

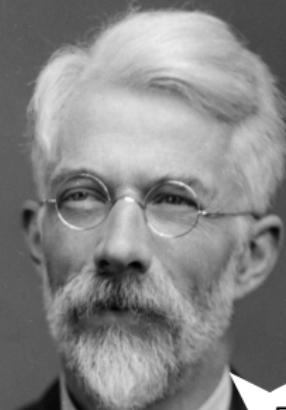
Quantum metrology with full and fast quantum control

Pavel Sekatski, Michalis Skotiniotis, Janek Kolodynski, Wolfgang Dür

0.Background

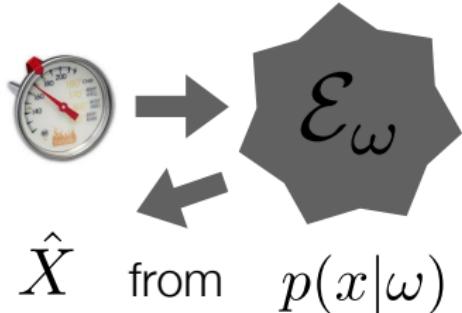


Metrology



5 more
minutes!

Metrology

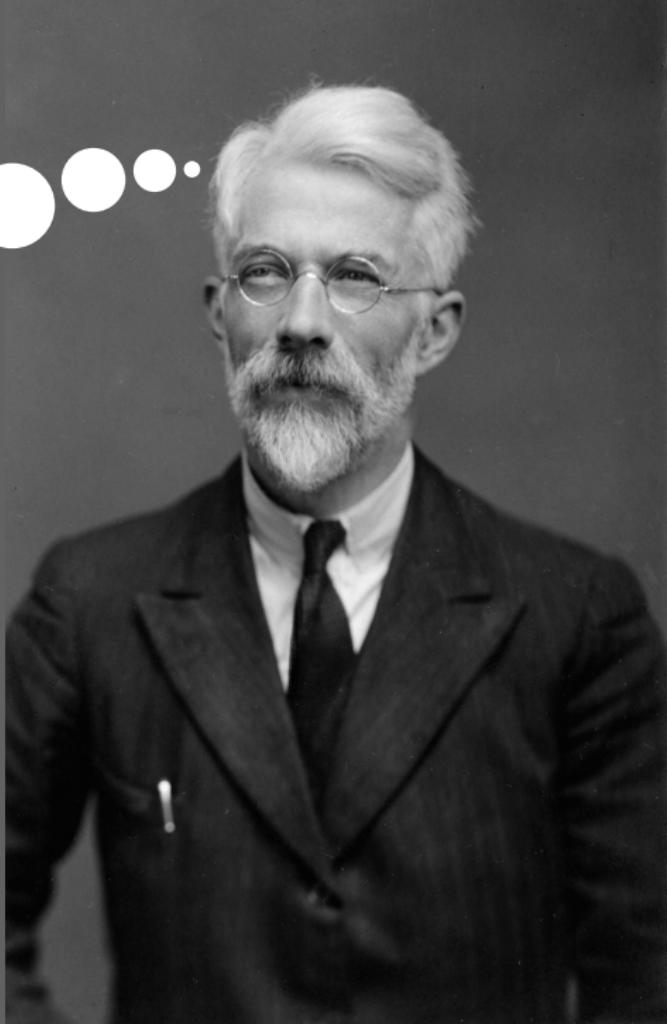


Fisher information:

$$\mathcal{F}_\omega = \sum_x \frac{\dot{p}(x|\omega)^2}{p(x|\omega)}$$

Cramer-Rao bound:

$$\delta\omega^2 \geq \frac{1}{\nu\mathcal{F}_\omega}$$



Quantum Metrology



Quantum Fisher information:

$$\mathcal{F}(\rho_\omega) = 8 \lim_{d\omega \rightarrow 0} \frac{1 - F(\rho_{\omega+d\omega}, \rho_\omega)}{d\omega^2}$$

PHYSICAL REVIEW
LETTERS

VOLUME 72

30 MAY 1994

NUMBER 22

Statistical Distance and the Geometry of Quantum States

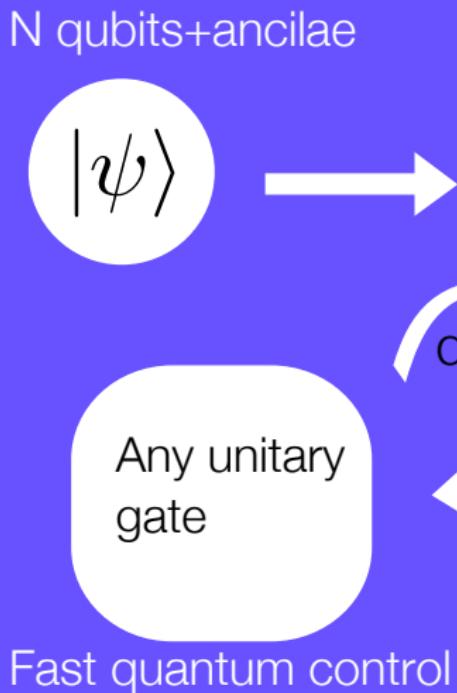
Samuel L. Braunstein* and Carlton M. Caves
Advanced Studies, Department of Physics and Astronomy, University of New Mexico,
Albuquerque, New Mexico 87131-1156
Received April 1993

