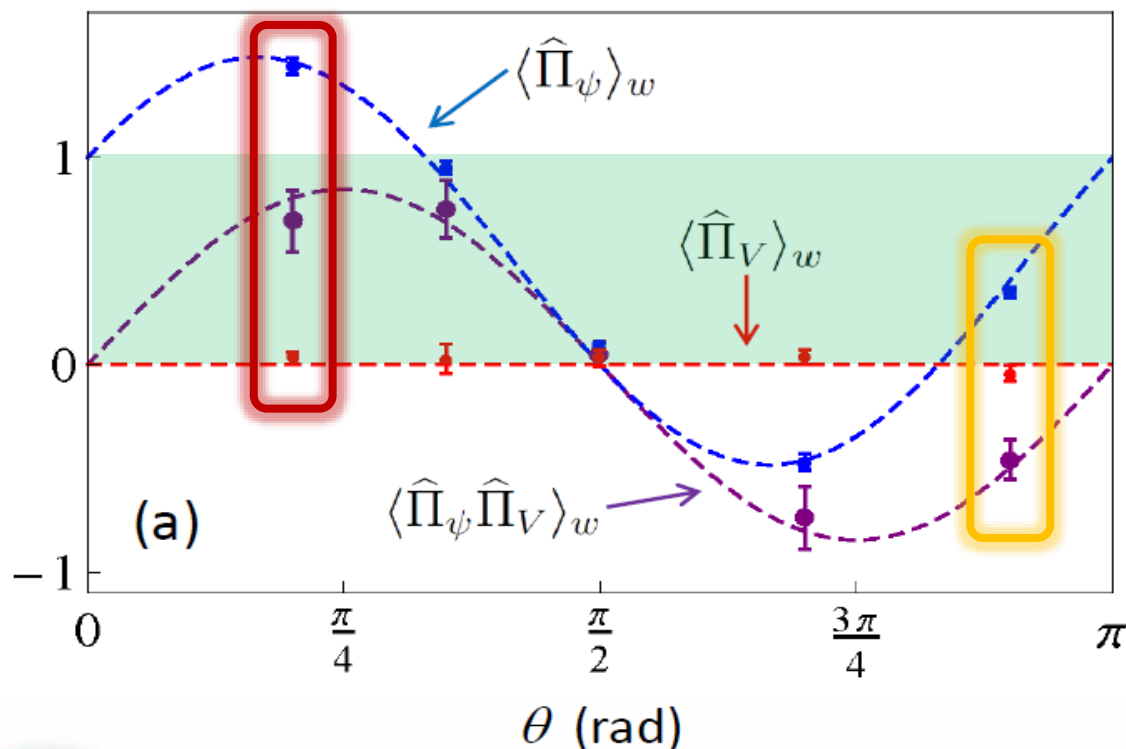
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$$\langle \hat{\Pi}_V \rangle_w = 0.03 \pm 0.03$$

$$\langle \hat{\Pi}_\psi \rangle_w = 1.44 \pm 0.04$$

$$\langle \hat{\Pi}_\psi \hat{\Pi}_V \rangle_w = 0.69 \pm 0.15$$

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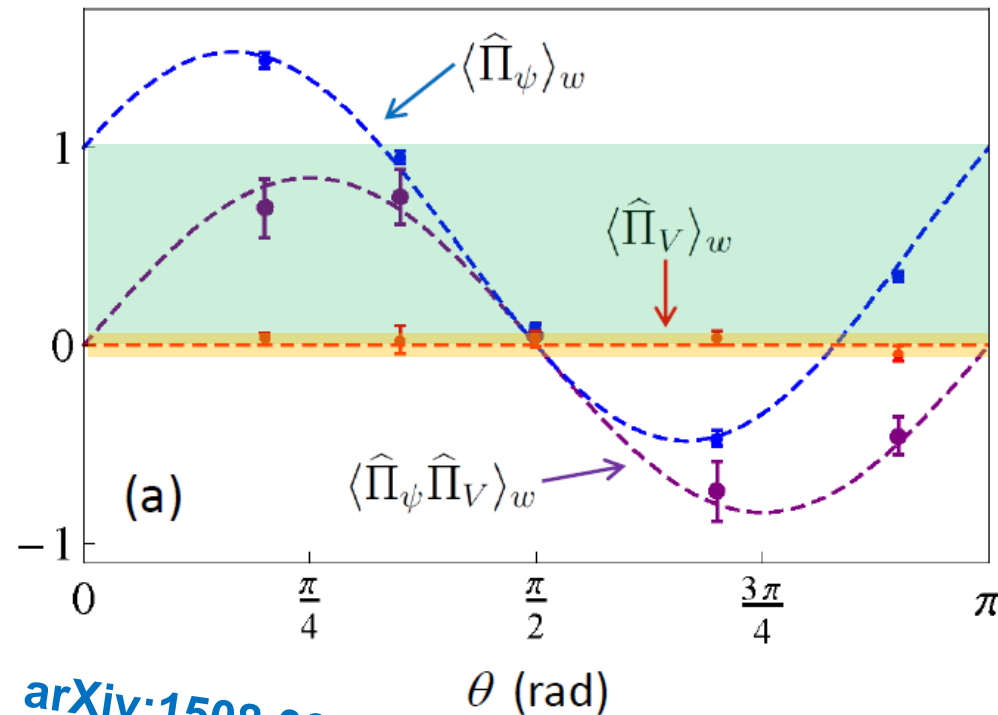
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$$|\psi_i\rangle = 0.588|H\rangle + 0.809|V\rangle \quad |\psi_f\rangle = |H\rangle$$



arXiv:1508.03220

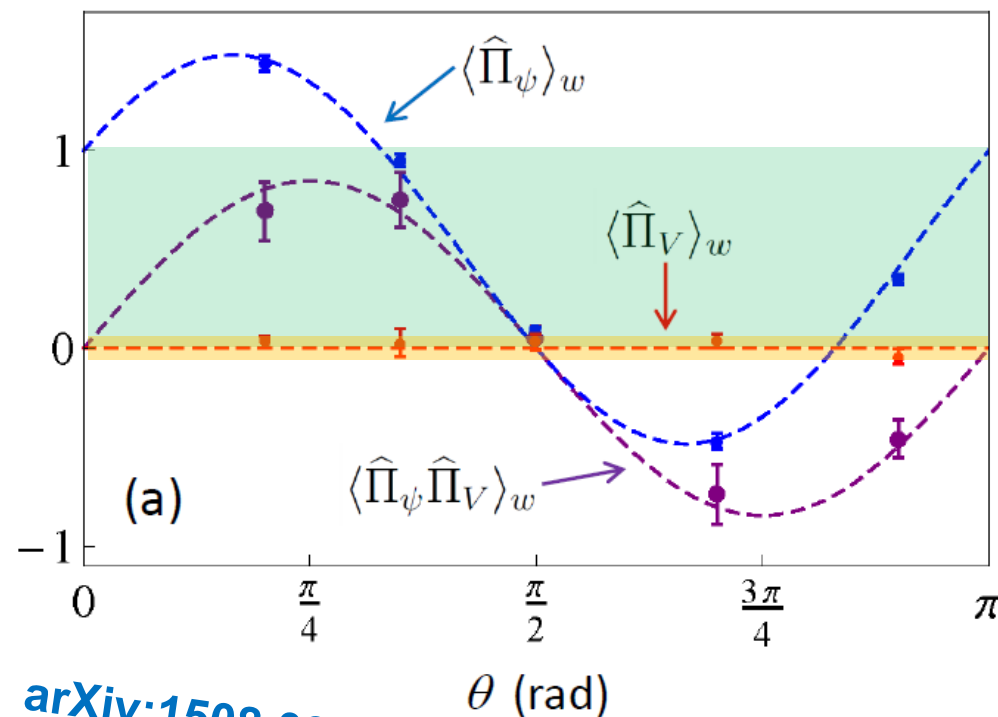
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Weak values
"internal consistency"



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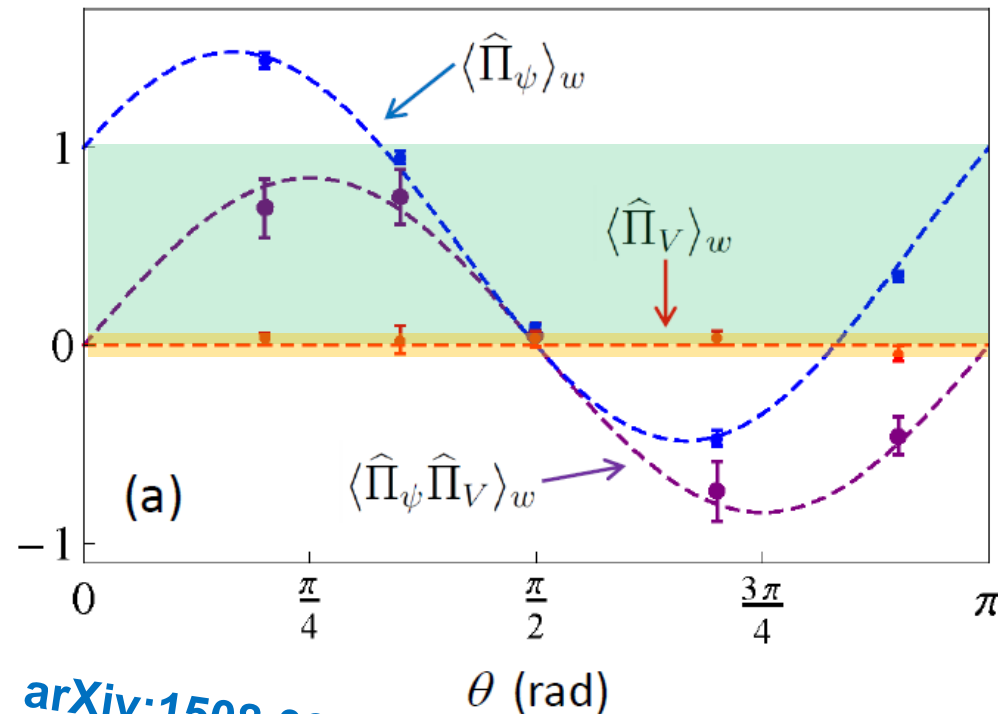
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Weak values

"internal consistency"

$$\langle\hat{\Pi}_\psi\rangle_w + \langle\hat{\Pi}_\psi^\perp\rangle_w = 1$$



Results

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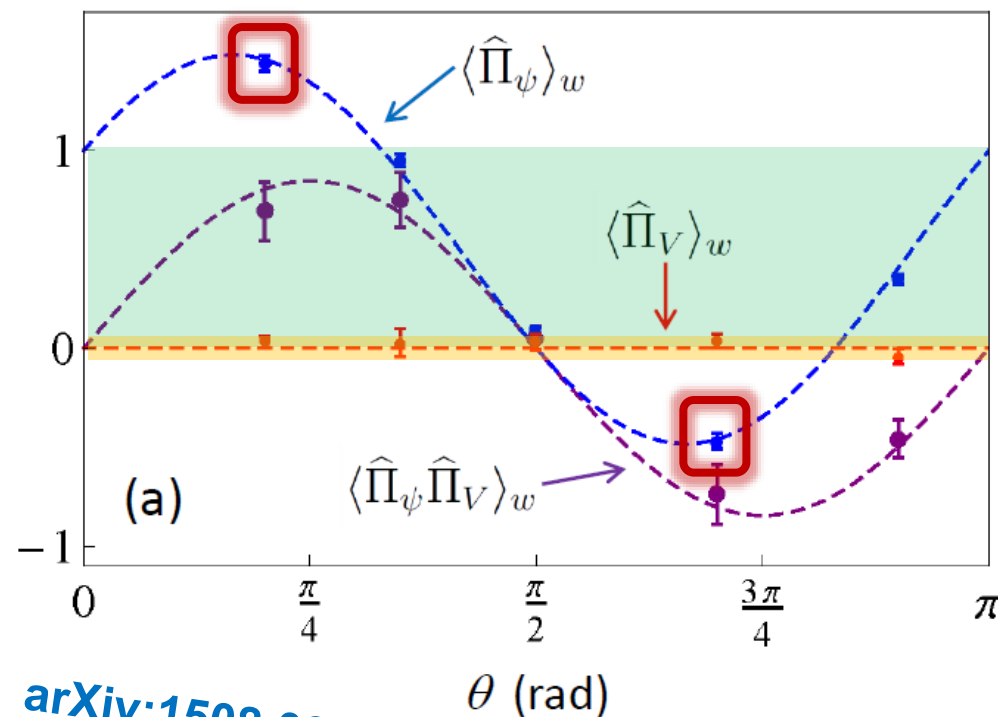
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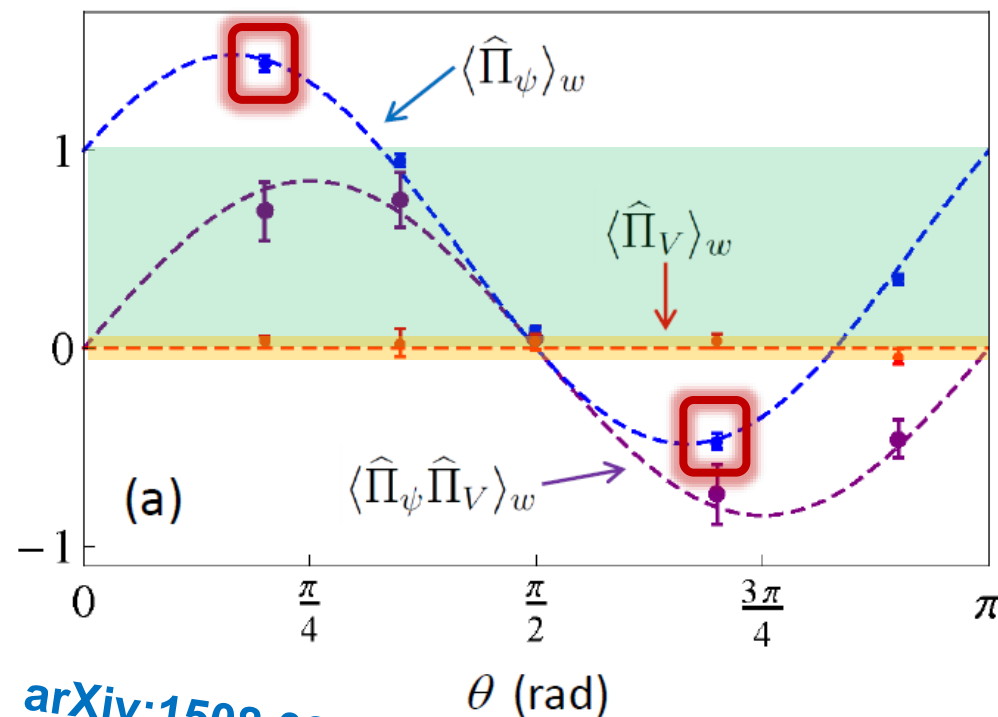
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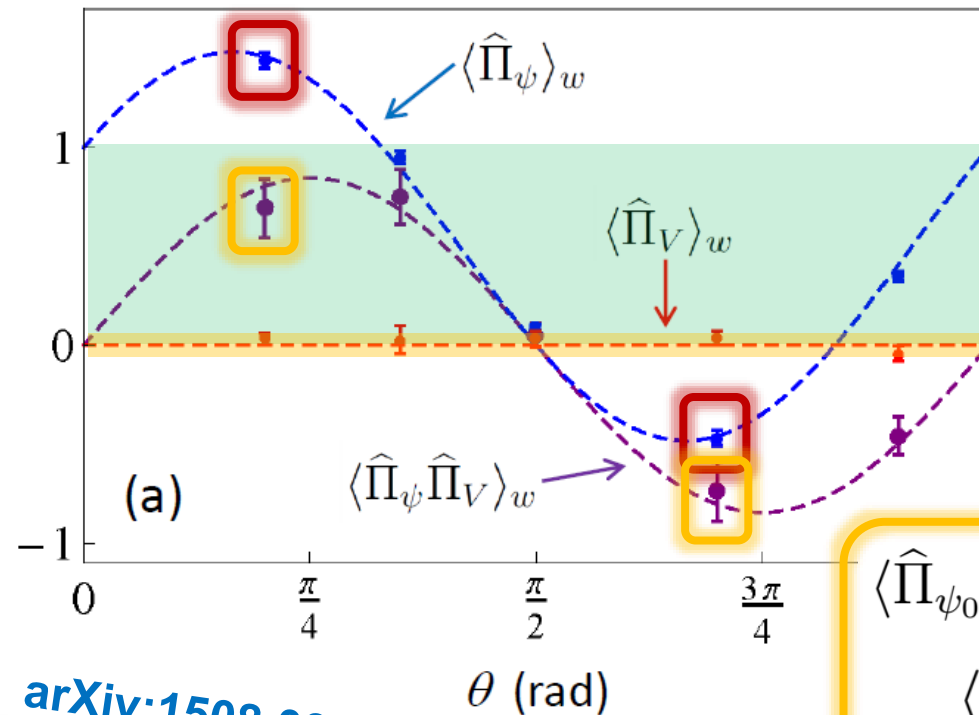
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$$\langle \hat{\Pi}_\psi \hat{\Pi}_\varphi \rangle_w + \langle \hat{\Pi}_\psi^\perp \hat{\Pi}_\varphi \rangle_w = \langle \hat{\Pi}_\varphi \rangle_w$$