1

.Introduction



Full and fast quantum control



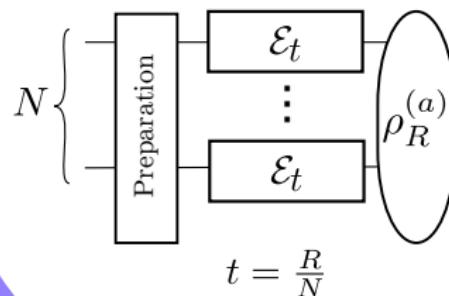
Evolution

$$H_\omega = \frac{\omega}{2} \sum_i \sigma_z^i$$

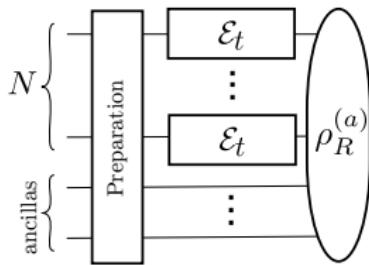
+ Noise

$$\rho_\omega(t)$$

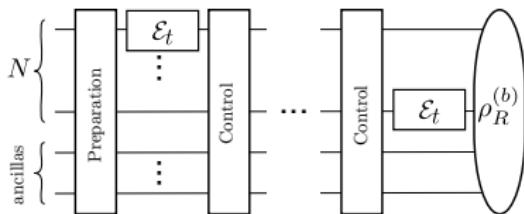
Parallel strategy



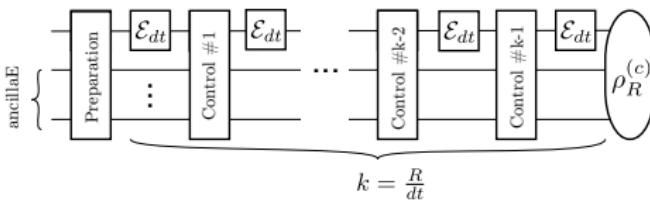
Parallel with ancilae



Sequential with full control



Sequential with full and fast control



Noise description

(how fast is fast?)

ultrafast

superduperfast

Lindbladian description

Hamiltonian description



Master equation

$$\dot{\rho} = i[H_\omega, \rho] + \sum_i \mathcal{L}_i(\rho)$$

(time homogenous)

Next talk!



Lindbladian noise

$$\mathcal{L}(\rho) := \frac{1}{2} \sum_{\mu, \nu=0}^3 \mathsf{L}_{\mu\nu} ([\sigma_\mu \rho, \sigma_\nu] + [\sigma_\mu, \rho \sigma_\nu])$$

Rank-one Pauli (dephasing)

Rank-one noise

$$\text{Re}(\mathbf{r}) \times \text{Im}(\mathbf{r}) = 0$$

$$\bar{\mathsf{L}}_{\mathbf{r}}^{1G} := \mathbf{r} \mathbf{r}^\dagger$$

Amplitude damping

$$|\text{Re}(\mathbf{r})| = |\text{Im}(\mathbf{r})| \text{ and } \text{Re}(\mathbf{r})^T \text{Im}(\mathbf{r}) = 0$$

Rank-two Pauli noise

$$\bar{\mathsf{L}}_{\boldsymbol{\Omega}}^{2P} := \frac{1}{2} R_{\boldsymbol{\Omega}}^T \begin{pmatrix} \gamma_1 & & \\ & \gamma_2 & \\ & & 0 \end{pmatrix} R_{\boldsymbol{\Omega}}$$

A few remarks

1. Unitary noise can be removed

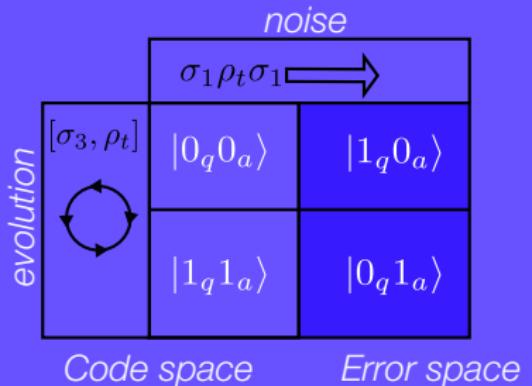
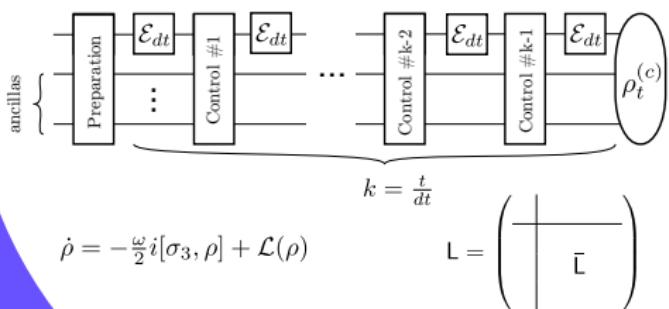
2. Perpendicular Pauli noise can be corrected:

$$\rho_{t+dt} = \rho_t(1 - \frac{\gamma}{2}dt) - idt \frac{\omega}{2} [\sigma_3, \rho_t] + dt \frac{\gamma}{2} \sigma_1 \rho_t \sigma_1 + O(dt^2)$$