$$\langle \hat{\Pi}_{\psi_0} \hat{\Pi}_V \rangle_w + \langle \hat{\Pi}_{\psi_0}^\perp \hat{\Pi}_V \rangle_w = -0.05 \pm 0.22$$

$$\langle \hat{\Pi}_V \rangle_w = 0 \quad (0.02 \pm 0.06)$$



arXiv:1508.03220



Measured weak values (data points) compared with the theoretical predictions

$$\hat{\Pi}_V = |V\rangle\langle V| \quad \hat{\Pi}_\psi = |\psi\rangle\langle\psi| \quad (|\psi\rangle = \cos\theta|H\rangle + \sin\theta|V\rangle)$$

$$|\psi_i\rangle = 0.509|H\rangle + 0.861|V\rangle$$

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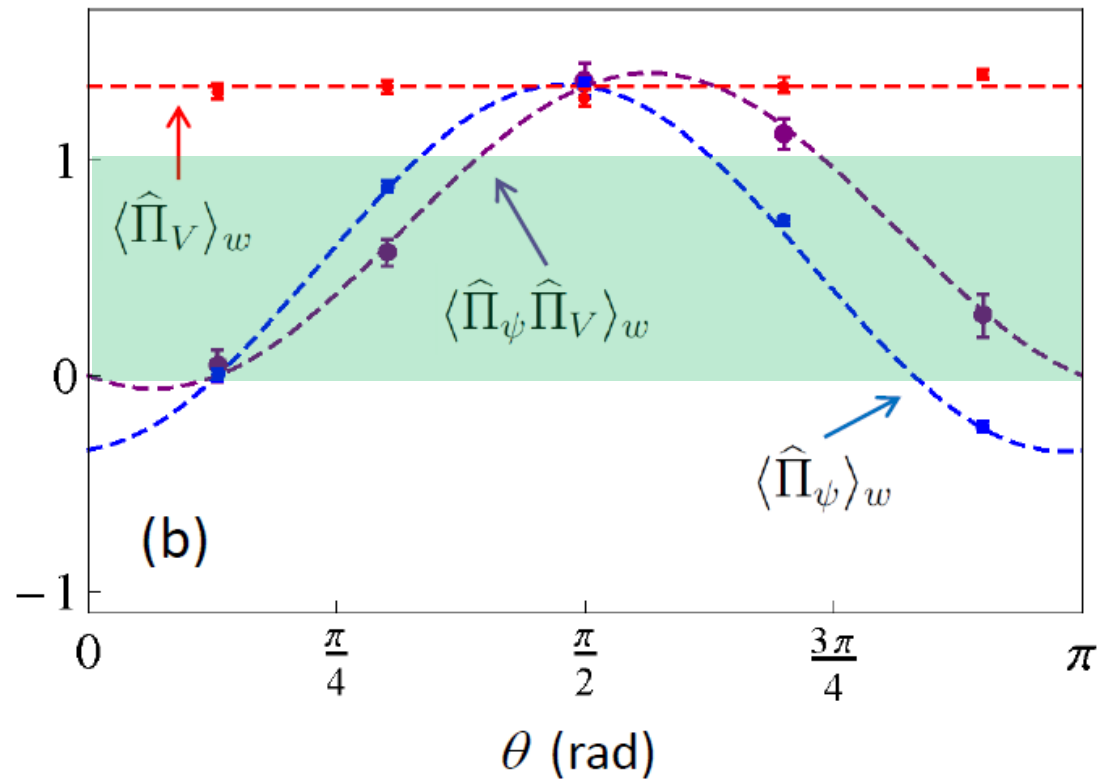
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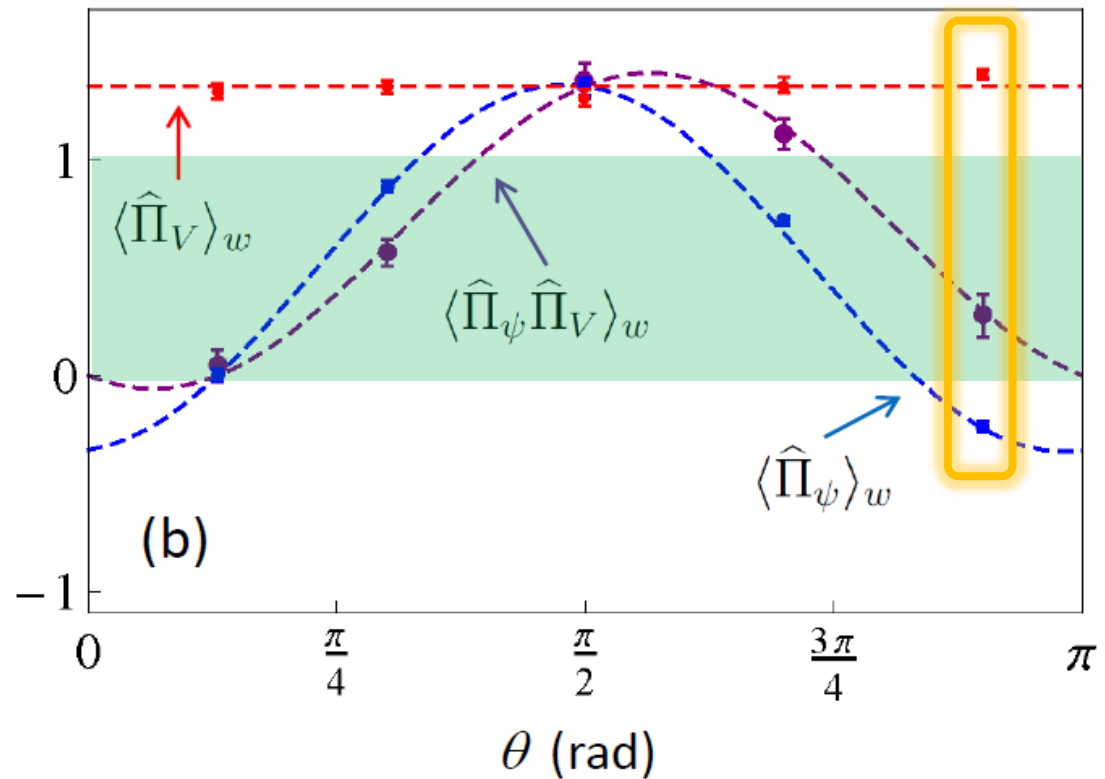
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$$\langle\hat{\Pi}_V\rangle_w = 1.40 \pm 0.04$$

$$\langle\hat{\Pi}_\psi\rangle_w = -0.24 \pm 0.03$$

$$\langle\hat{\Pi}_\psi\hat{\Pi}_V\rangle_w = 0.28 \pm 0.10$$



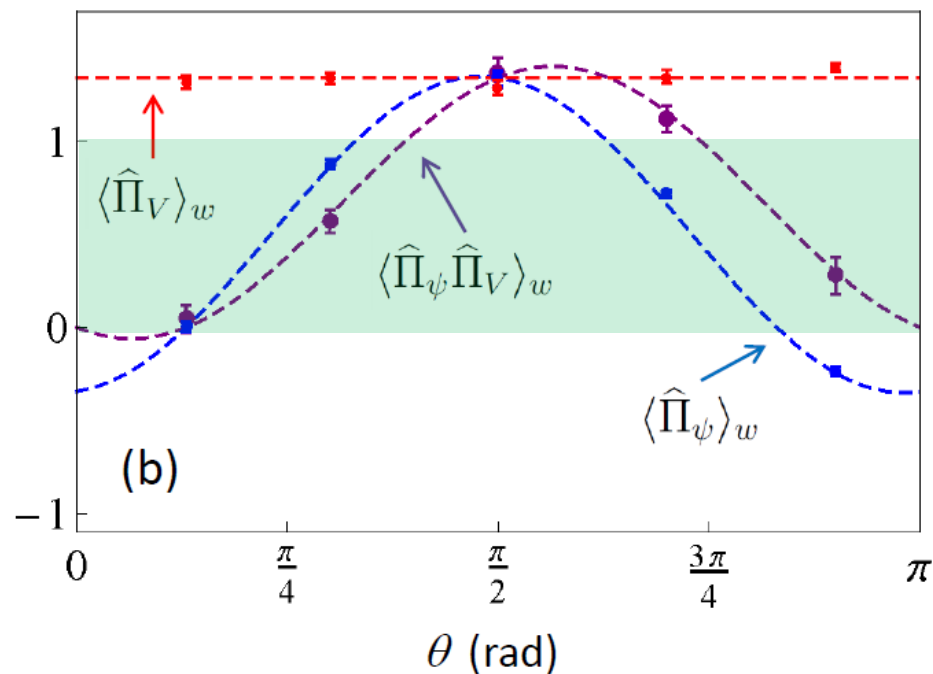
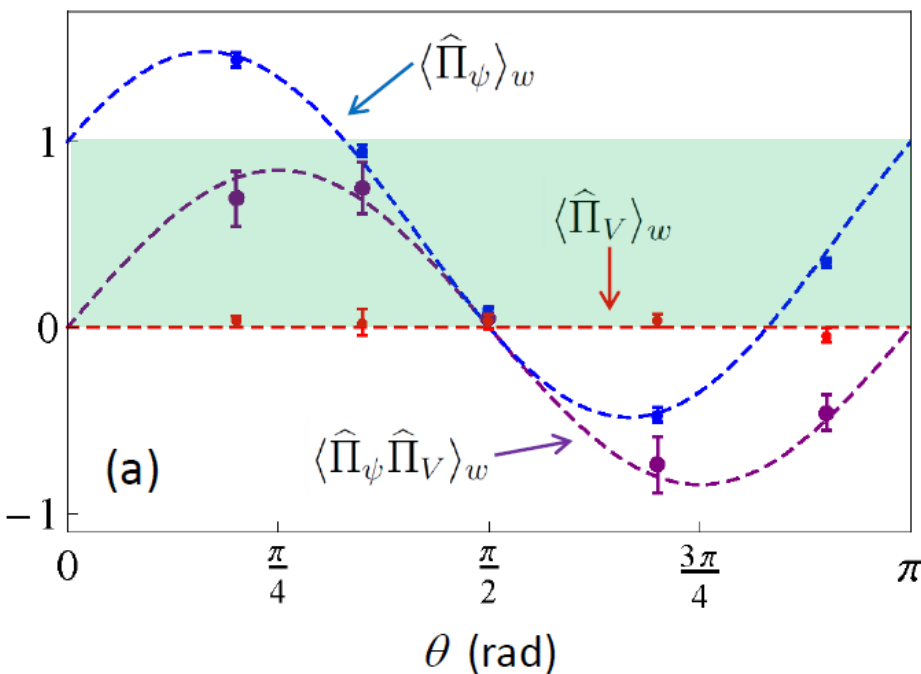
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Results summary

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WMs and quantum contextuality

Non-Contextual Hidden Variable Theory: ontological model of an operational theory where, if two experimental procedures are operationally equivalent, then they have equivalent representations in such model [Spekkens, PRA 71 (2005)].

WMs and quantum contextuality

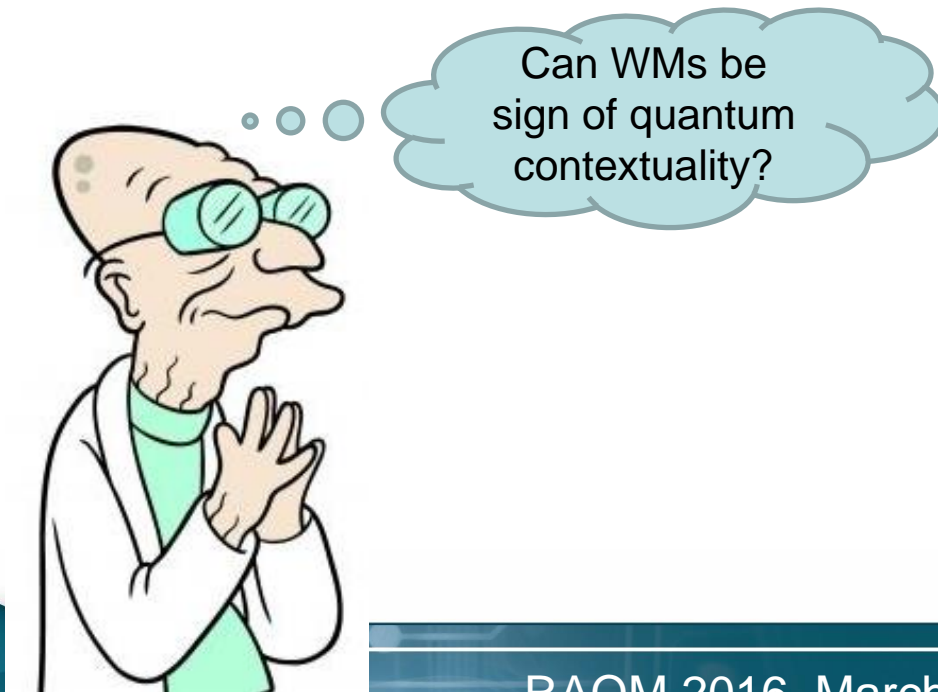
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The measurement outcome depends only on the Hermitian operator associated with the measurement, not on the ones measured simultaneously with it: **each observable has a predetermined value (given by some HVs), independent of the context.**