Encoding:

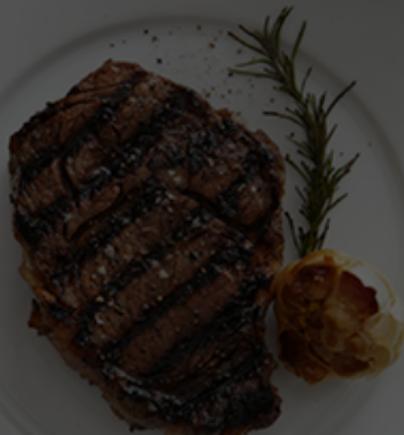
$$|0\rangle \rightarrow |0_q 0_a\rangle$$

$$|1\rangle \rightarrow |1_q 1_a\rangle$$



2.Quntum

metrology
with full
and fast
control



Bounding the QFI of a channel

Uhlmann-Josza Fidelity

$$F(\mathcal{E}_{\omega_1}(|\psi\rangle), \mathcal{E}_{\omega_2}(|\psi\rangle)) \geq F\left(\sum_k K_k^{\omega_1} |\psi\rangle\langle\psi| K_k^{\omega_1\dagger}, \sum_k \tilde{K}_k^{\omega_2} |\psi\rangle\langle\psi| \tilde{K}_k^{\omega_2\dagger}\right) \geq$$

$$\sum_k \sqrt{p_k \tilde{p}_k} F\left(\frac{K_k^{\omega_1} |\psi\rangle}{\sqrt{p_k}}, \frac{\tilde{K}_k^{\omega_2} |\psi\rangle}{\sqrt{\tilde{p}_k}}\right) \geq \sum_k |\langle\psi| K_k^{\omega_1\dagger} \tilde{K}_k^{\omega_2} |\psi\rangle| \geq |\langle\psi| \sum_k K_k^{\omega_1\dagger} \tilde{K}_k^{\omega_2} |\psi\rangle|$$

Quantum Fisher Information

$$\mathcal{F}_{\mathcal{E}(\omega)} \leq 4 |\langle\psi| \sum_k \dot{K}_k^{\omega\dagger} \dot{K}_k^{\omega} |\psi\rangle| \leq 4 \|\sum_k \dot{K}_k^{\omega\dagger} \dot{K}_k^{\omega}\|$$

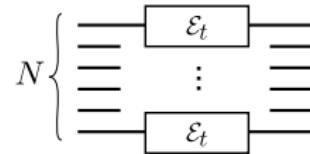
Explicit dependence on the parameter



Bound for a parallel channel

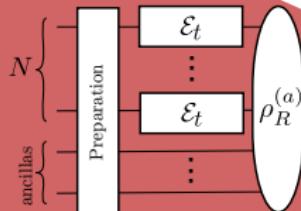
Kraus representation

$$K_{\mathbf{k}}^{\omega} = K_{k_1}^{\omega} \otimes \dots \otimes K_{k_N}^{\omega}$$



Quantum Fisher Information

$$\mathcal{F}_{\mathcal{E}(\omega)} \leq 4N \underbrace{\left\| \sum_k \dot{K}_k^{\omega\dagger} \dot{K}_k^{\omega} \right\|}_{{||\alpha(t)||}} + 4N(N-1) \underbrace{\left\| \sum_k \dot{K}_k^{\omega\dagger} K_k^{\omega} \right\|^2}_{{||\beta(t)||^2}} = 0$$



Linear scaling in N!

Sequential channel with control

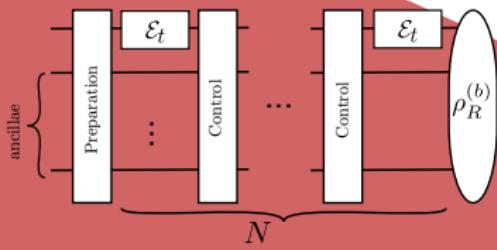
Kraus representation

$$K_{\mathbf{k}}^{\omega} = K_{k_N}^{\omega} U_N \dots K_{k_1}^{\omega} U_1^{\omega}$$

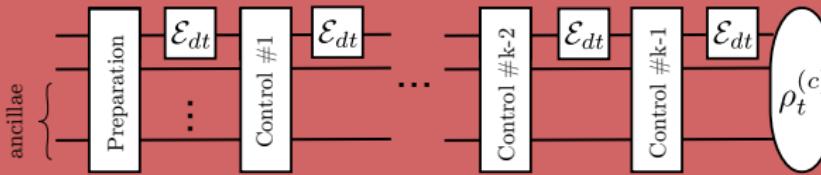
Quantum Fisher Information

$$\mathcal{F}_{\mathcal{E}(\omega)} \leq 4N \|\alpha(t)\| + 4N(N-1)\|\beta(t)\| \left(\|\beta(t)\| + \frac{\|\alpha(t)\|}{x} + x \right)$$

$$\|\beta(t)\| = 0$$



Linear scaling in N !