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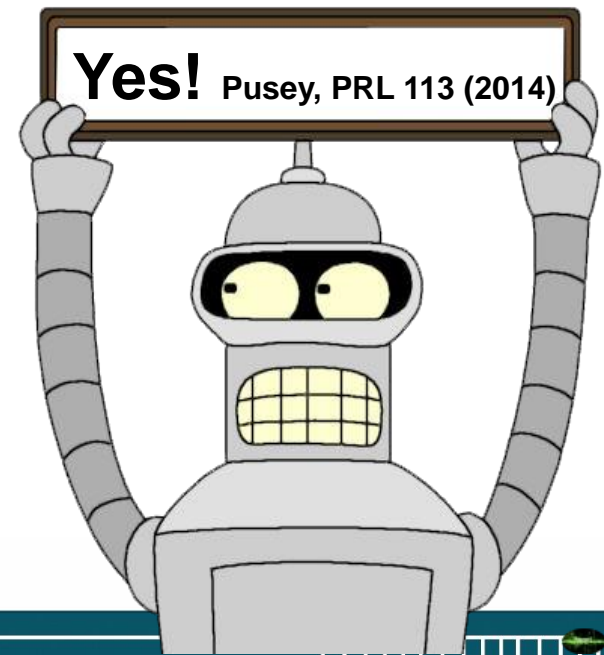
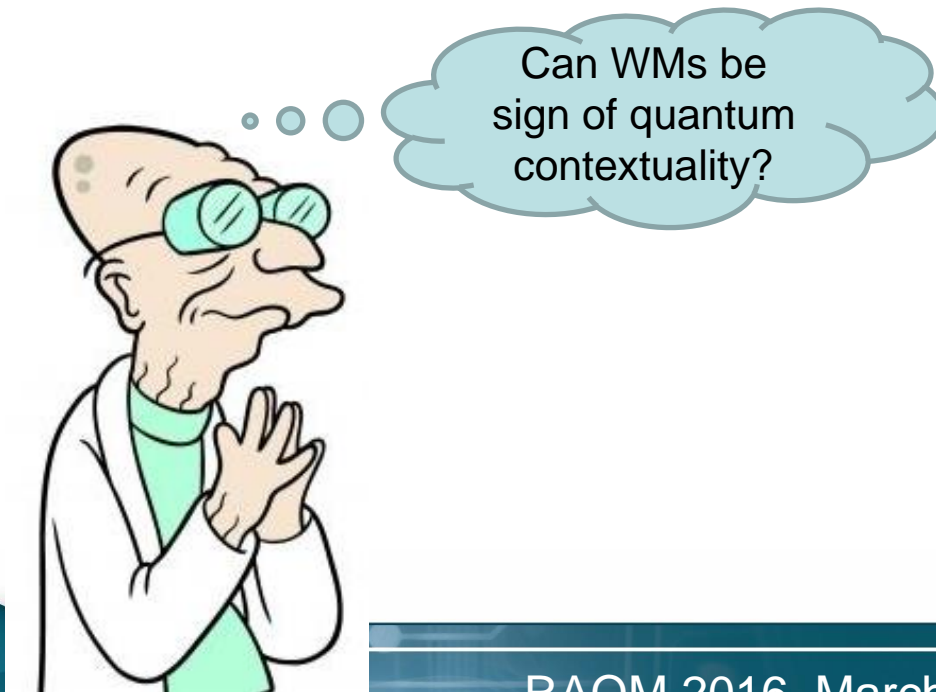
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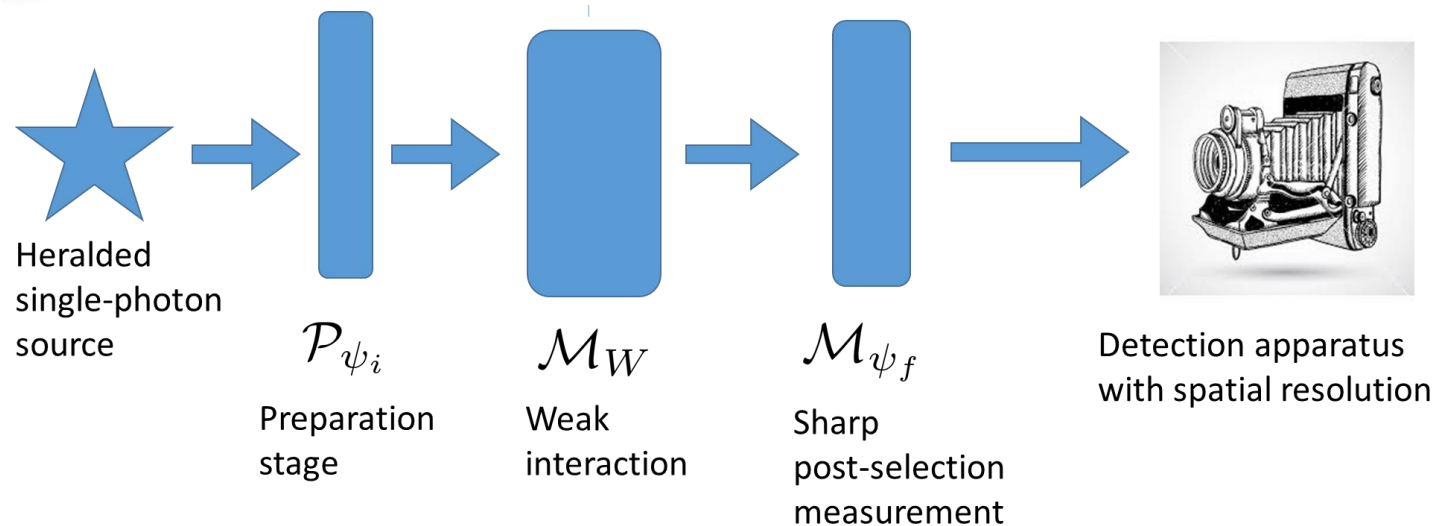
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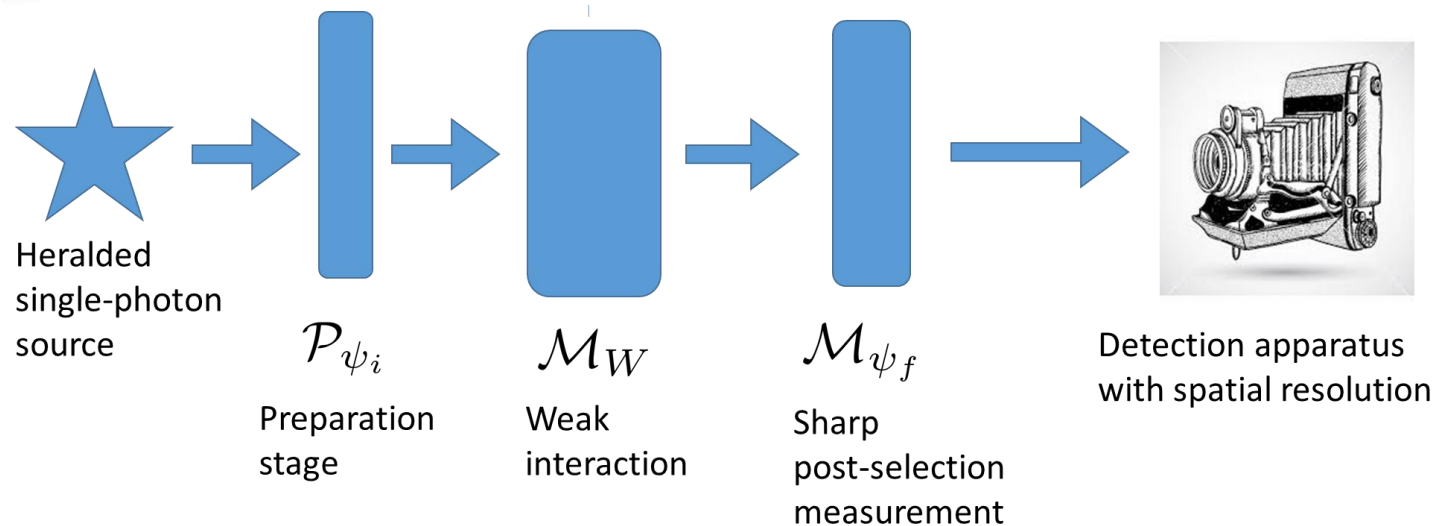
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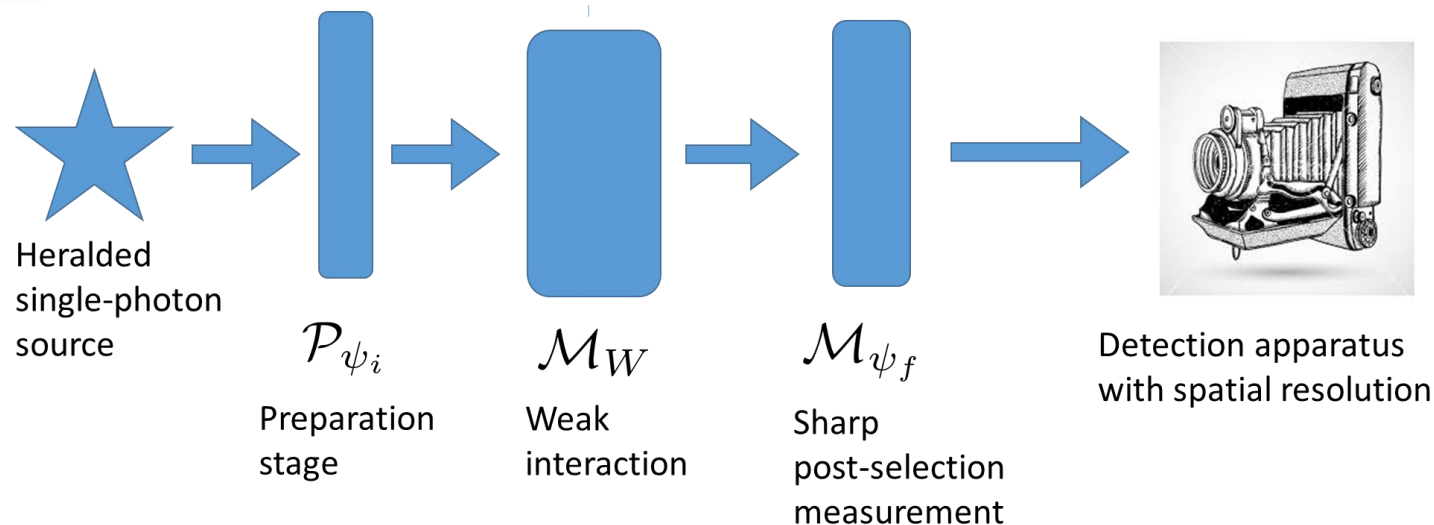


WM and quantum contextuality



Initial and final states are non-orthogonal : $p_{\psi_f} := \mathbb{P}(\text{PASS} | \mathcal{P}_{\psi_i}, \mathcal{M}_{\psi_f}) > 0$

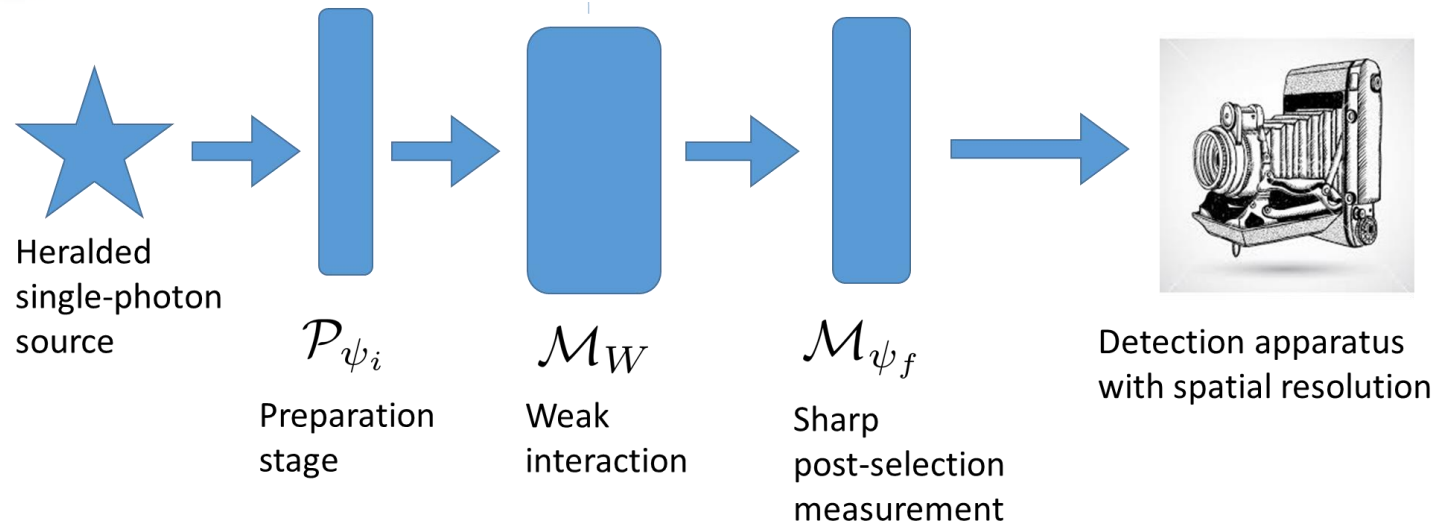
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WM and quantum contextuality

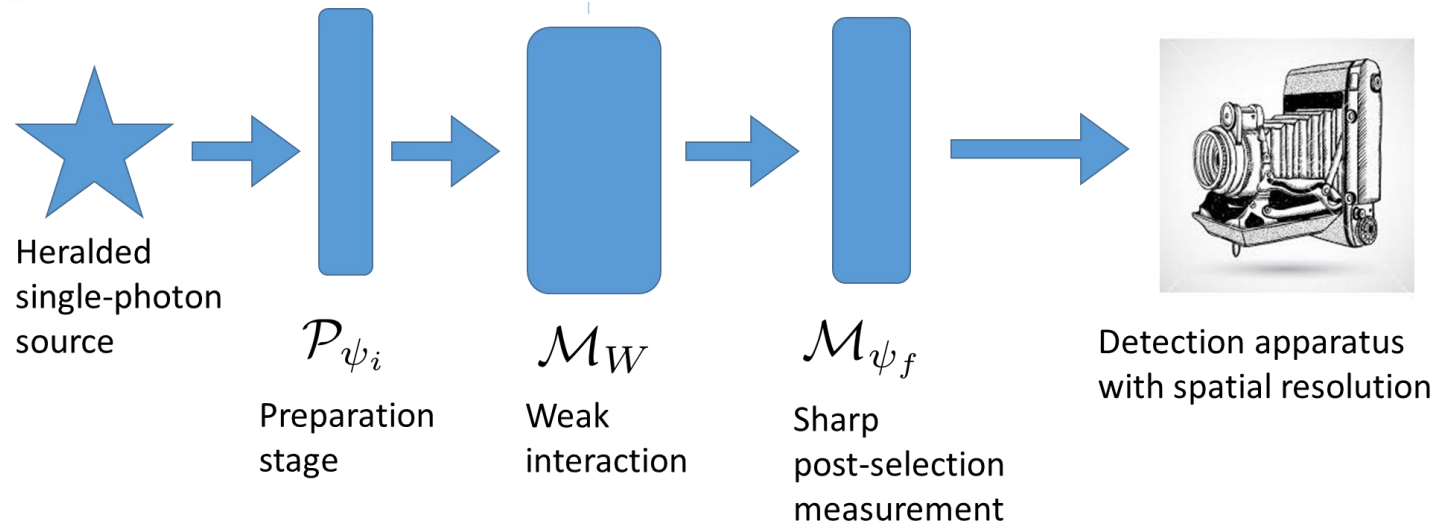


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WM and quantum contextuality



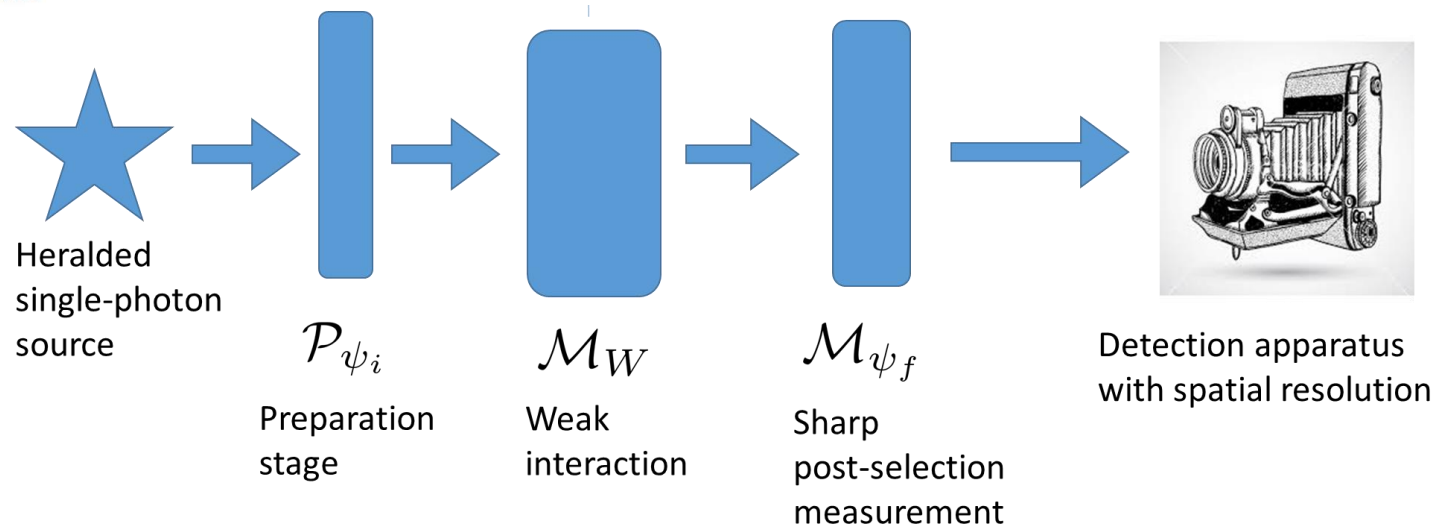
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$p_- := (p_{\psi_f})^{-1} \int_{-\infty}^0 \mathbb{P}(x, \text{PASS} | \mathcal{P}_{\psi_i}, \mathcal{M}_W, \mathcal{M}_{\psi_f}) dx : \quad \mathcal{I} = p_- - \frac{1}{2} - \frac{p_d}{p_{\psi_f}} > 0$