$$\mathcal{F}_{\mathcal{E}(\omega)} \leq 4k \|\alpha(t)\| + 4k(k-1)\|\beta(t)\| (\|\beta(t)\| + \frac{\|\alpha(t)\|}{x} + x)$$

Take the limit $dt \rightarrow 0$ $k = \frac{t}{dt} \rightarrow \infty$

$$4\frac{t}{dt} \|\alpha(dt)\| + 4\frac{t^2}{dt^2} \|\beta(dt)\| (\|\beta(dt)\| + \frac{\|\alpha(dt)\|}{\sqrt{dt}} + \sqrt{dt})$$

No need to solve the master equation



$$\mathcal{E}_{dt}(\omega) = \mathcal{E}^{(0)} + dt \mathcal{E}^{(2)}(\omega) + \dots$$

trivial

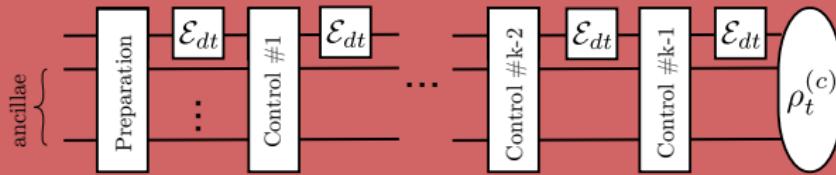
given by the Lindblad matrix L

$$\mathbf{K} = \mathbf{K}^{(0)} + \sqrt{dt} \mathbf{K}^{(1)} + dt \mathbf{K}^{(1)} + \dots$$

$$\alpha(dt) = \cancel{\alpha^{(0)}} + \cancel{\sqrt{dt} \alpha^{(1)}} + dt \alpha^{(2)} + \dots$$

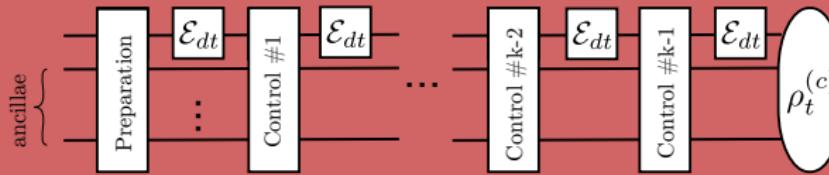
$$\mathbf{h} = \mathbf{h}^{(0)} + \sqrt{dt} \mathbf{h}^{(1)} + dt \mathbf{h}^{(2)} + \dots$$

$$\beta(dt) = \cancel{\beta^{(0)}} + \cancel{\sqrt{dt} \beta^{(1)}} + dt \beta^{(2)} + \dots$$



If there exist \mathbf{h} s.t. $\beta^{(2)} = 0$ then $\mathcal{F}(\rho_t(\omega)) \leq 4t \|\alpha^{(2)}\|$

$$\beta^{(2)} = i \left(\frac{-1}{2} \sigma_3 + \begin{pmatrix} \sigma_0 \\ \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{pmatrix}^\dagger \begin{pmatrix} h_{00}^{(2)} & \mathbf{h}^{(1)\dagger} \bar{\mathbf{L}}^{1/2} \\ \bar{\mathbf{L}}^{1/2} \mathbf{h}^{(1)} & \bar{\mathbf{L}}^{1/2} \mathbf{H}^{(0)} \bar{\mathbf{L}}^{1/2} \end{pmatrix} \begin{pmatrix} \sigma_0 \\ \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{pmatrix} \right)$$



Result 1: For all Lindbladians except the rank-one Pauli noise the QFI is upper-bounded by:

$$\mathcal{F}_{\mathcal{L}} \leq 4 \alpha_{\mathcal{L}} t$$

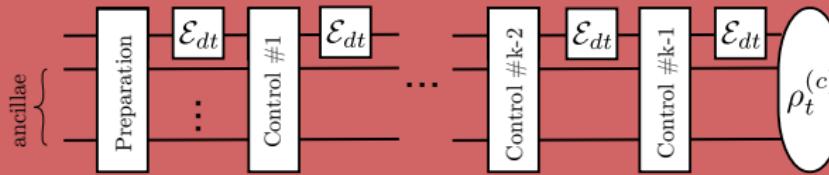
$$\bar{\mathsf{L}}_{\mathbf{r}}^{1G} := \mathbf{r} \mathbf{r}^\dagger$$

$$\mathcal{F}_{\mathbf{z}}^{1P} \leq \frac{t}{2\gamma}$$

$$\mathcal{F}_{\mathbf{r}}^{1G} \leq \frac{t \max |x \pm iy|^2}{4(|\text{Re}(\mathbf{r})|^2|\text{Im}(\mathbf{r})|^2 - (\text{Re}(\mathbf{r})^T \text{Im}(\mathbf{r}))^2)}$$

$$\bar{\mathsf{L}}_{\boldsymbol{\Omega}}^{2P} := \frac{1}{2} R_{\boldsymbol{\Omega}}^T \begin{pmatrix} \gamma_1 & & \\ & \gamma_2 & \\ & & 0 \end{pmatrix} R_{\boldsymbol{\Omega}}$$

$$\mathcal{F}_{\boldsymbol{\Omega}}^{2P} \leq \frac{t}{2\gamma_1\gamma_2} \left(c_\theta^2(\gamma_1 + \gamma_2) + s_\theta^2(\gamma_1 s_\varphi^2 + \gamma_2 c_\varphi^2) \right).$$



Result 1: For all Lindbladians except the rank-one Pauli noise the QFI is upper-bounded by:

$$\mathcal{F}_{\mathcal{L}} \leq 4 \alpha_{\mathcal{L}} t$$

NOISE WINS

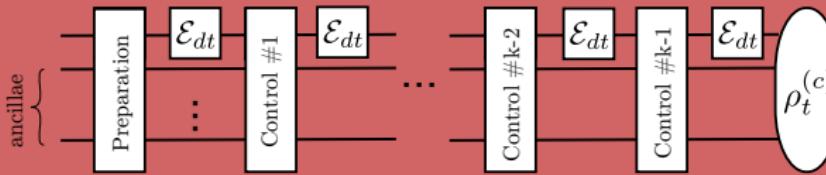
FATALITY

$$\bar{\mathsf{L}}_{\mathbf{r}}^{1G} := \mathbf{r} \mathbf{r}^\dagger$$

$$\bar{\mathsf{L}}_{\boldsymbol{\Omega}}^{2P} := \frac{1}{2} R_{\boldsymbol{\Omega}}^T \begin{pmatrix} \gamma_1 & & \\ & \gamma_2 & \\ & & 0 \end{pmatrix} R_{\boldsymbol{\Omega}}$$

$$\mathcal{F}_{\mathbf{r}} \leq \frac{t}{4(|\text{Re}(\mathbf{r})|^2|\text{Im}(\mathbf{r})|^2 - (\text{Re}(\mathbf{r})^T \text{Im}(\mathbf{r}))^2)}$$

$$\mathcal{F}_{\boldsymbol{\Omega}}^{2P} \leq \frac{t}{2\gamma_1\gamma_2} \left(c_\theta^2(\gamma_1 + \gamma_2) + s_\theta^2(\gamma_1 s_\varphi^2 + \gamma_2 c_\varphi^2) \right).$$



What about rank-one Pauli noise $\mathcal{L}(\rho) = \frac{\gamma}{2}(\sigma_{\mathbf{n}}\rho\sigma_{\mathbf{n}} - \rho)$?

Result 2: Rank-one Pauli noise can be corrected without cancelling the evolution completely, but slowing it down:

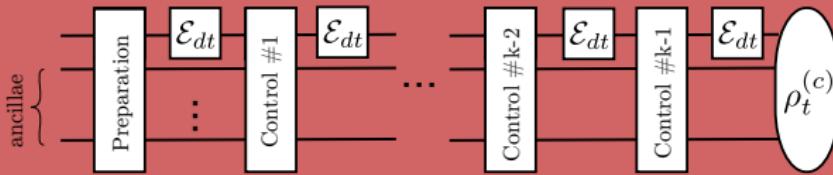
$$\omega \rightarrow \sqrt{1 - (\mathbf{n} \cdot \mathbf{z})^2} \omega$$

$$\rho_{t+dt} = \rho_t(1 - \frac{\gamma}{2}dt) - idt \frac{\omega}{2} [\sigma_{\mathbf{n}}, \rho_t] + dt \frac{\gamma}{2} \sigma_1 \rho_t \sigma_1 + O(dt^2)$$

$$\Pi_C \rho_{t+dt} \Pi_C + \sigma_1 \Pi_E \rho_{t+dt} \Pi_E \sigma_1$$

$$\rho_{t+dt} = \rho_t - idt \frac{\sqrt{1-(\mathbf{n}\cdot\mathbf{z})^2}\omega}{2} [\sigma_3, \rho_t] + O(dt^2)$$

		noise	
		$\sigma_1 \rho_t \sigma_1$	\longrightarrow
evolution	$[\sigma_{\mathbf{n}}, \rho_t]$	$ 0_q 0_a\rangle$	$ 1_q 0_a\rangle$
	\circlearrowleft	$ 1_q 1_a\rangle$	$ 0_q 1_a\rangle$
		Code space	Error space



What about rank-one Pauli noise $\mathcal{L}(\rho) = \frac{\gamma}{2}(\sigma_{\mathbf{n}}\rho\sigma_{\mathbf{n}} - \rho)$?

Result 2: Rank-one noise can be removed without cancelling the error term:

Yes we can!

Barack Obama smiling.

$$\rho_{t+dt} = \rho_t + i\sigma_1\rho_t\sigma_1 - idt[\sigma_3, \rho_t] + \frac{-(\mathbf{n}\cdot\mathbf{z})^2\omega}{2}[\sigma_3, \rho_t] + O(dt^2)$$

$$\Pi_C \rho_{t+dt} \Pi_E = \rho_{t+dt} \Pi_E \sigma_1$$

noise

$\sigma_1 \rho_t \sigma_1$		
$[\sigma_{\mathbf{n}}, \rho_t]$	$ 0_q 0_a\rangle$	$ 1_q 0_a\rangle$
	$ 1_q 1_a\rangle$	$ 0_q 1_a\rangle$
evolution		
	Code space	Error space