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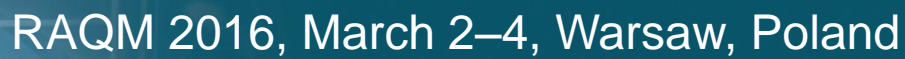
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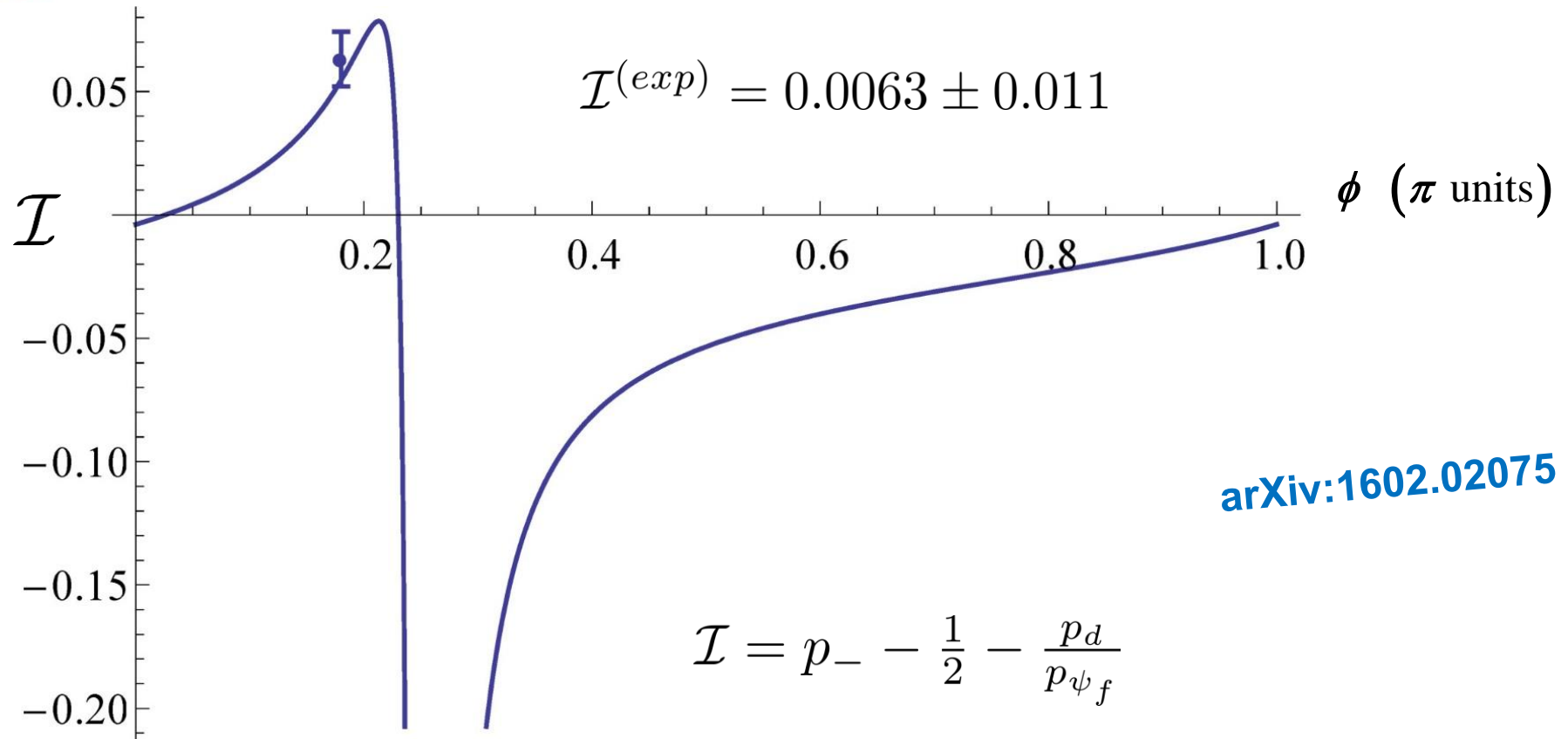
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No non-contextual model satisfying outcome determinism for sharp measurements



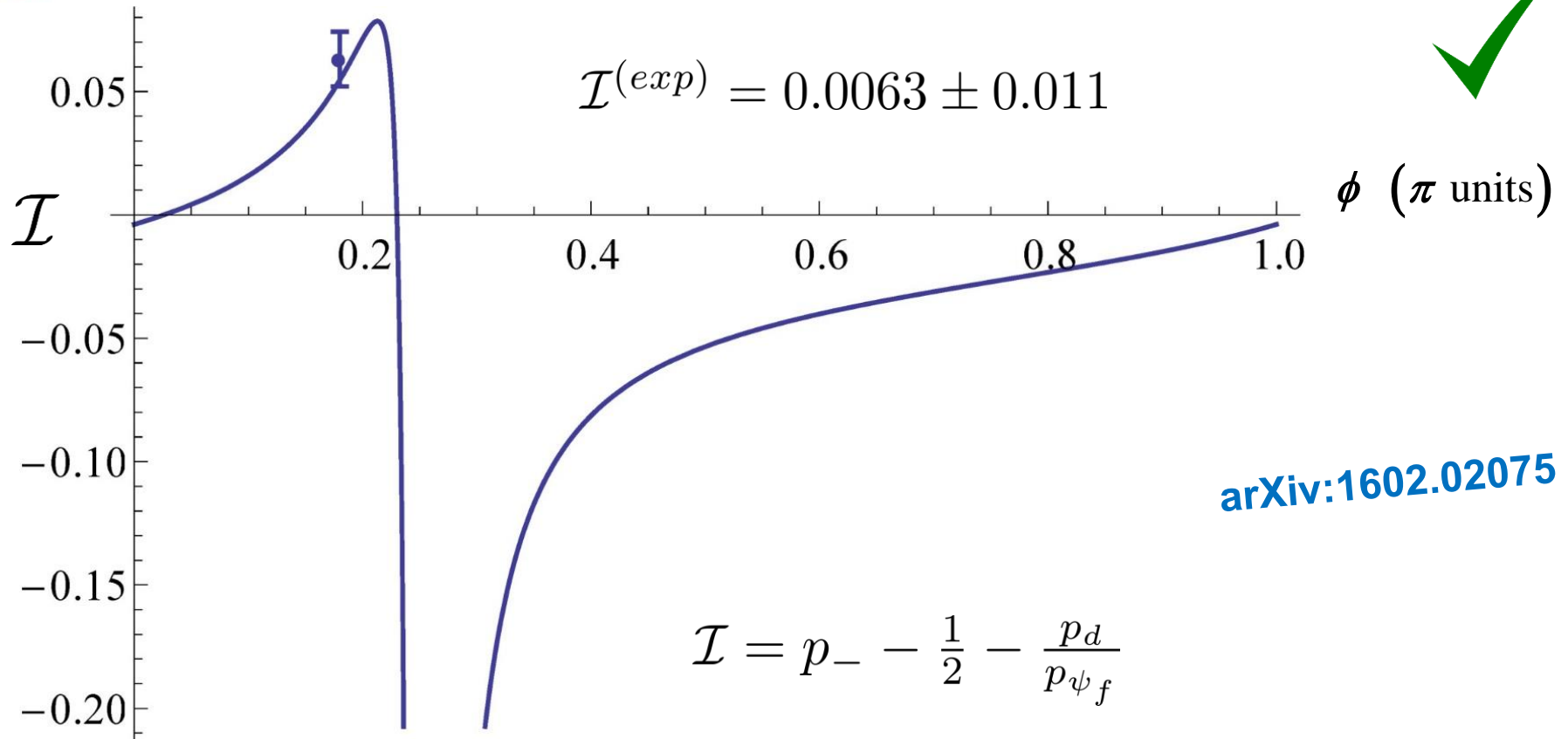
Condition 4: non-contextual bound violation



arXiv:1602.02075

- input state: $|-\rangle = \frac{1}{\sqrt{2}}(|H\rangle - |V\rangle)$
- post-selection state: $|\psi_f\rangle = \cos \phi |H\rangle + \sin \phi |V\rangle$ ($\mathcal{I}^{(exp)}$: $\phi = 0.18\pi$)
- From experimental parameters: $p_d = 0.0019 \pm 0.0002$

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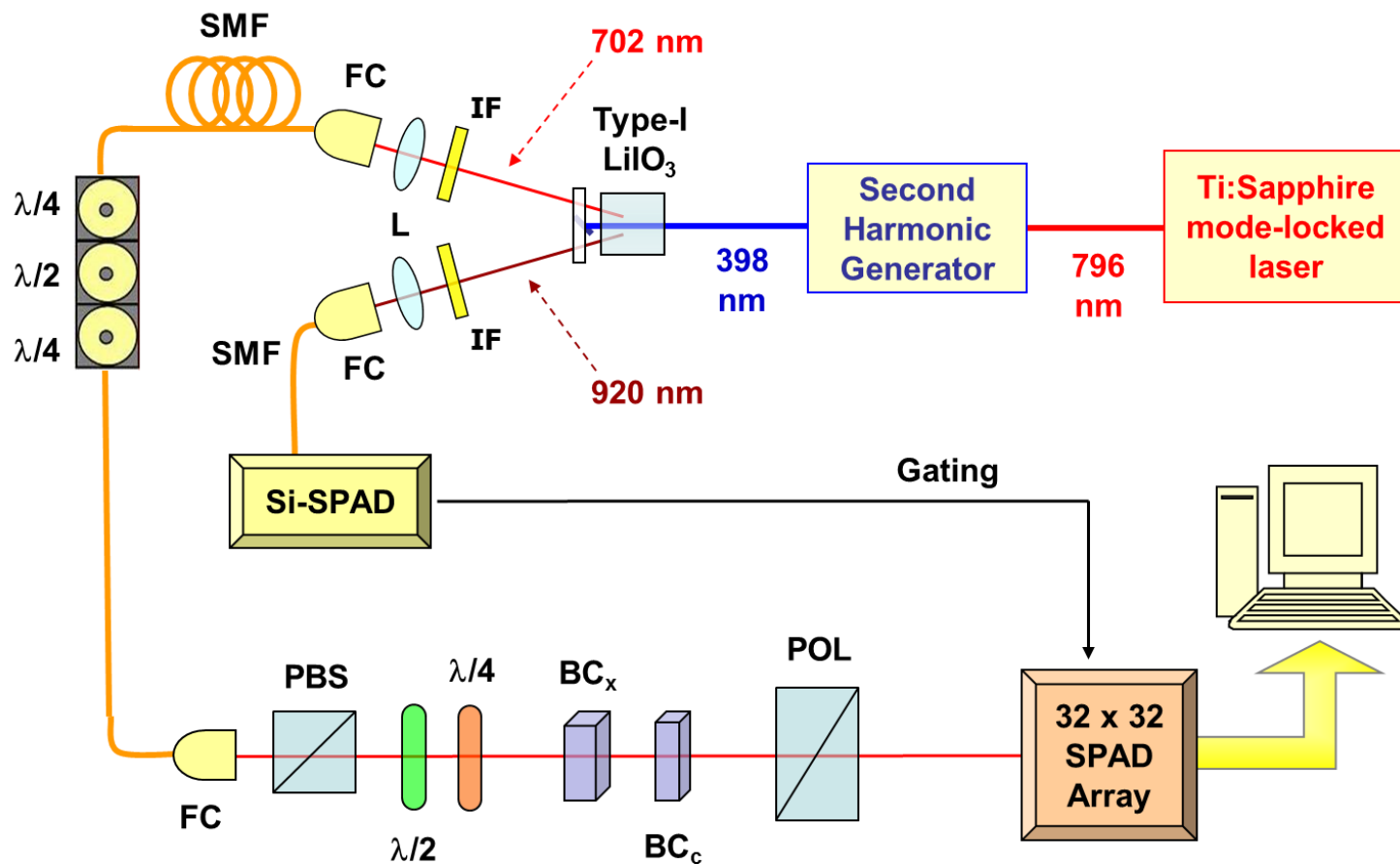
Condition 2 verification

$$\mathbb{P}(x|\mathcal{P}, \mathcal{M}_W) = p_n(x - g)\mathbb{P}(1|\mathcal{P}, \mathcal{M}_\Pi) + p_n(x)\mathbb{P}(0|\mathcal{P}, \mathcal{M}_\Pi) \quad \forall \mathcal{P}$$



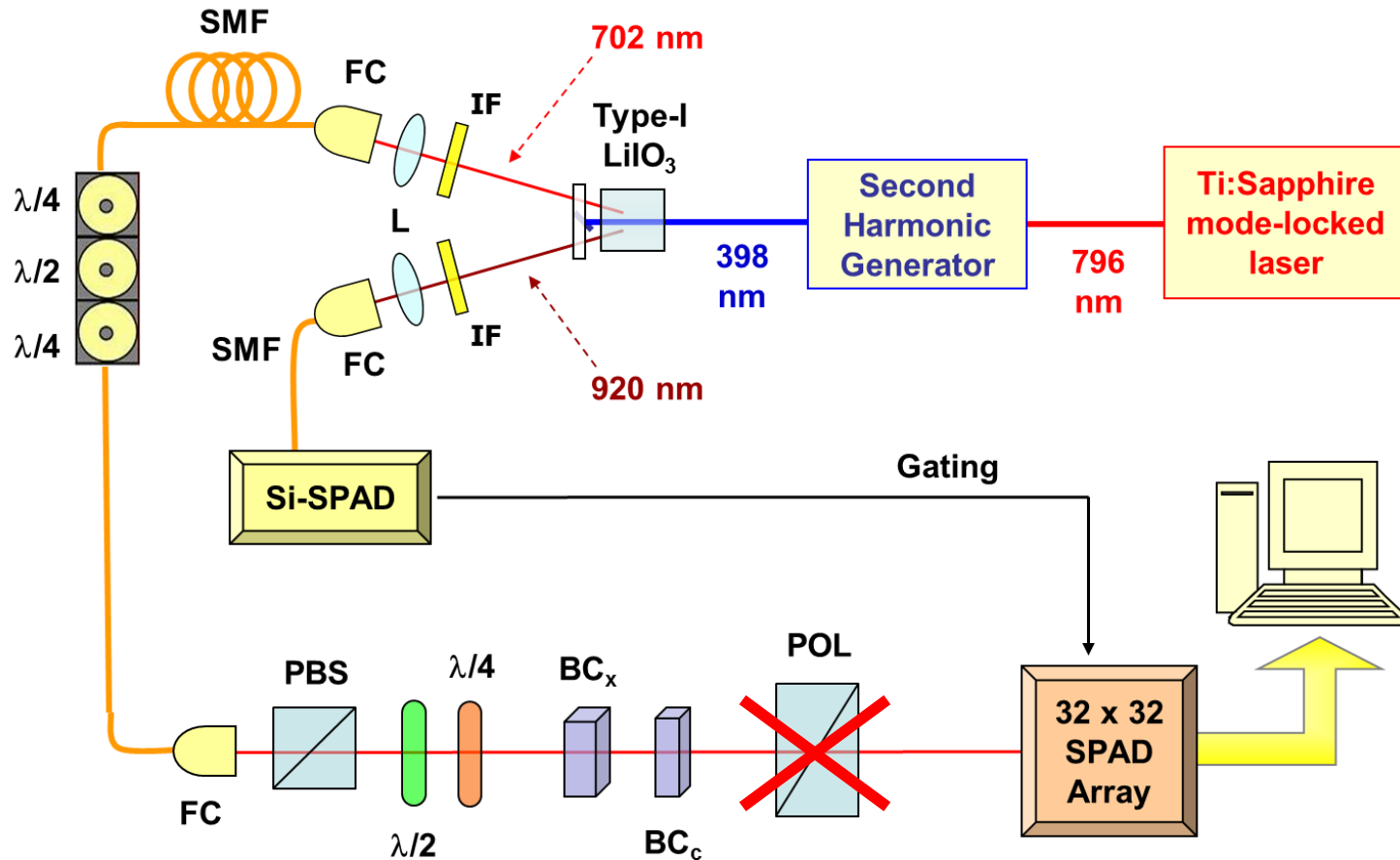
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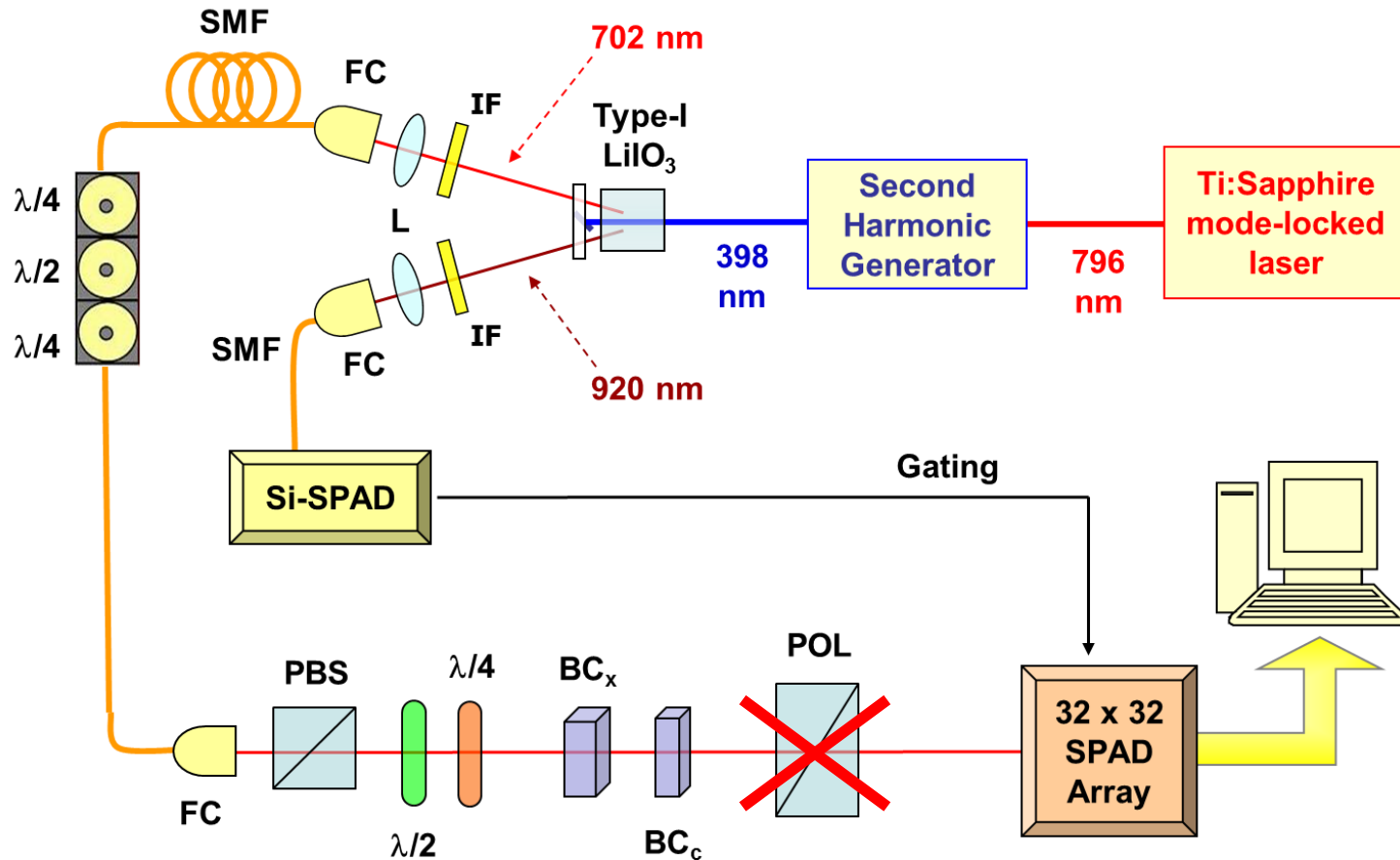
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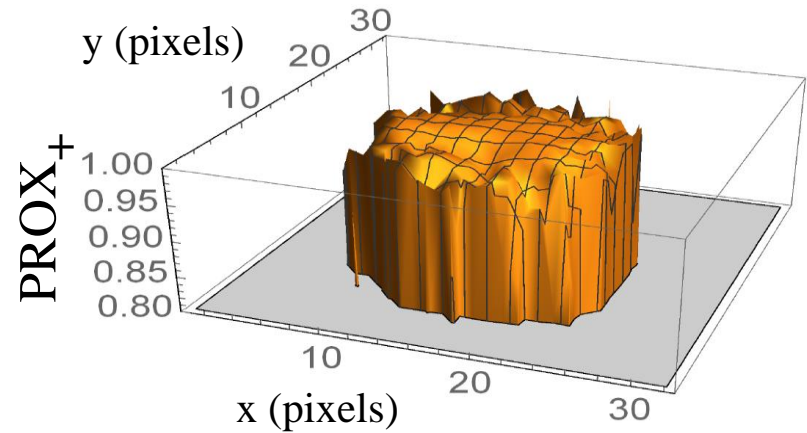
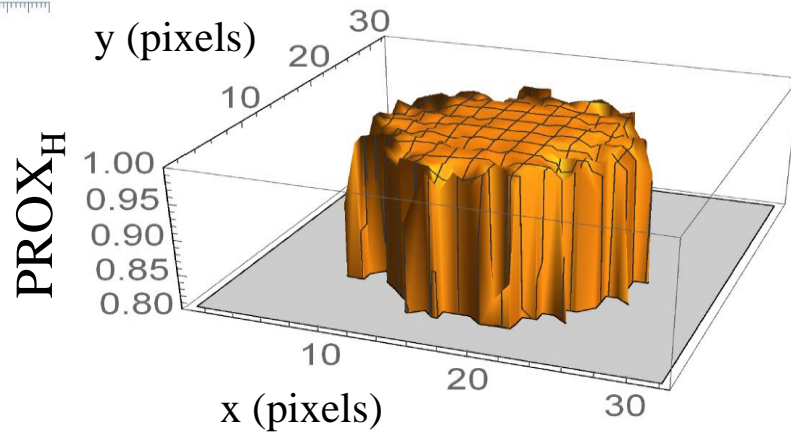
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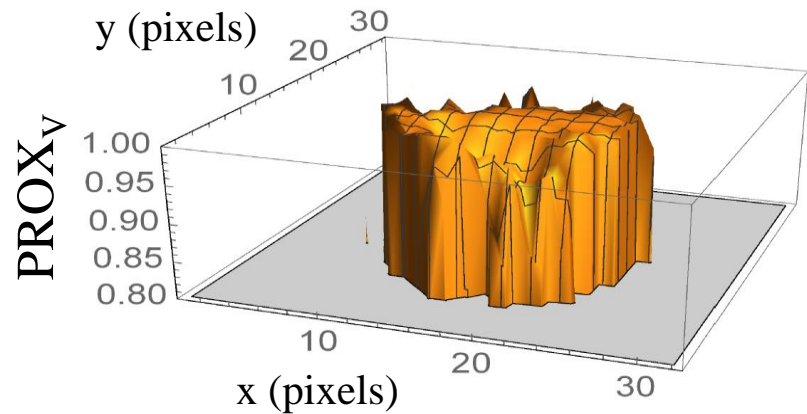
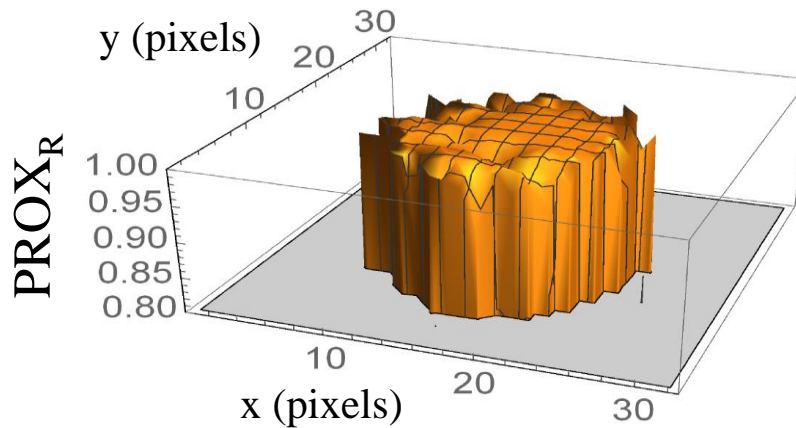
$\mathbb{P}(0|\mathcal{P}, \mathcal{M}_\Pi)$: probability of not undergoing the weak interaction

$\mathbb{P}(1|\mathcal{P}, \mathcal{M}_\Pi)$: probability of undergoing the weak interaction

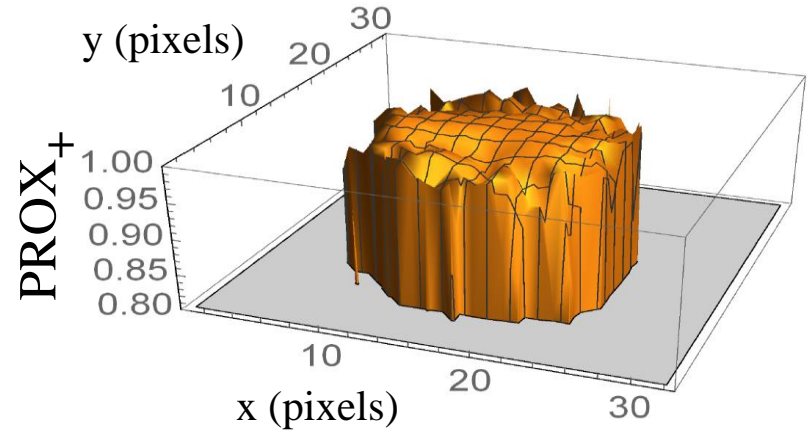
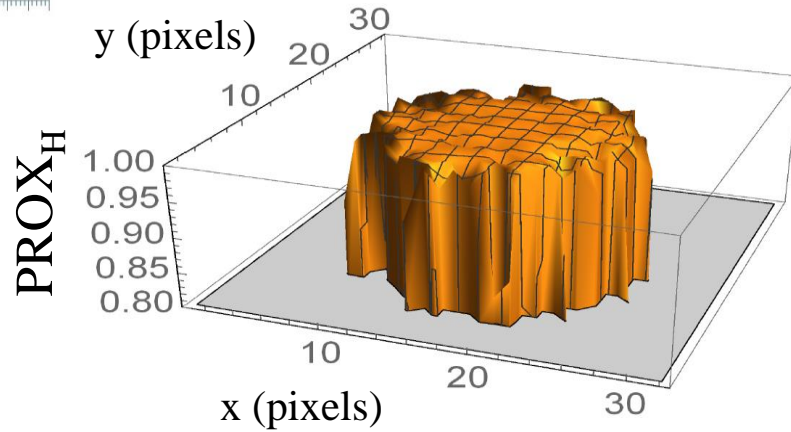
Condition 2 verification



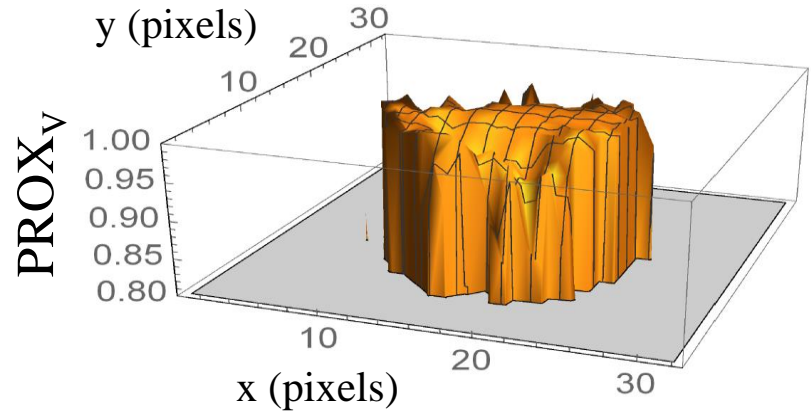
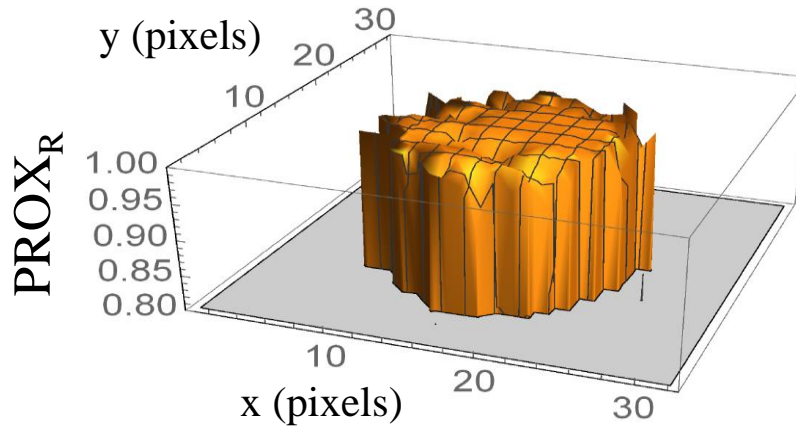
[arXiv:1602.02075](https://arxiv.org/abs/1602.02075)



Condition 2 verification



[arXiv:1602.02075](https://arxiv.org/abs/1602.02075)

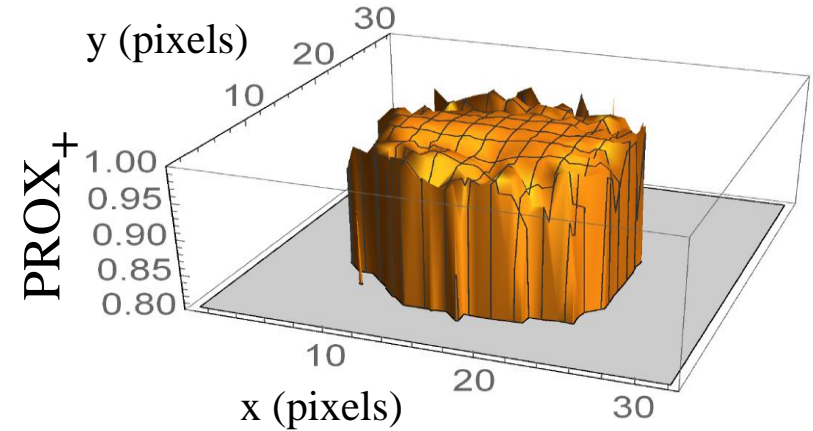
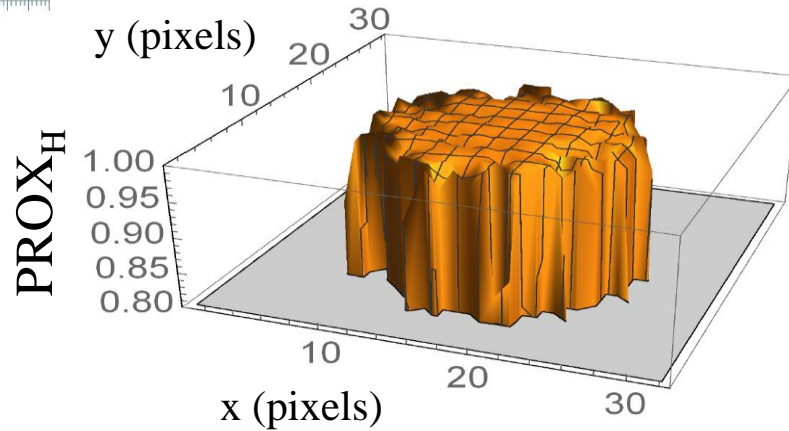


$$PROX_{\psi}(x) = \left[\frac{2Q(x)Q^{(e)}(x)}{(Q(x))^2 + (Q^{(e)}(x))^2} \right]^{\frac{1}{2}}$$

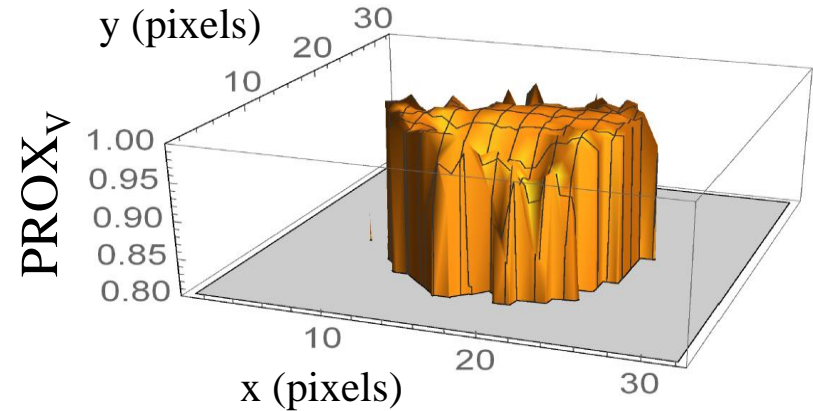
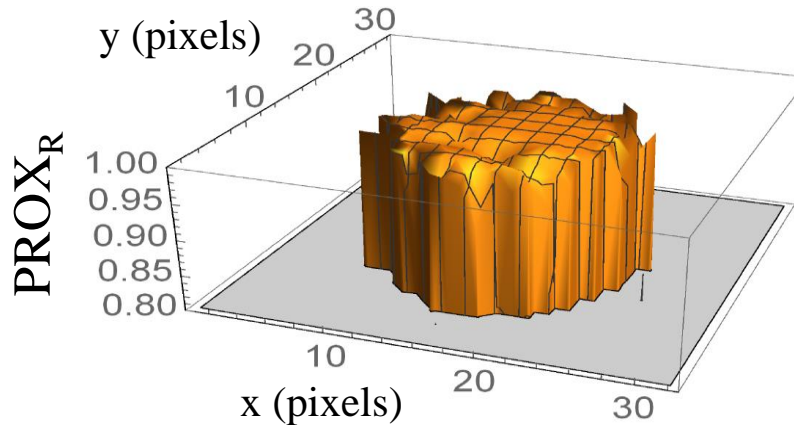
$$Q(x) = \mathbb{P}(x|\mathcal{P}, \mathcal{M}_W)$$

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Condition 2 verification



[arXiv:1602.02075](https://arxiv.org/abs/1602.02075)