Scaling of the QFI

Rank-one Pauli noise

$$\mathcal{F}_{\mathbf{n}} = t^2(1 - (\mathbf{n} \cdot \mathbf{z})^2)$$

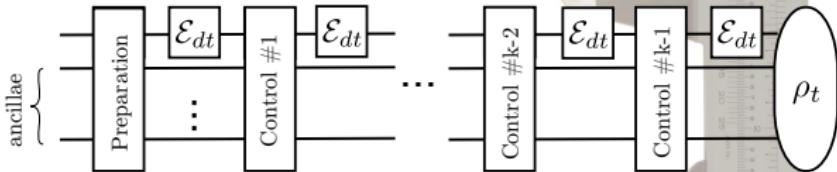
Any other noise

$$\mathcal{F}_{\mathcal{L}} \leq 4 \alpha_{\mathcal{L}} t$$



Attainable precision (free repetitions)

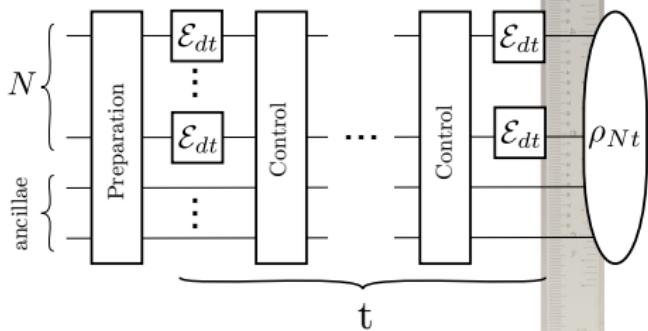
1. Time-particles



$$\nu\delta\omega^2 \geq \frac{1}{(1-(\mathbf{n}\cdot\mathbf{z})^2)t^2}$$

$$\nu\delta\omega^2 \geq \frac{1}{4\alpha_{\mathcal{L}} t}$$

2. Frequency estimation



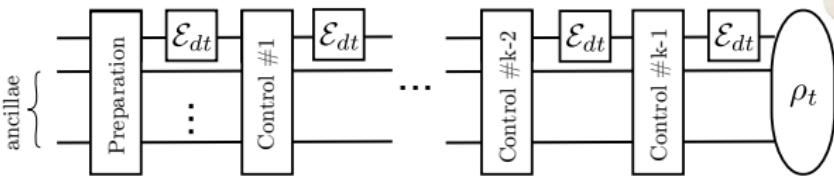
$$T\delta\omega^2 \geq \frac{1}{4\alpha_{\mathcal{L}} N}$$

$$T\delta\omega^2 \geq \frac{1}{(1-(\mathbf{n}\cdot\mathbf{z})^2)N^2 t}$$

with

$$T := \nu t \gg t$$

Attainable precision (single-shot)



Bayesian Cramer-Rao

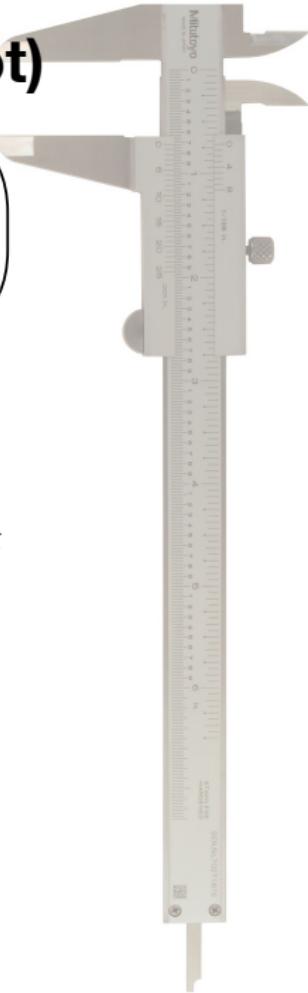
Ziv-Zakai (for QFI)

$$\langle \delta\omega^2 \rangle \geq \frac{1}{4\alpha_{\mathcal{L}} t + \mathcal{F}(p(\omega))}$$

$$\langle \delta\omega^2 \rangle \geq \frac{1}{12\alpha_{\mathcal{L}} t}$$

Explicit strategy for interval prior

$$\langle \delta\omega^2 \rangle \leq \frac{165}{(1 - (\mathbf{n} \cdot \mathbf{z})^2)t^2}$$



3.Qunatum control for metrology with limited resources



FFQC with limited ressource

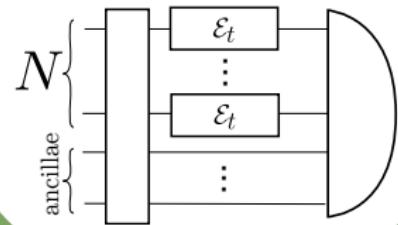
Lindbladian: X-Y noise

$$\mathcal{L}(\rho) = \frac{\gamma}{2}(p\sigma_1\rho\sigma_1 + (1-p)\sigma_2\rho\sigma_2 - \rho)$$

Sequential strategy with
2 qubits and FFQC



Parallel strategy with
N qubits and ancillae

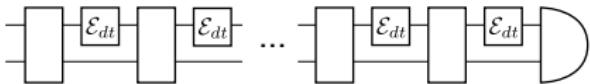


FFQC with limited ressource

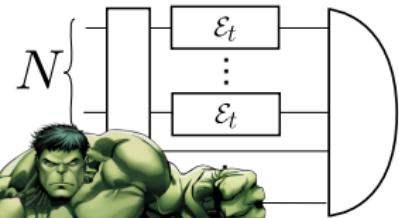
Lindbladian: X-Y noise

$$\mathcal{L}(\rho) = \frac{\gamma}{2}(p\sigma_1\rho\sigma_1 + (1-p)\sigma_2\rho\sigma_2 - \rho)$$

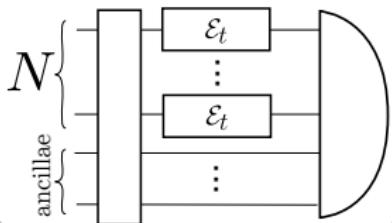
Sequential strategy with
2 qubits and FFQC



Parallel strategy with
N qubits and ancillae



Parallel strategy with
N qubits and ancillae



1. Solve the master equation

2. Optimize the bound numerically for a fixed t

$$\mathcal{F}(t) \leq \hat{\mathcal{F}}_{N,t} = 4N \|\alpha(t)\| + 4N(N-1) \|\beta(t)\|^2$$

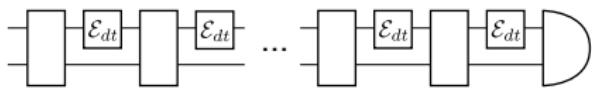
3. Optimize over t

$$\hat{f}_N = \max_t \frac{\hat{\mathcal{F}}_{N,t}}{tN}$$



		noise	
		$p : \sigma_1 \rho \sigma_1$	$(1 - p) : \sigma_2 \rho \sigma_2$
evolution	$[\sigma_3, \rho]$	$ 0_q 0_a\rangle$	$ 1_q 0_a\rangle$
		$ 1_q 1_a\rangle$	$ 0_q 1_a\rangle$

Code space Error space



$$\mathcal{L}(\rho) = \frac{\gamma}{2}(p\sigma_1\rho\sigma_1 + (1-p)\sigma_2\rho\sigma_2 - \rho)$$

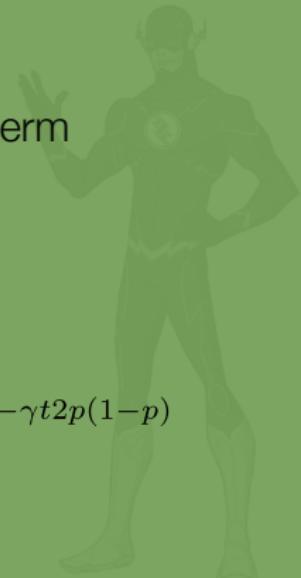
Sequential strategy with
2 qubits and FFQC

Detect the noise & Correct the most probable term

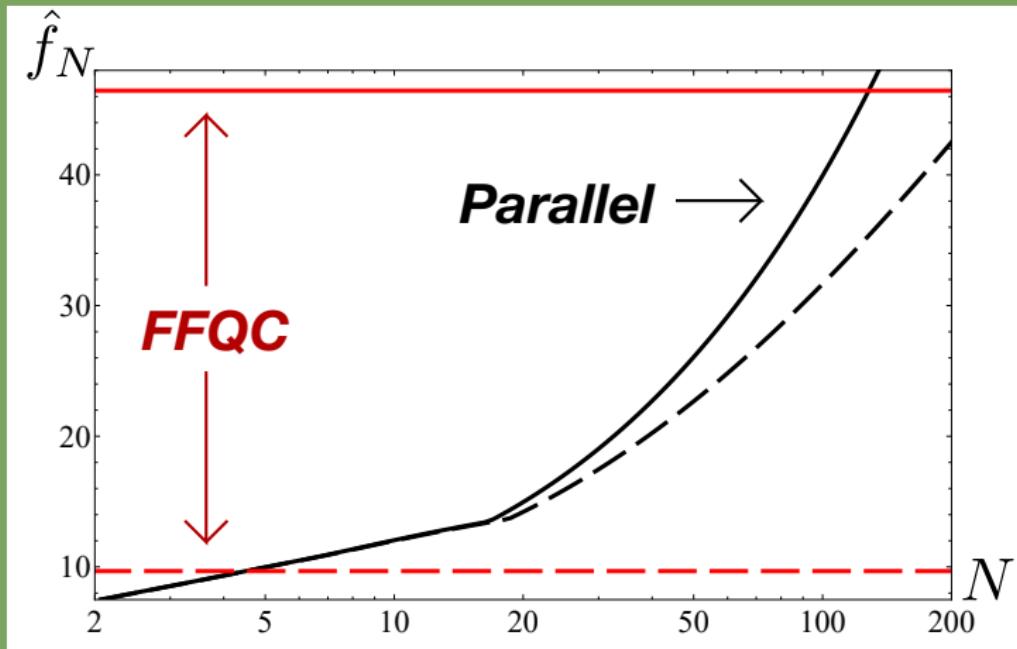
$$\rho_t = \bigoplus_m p(m; t) U_t \rho_m U_t^\dagger$$