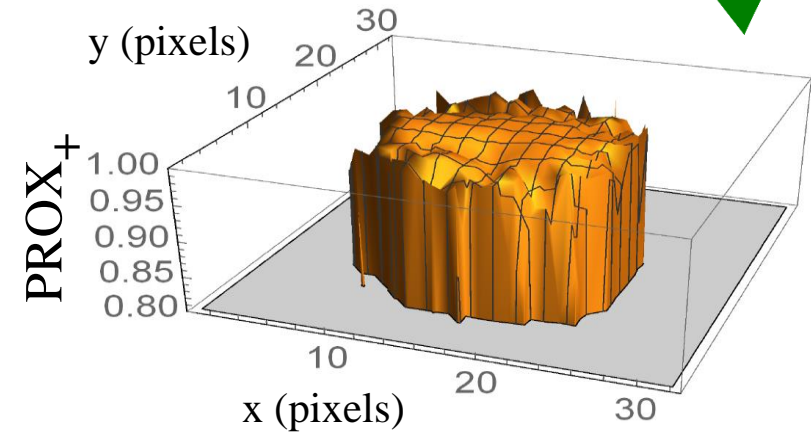
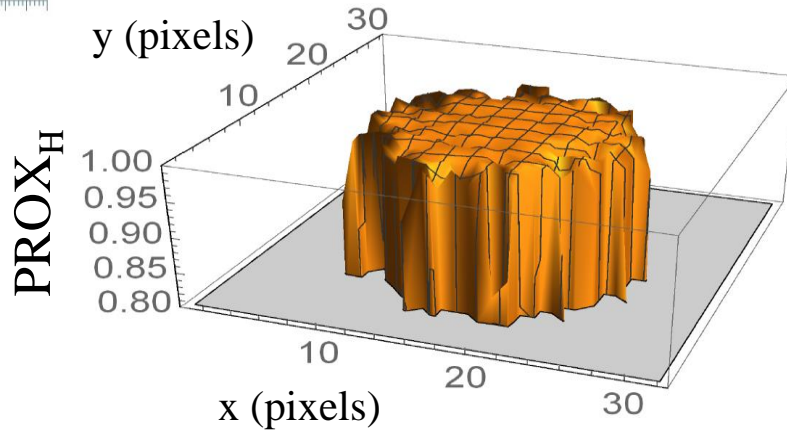
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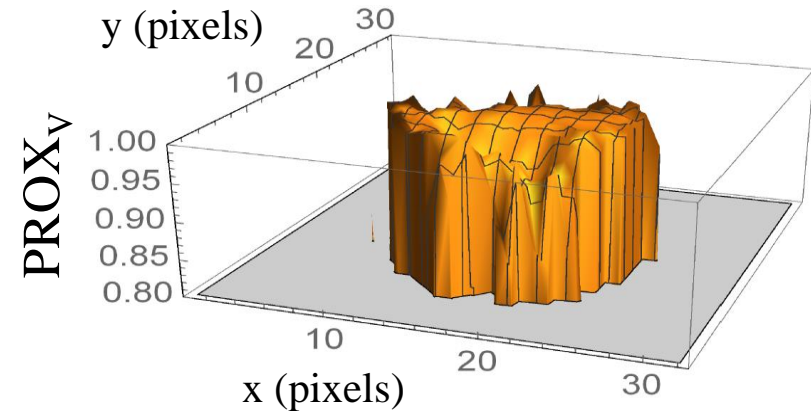
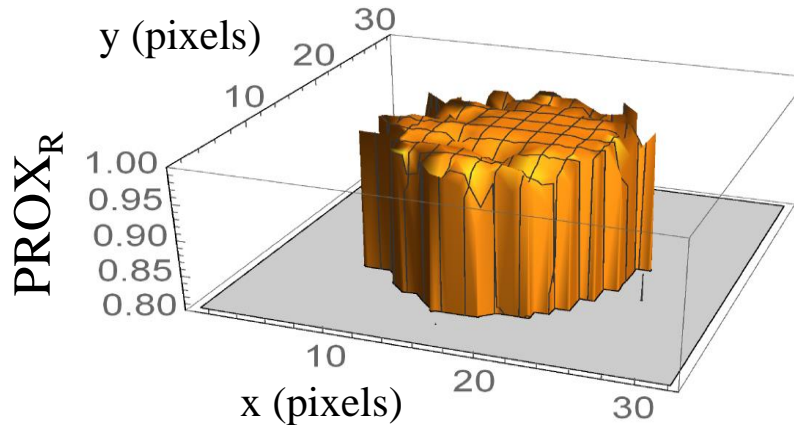
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Fidelity between $Q(x)$ and $Q^{(e)}(x)$ always above 99% (sampling on >230 points)

Condition 2 verification



[arXiv:1602.02075](https://arxiv.org/abs/1602.02075)



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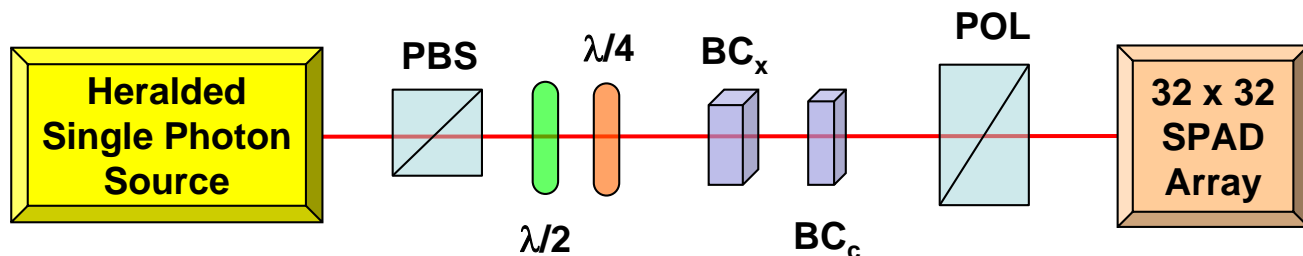
Condition 3 verification

$$\exists p_d : \mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_W, \mathcal{M}_{\psi_f}) = (1-p_d)\mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_{\psi_f}) + p_d\mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_d)$$

Condition 3 verification

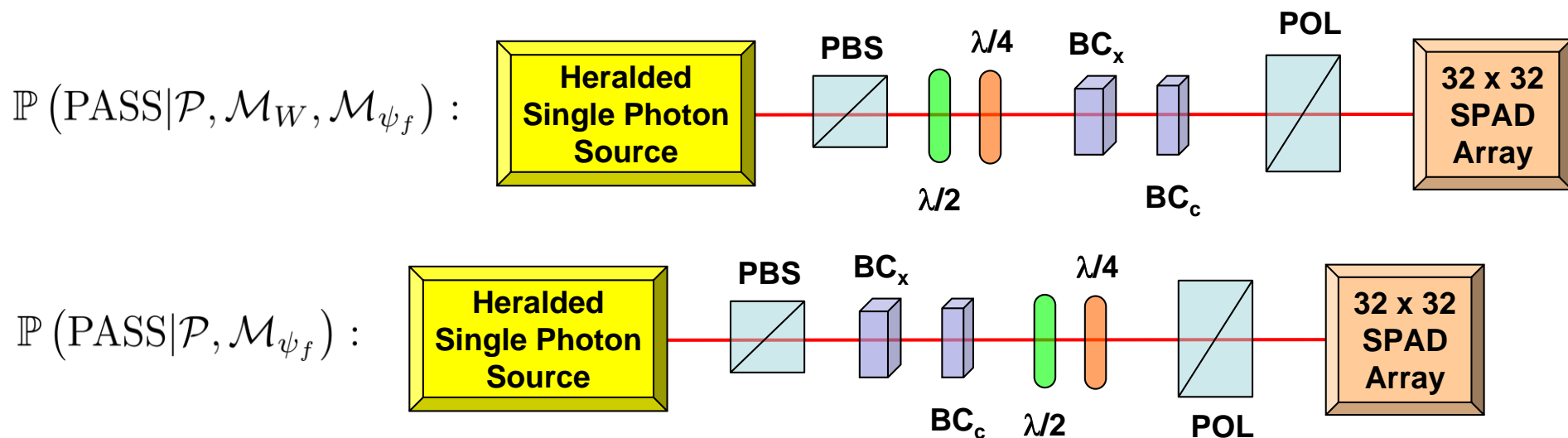
$$\exists p_d : \mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_W, \mathcal{M}_{\psi_f}) = (1-p_d)\mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_{\psi_f}) + p_d\mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_d)$$

$\mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_W, \mathcal{M}_{\psi_f}) :$



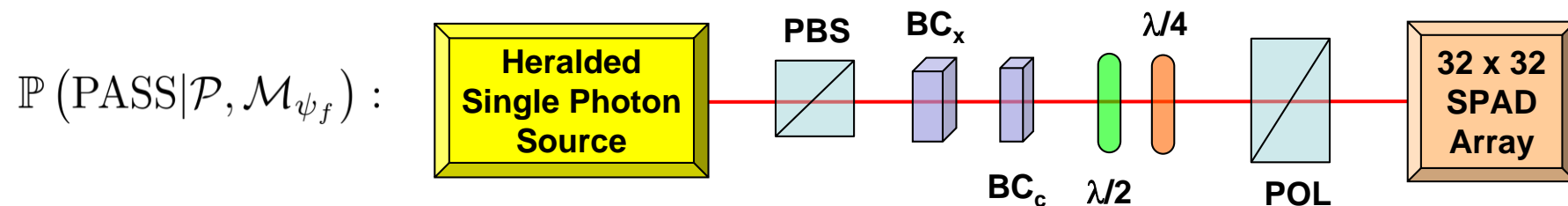
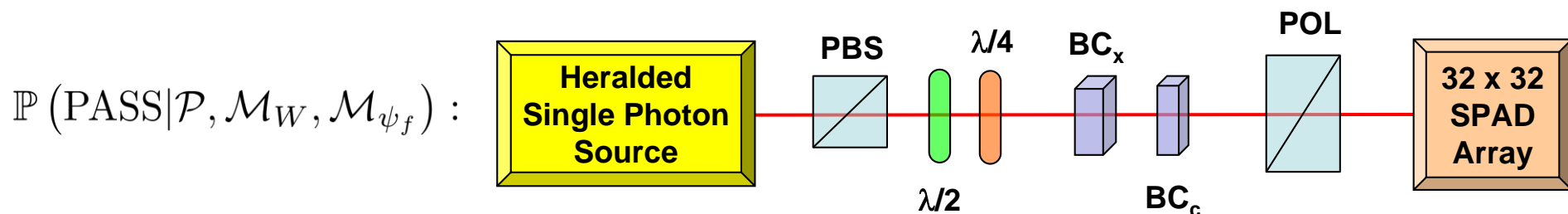
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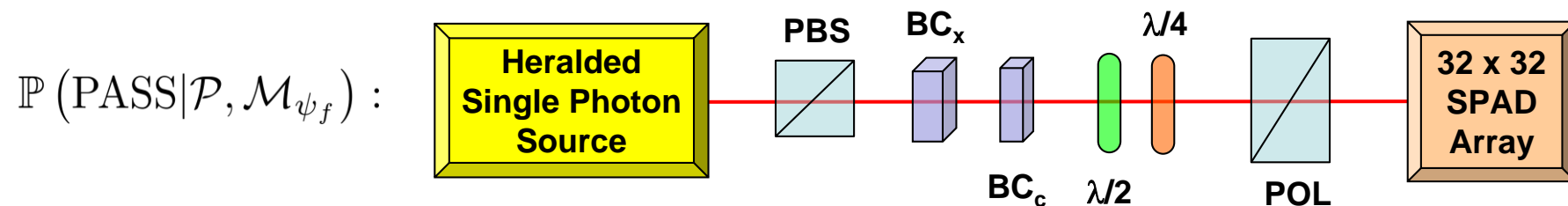
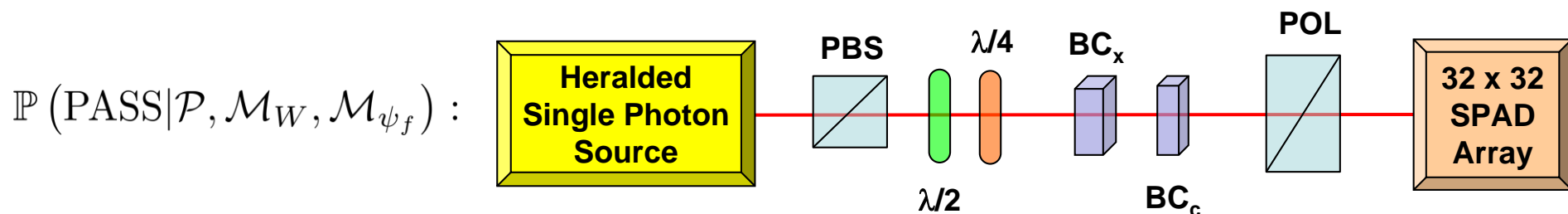
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\mathcal{M}_d is unknown $\Rightarrow \mathbb{P}(\text{PASS}|\mathcal{P}, \mathcal{M}_d) = ??$

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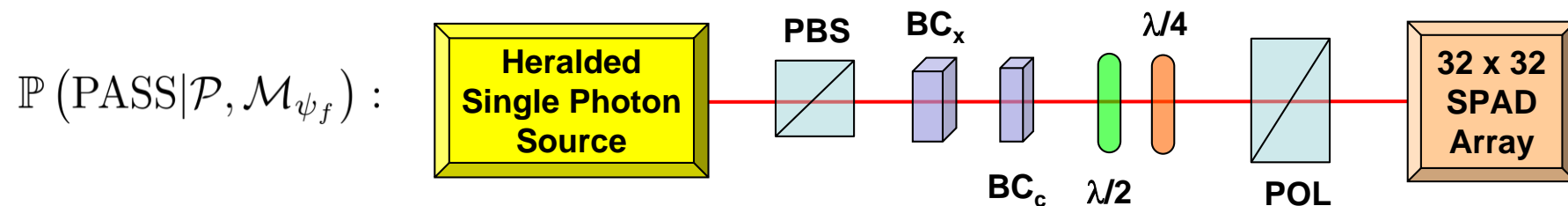
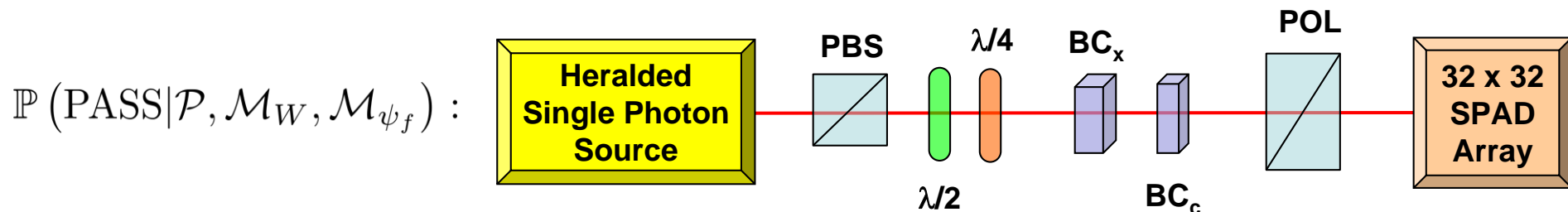
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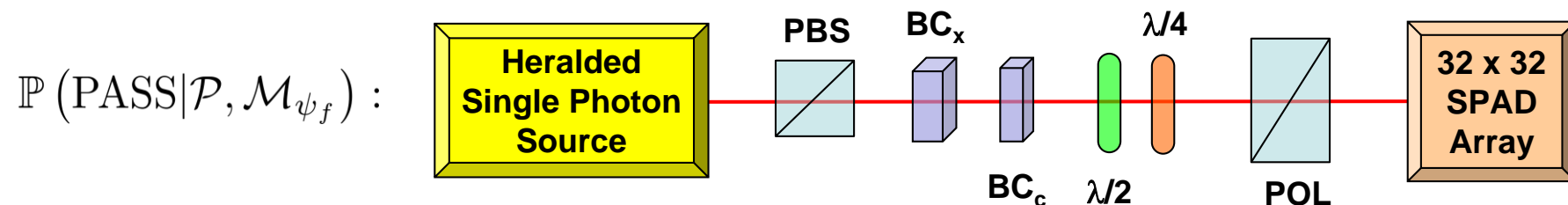
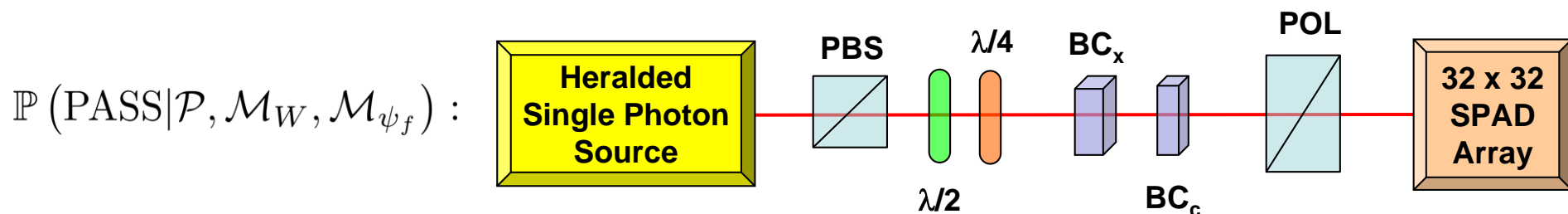


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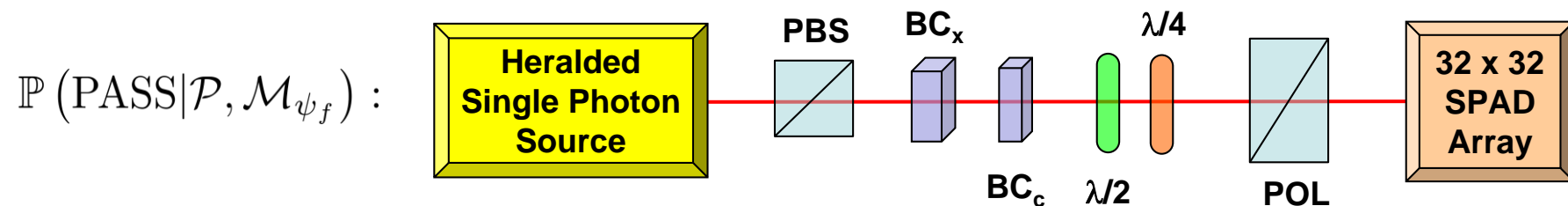
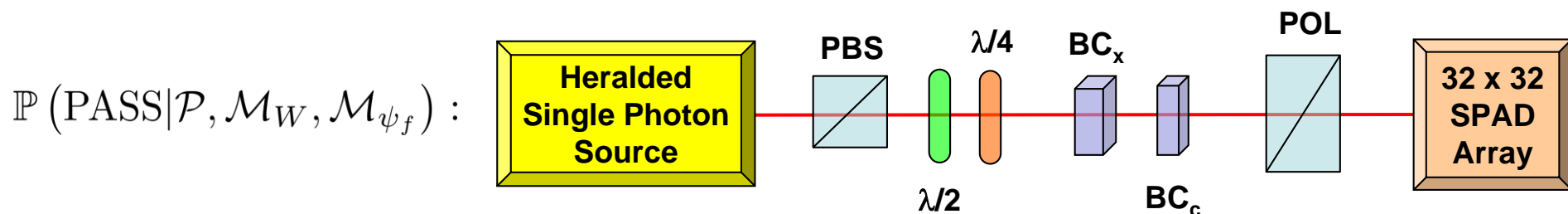
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arXiv:1602.02075

$$(0.000021 \pm 0.000014) \leq p_d \leq (0.086 \pm 0.050)$$

Condition 3 verification

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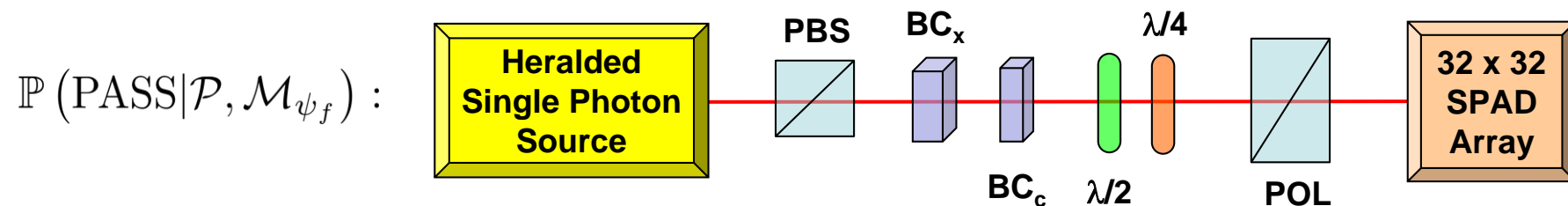
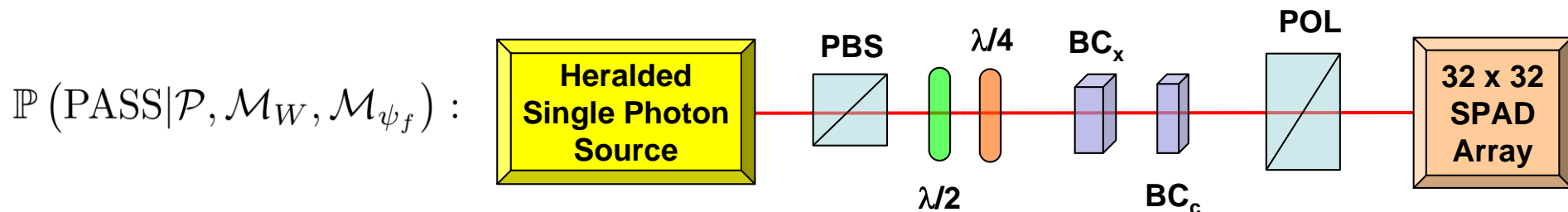
$$p_d = 0.0019 \pm 0.0002 \text{ fits in!}$$



Condition 3 verification



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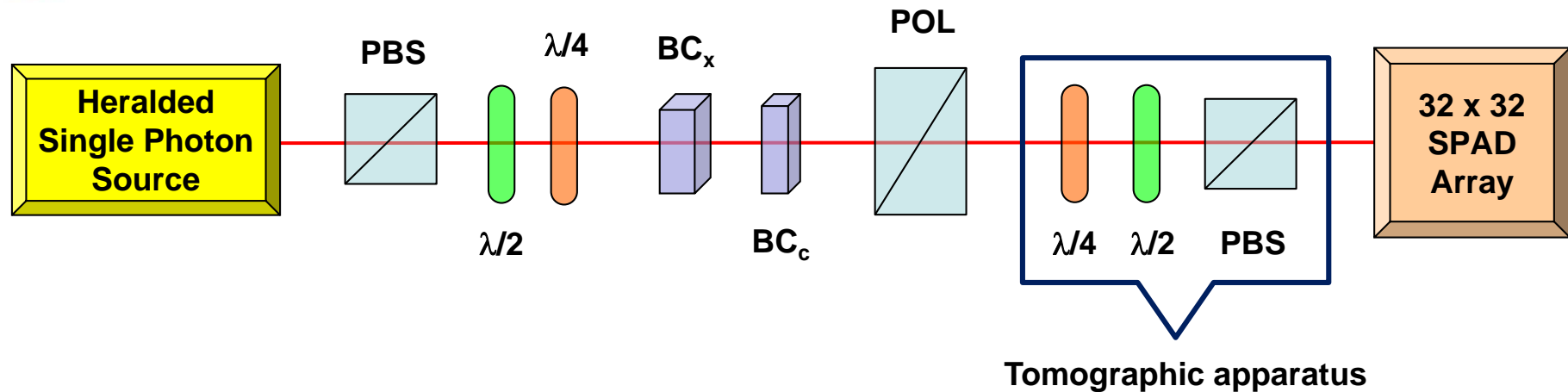
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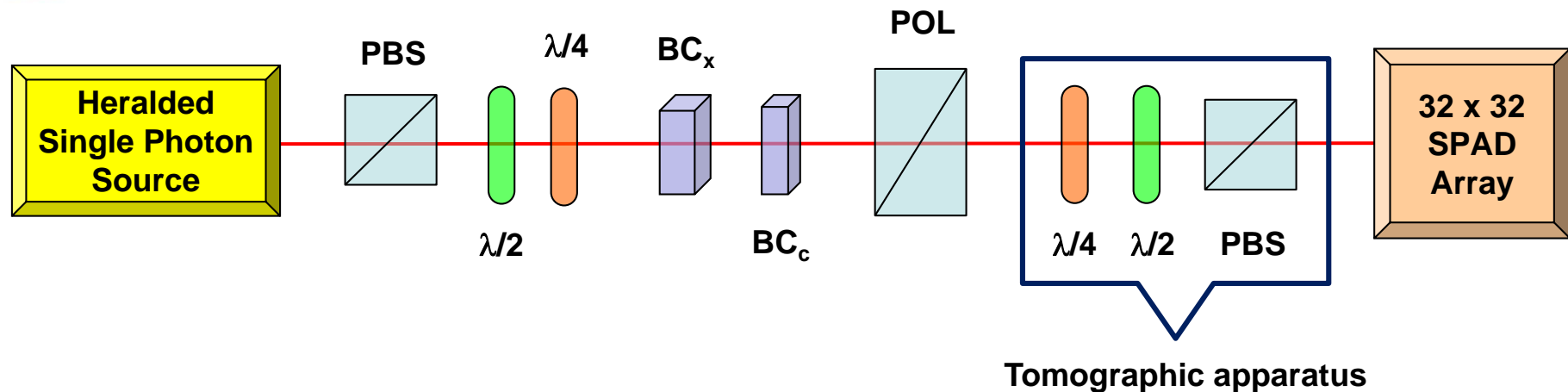
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Condition 3: consistency check

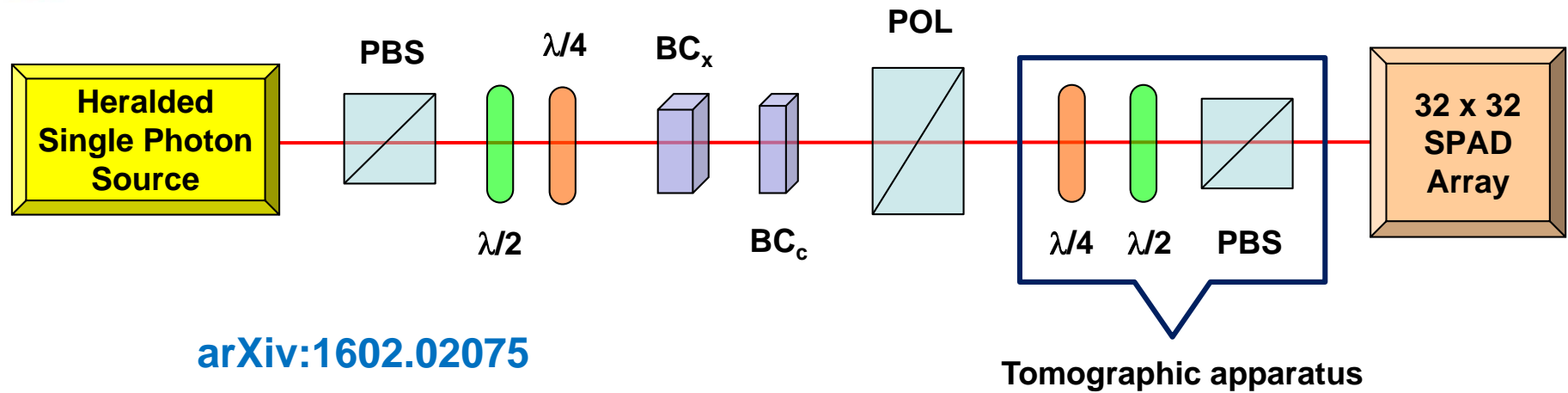


Condition 3: consistency check



We produce the (tomographically complete) set of states $\{|H\rangle, |+\rangle, |L\rangle, |R\rangle\}$, and perform quantum tomography after post-selection, calculating the fidelity with respect to the post-selected state $|\psi_f\rangle = \cos(0.18\pi)|H\rangle + \sin(0.18\pi)|V\rangle$:

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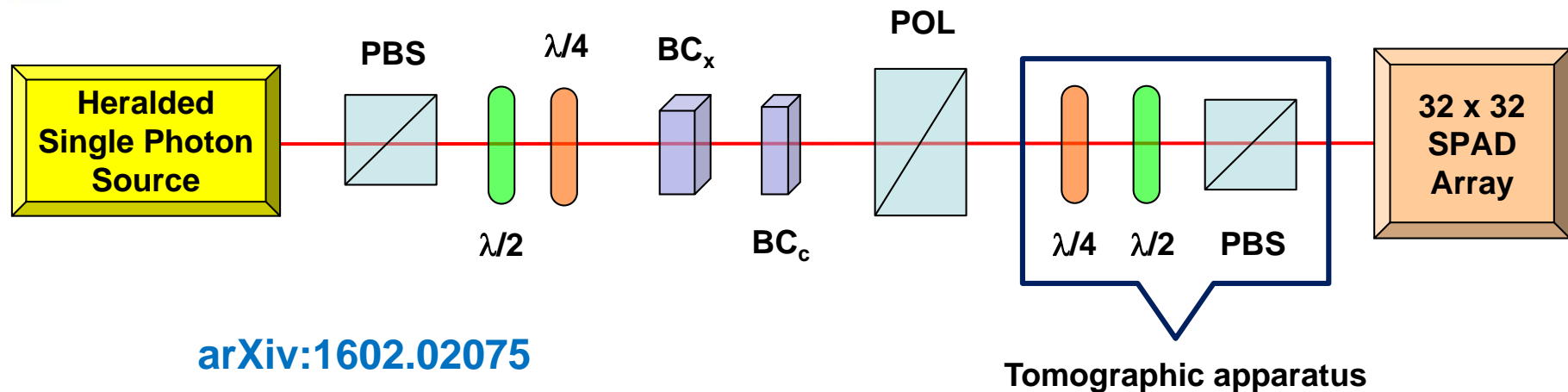
$$\mathcal{F}_H = 0.9995$$

$$\mathcal{F}_+ = 0.9999$$

$$\mathcal{F}_L = 0.9991$$

$$\mathcal{F}_R = 0.9811$$

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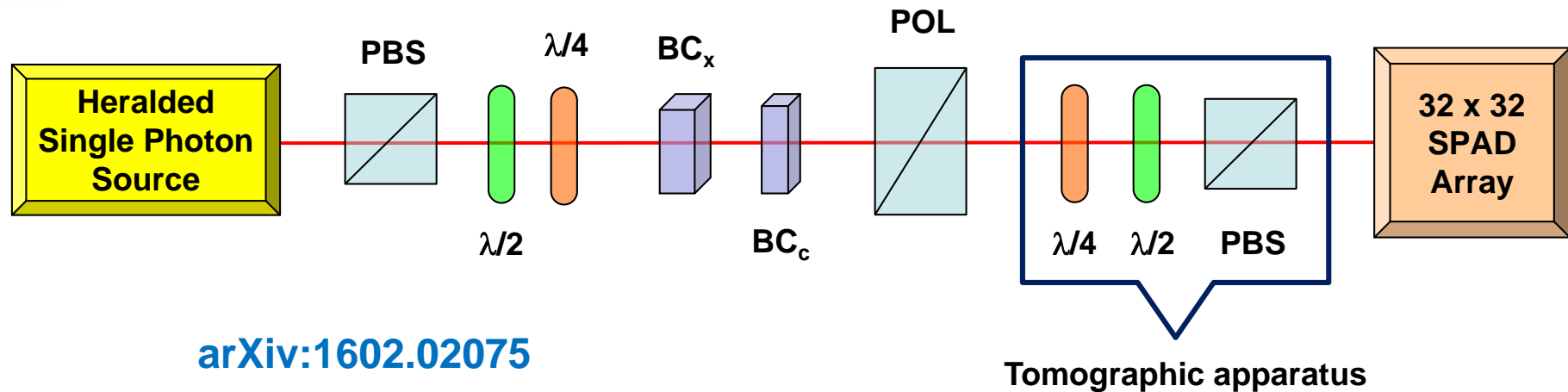
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$$p_d = 0.0051 \pm 0.0046$$

Condition 3: consistency check



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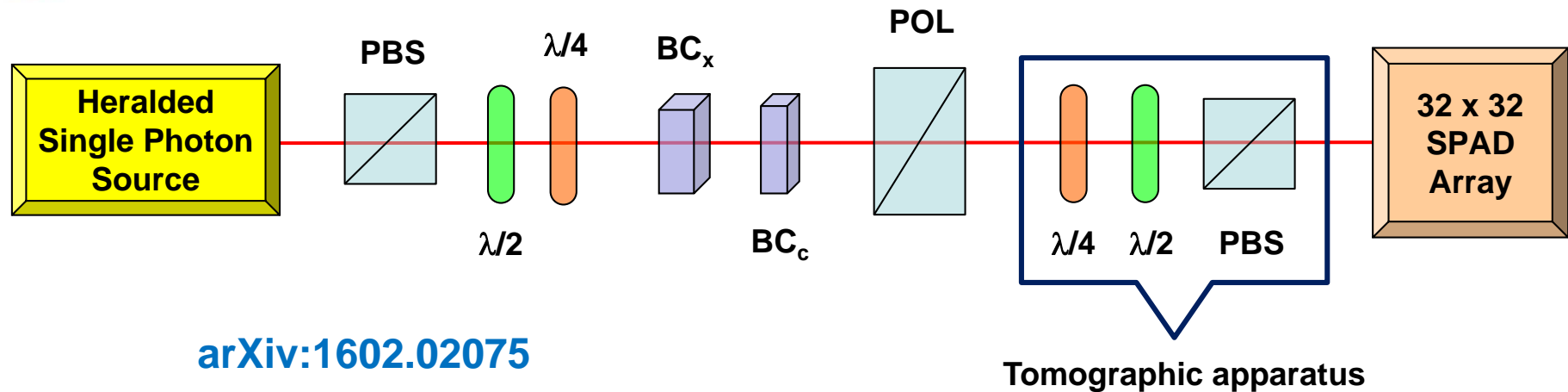


$$p_d = 0.0051 \pm 0.0046$$



$$p_d = 0.0019 \pm 0.0002$$

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We produce the (tomographically complete) set of states $\{|H\rangle, |+\rangle, |L\rangle, |R\rangle\}$, and perform quantum tomography after post-selection, calculating the fidelity with respect to the post-selected state $|\psi_f\rangle = \cos(0.18\pi)|H\rangle + \sin(0.18\pi)|V\rangle$:

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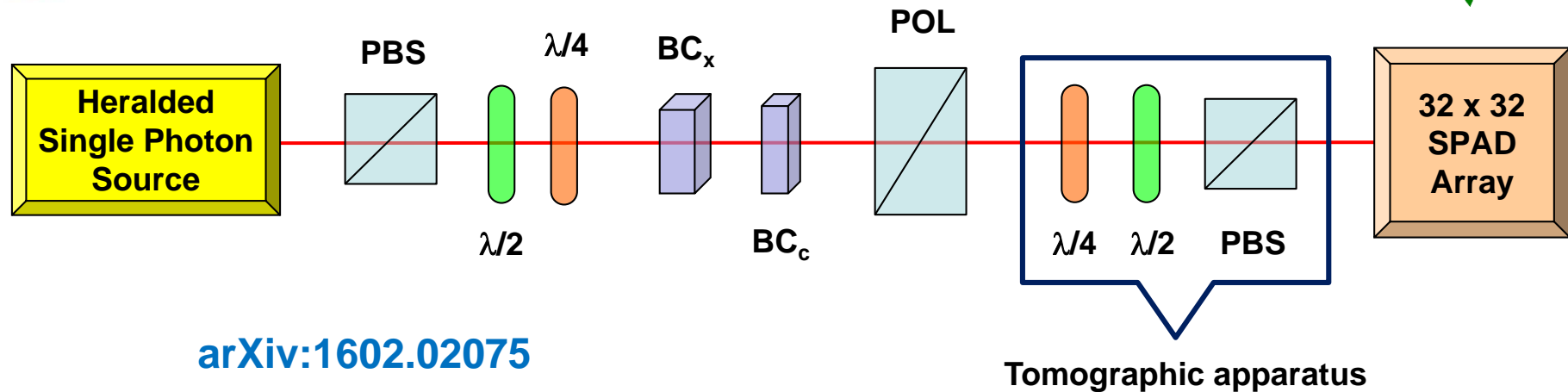


$$p_d = 0.0051 \pm 0.0046$$

$$p_d = 0.0019 \pm 0.0002$$

$$(0.000021 \pm 0.000014) \leq p_d \leq (0.086 \pm 0.050)$$

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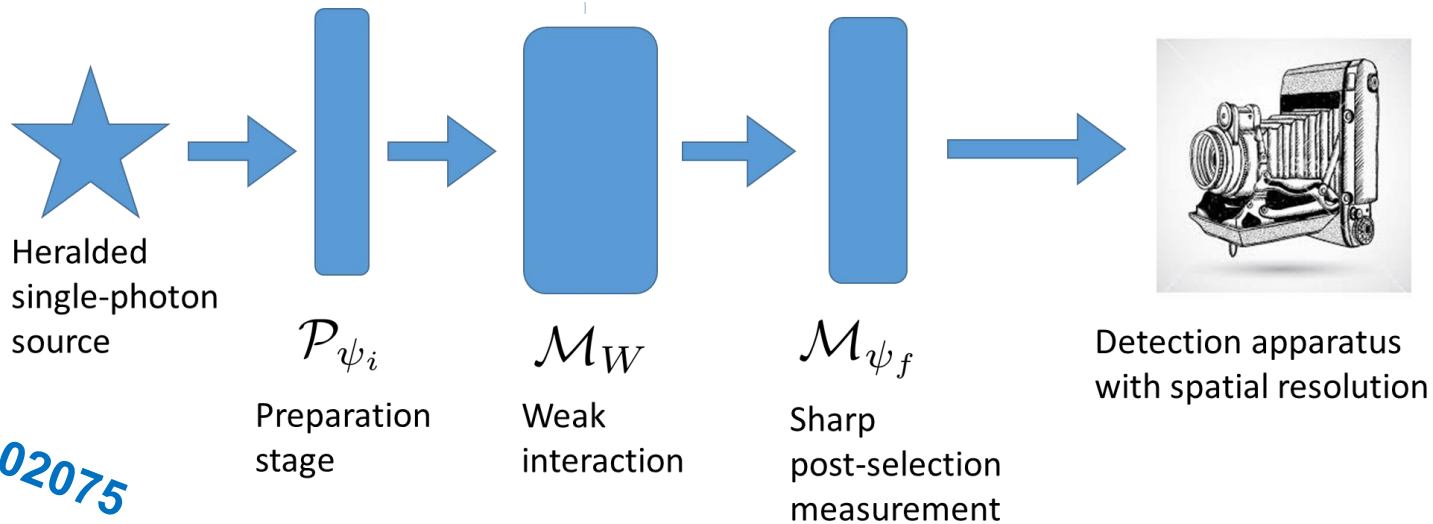


$$p_d = 0.0051 \pm 0.0046$$

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WM and contextuality: final check



arXiv:1602.02075

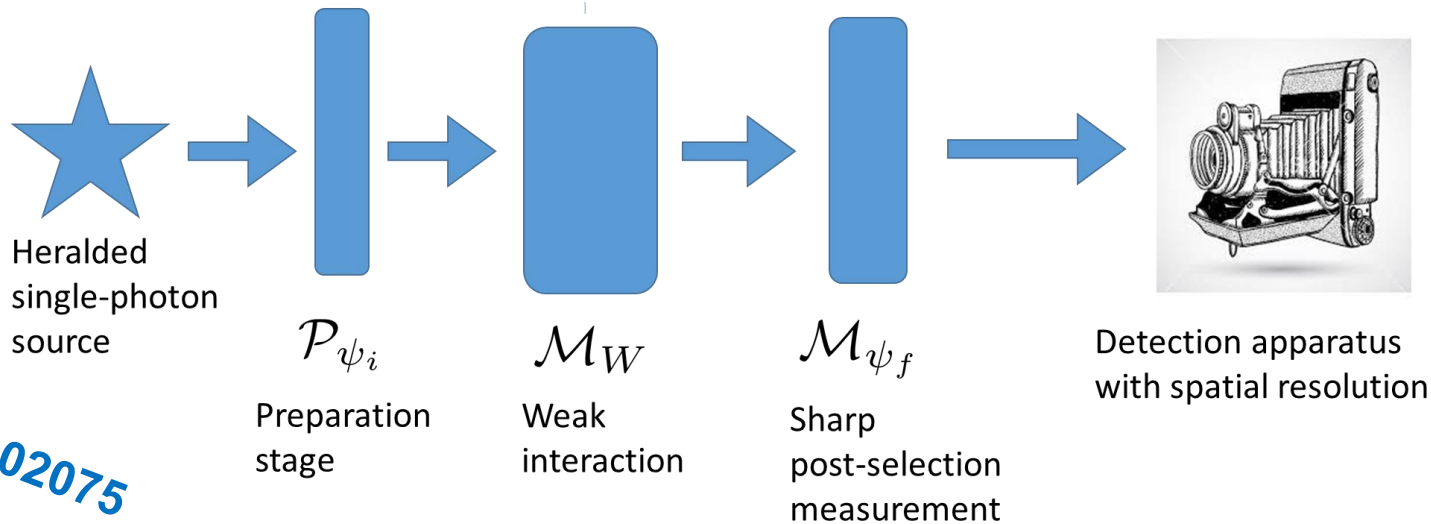
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Without post-selection: $\mathbb{P}(x | \mathcal{P}, \mathcal{M}_W) = p_n(x-g) \mathbb{P}(1 | \mathcal{P}, \mathcal{M}_{\Pi}) + p_n(x) \mathbb{P}(0 | \mathcal{P}, \mathcal{M}_{\Pi}) \quad \forall \mathcal{P}$

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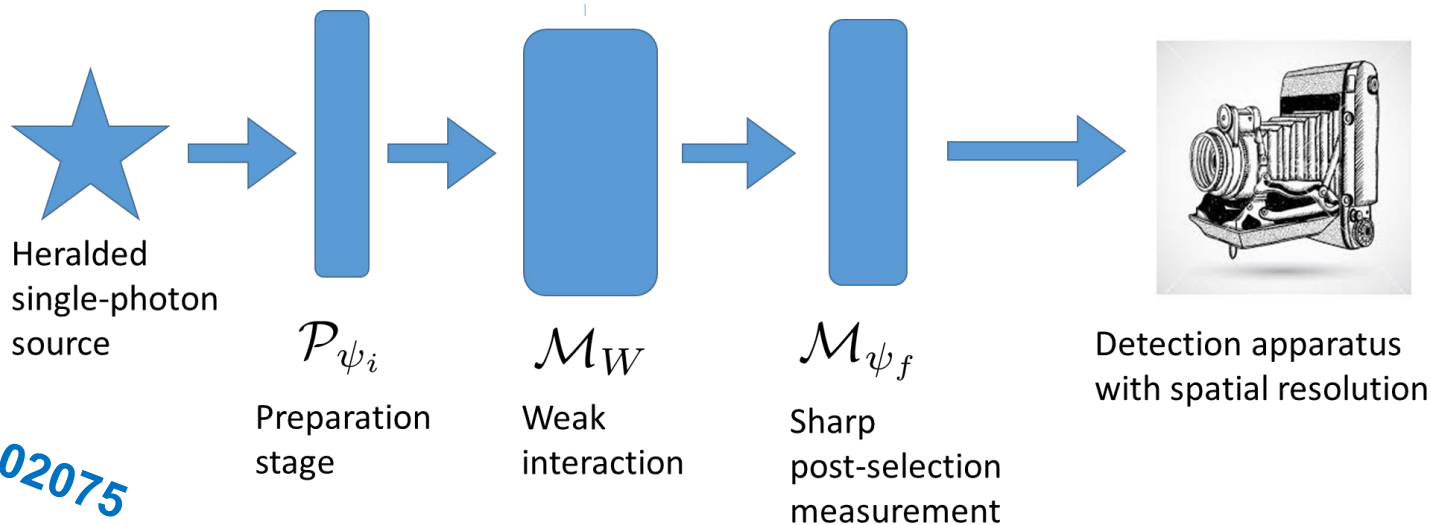
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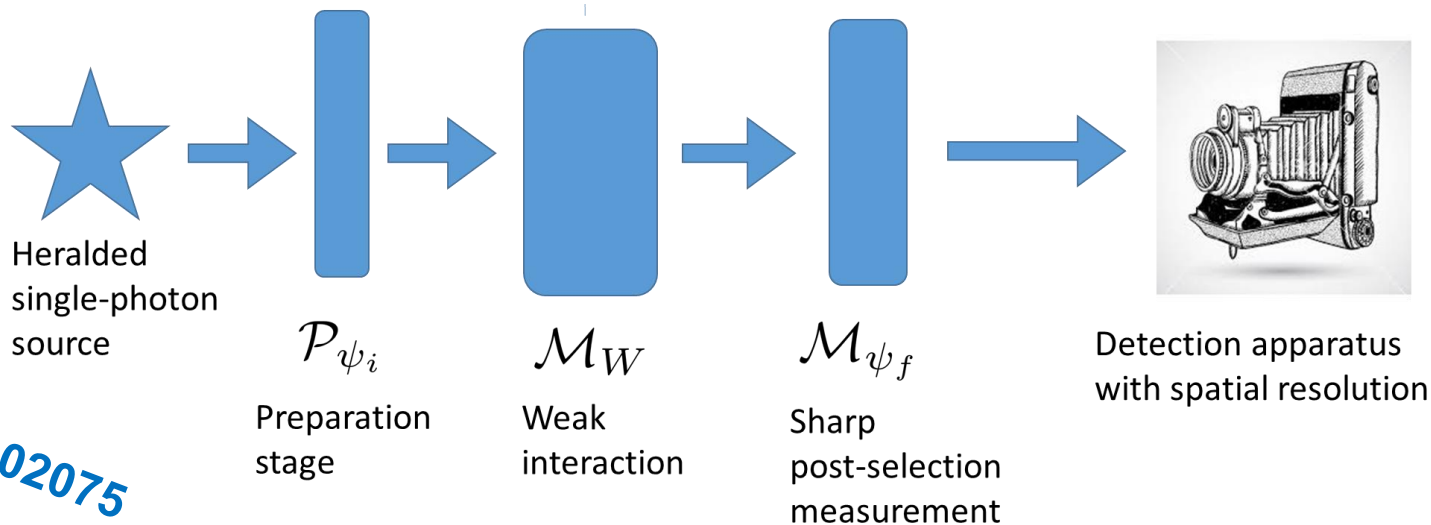
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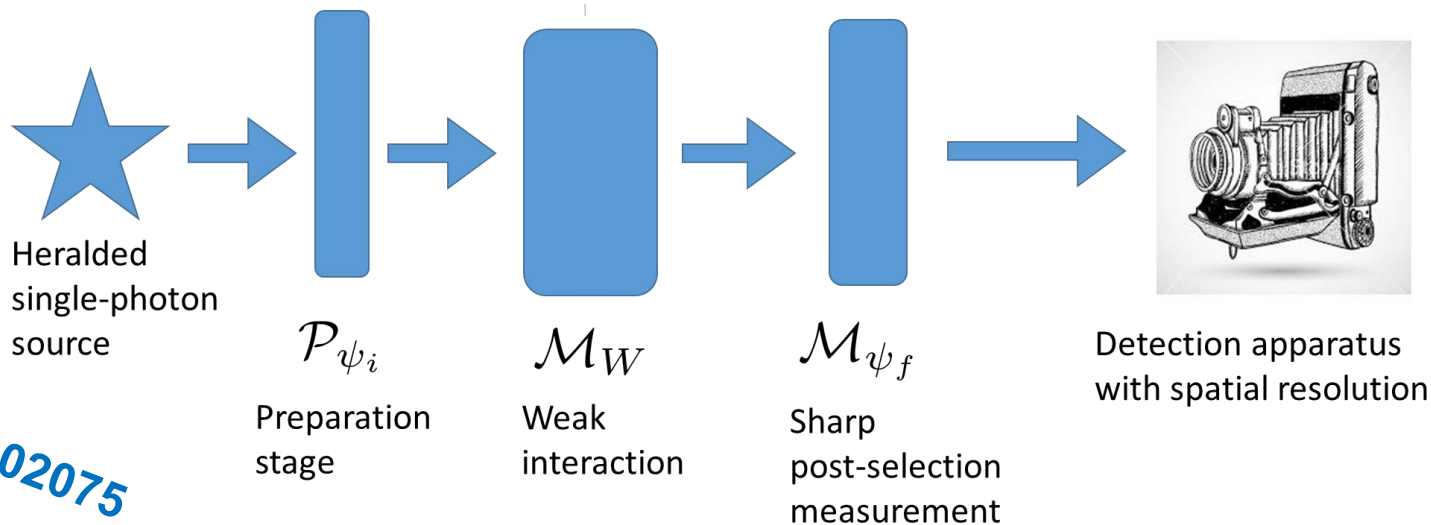
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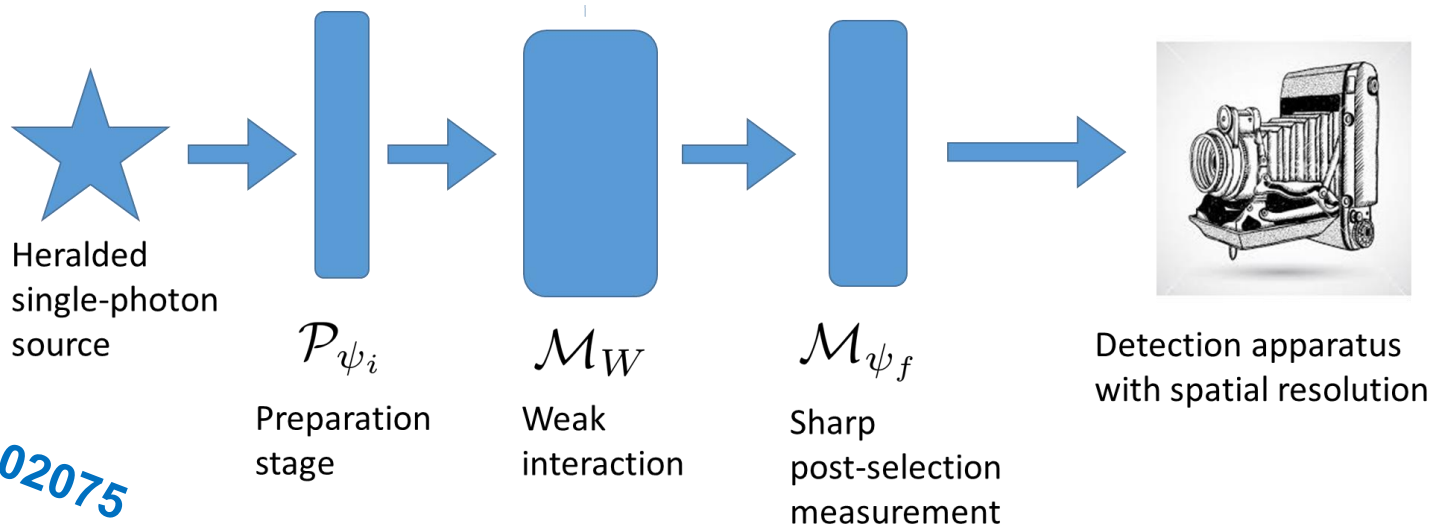
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No non-contextual model allowed: weak measurements proved quantum contextuality

The weak crew

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Mattia P. Levi

Alessio Avella

Marco Gramegna

Giorgio Brida

Ivo P. Degiovanni

Marco Genovese



*“Measuring incompatible
observables of a single photon”*
arXiv:1508.03220

Eliahu Cohen



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*“An experiment investigating
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Thanks for
your
attention!!

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