Measure out the qubit at the optimal time

$$\mathcal{F}_t = t^2 \sum_m p(m; t) \mathcal{F}(\rho_m) = t^2 e^{-\gamma t 2p(1-p)}$$

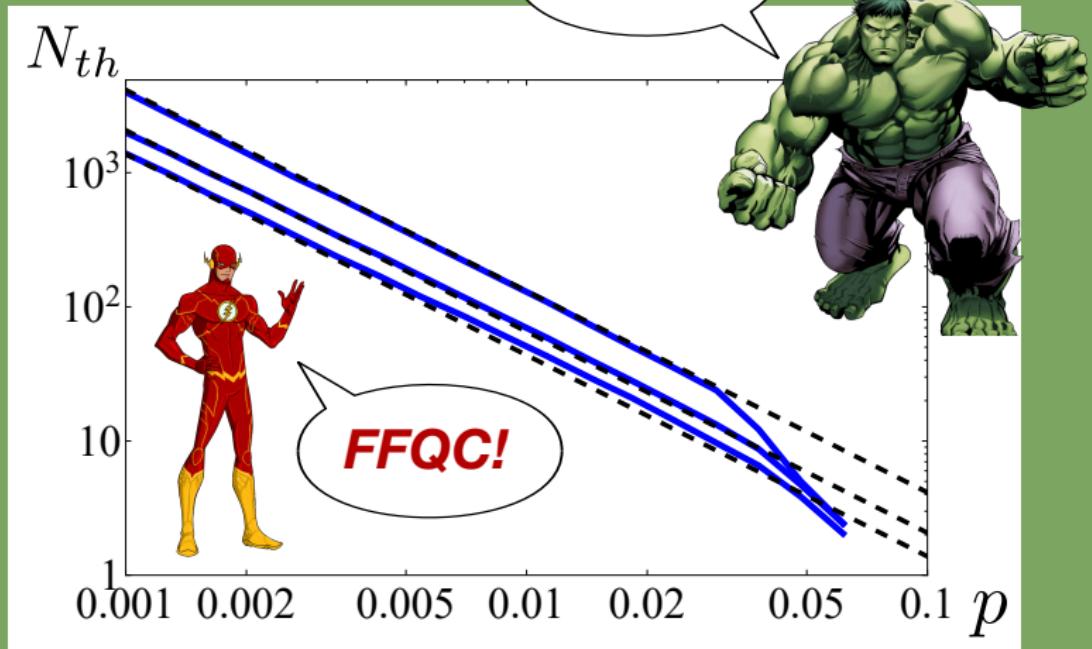


Comparision



For $p= 0.01$ (solid) and $p= 0.05$ (dashed)

Comparision

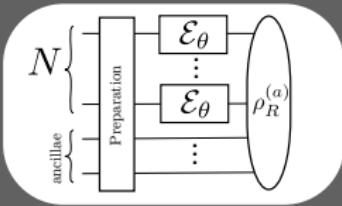


For $\omega = 2$ and $\gamma = \{0.1, 0.2, 0.3\}$

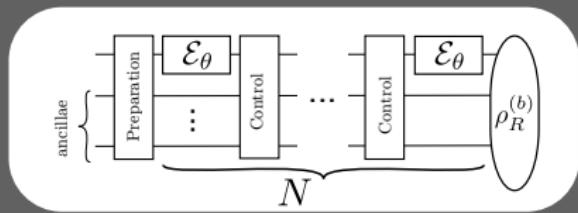
4 .Role of intermediate control for phase estimation



Phase estimation



parallel

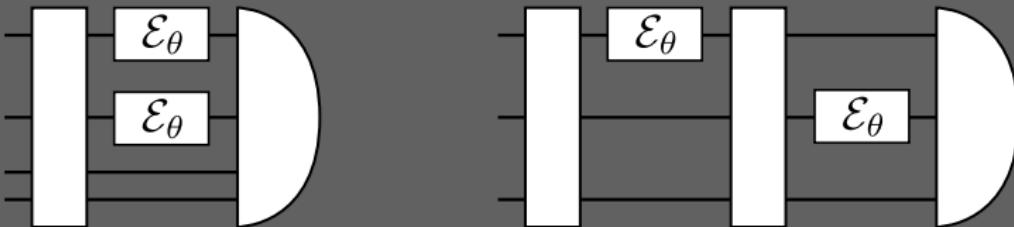


sequential

Is there an improvement?

Simple example

Two qubits and two ancilae



X-Y noise channel

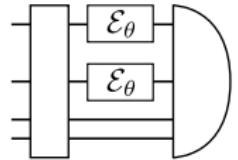
$$\mathbf{K} = (\sqrt{p} U_\theta, \sqrt{\frac{1-p}{2}} \sigma_1, \sqrt{\frac{1-p}{2}} \sigma_2) \simeq (\sqrt{p} U_\theta, \sqrt{1-p} |1\rangle\langle 0|, \sqrt{1-p} |0\rangle\langle 1|)$$

Optimal encoding

$$|0\rangle \rightarrow |0_q 0_a\rangle$$

$$|1\rangle \rightarrow |1_q 1_a\rangle$$

Find the optimal entangled state



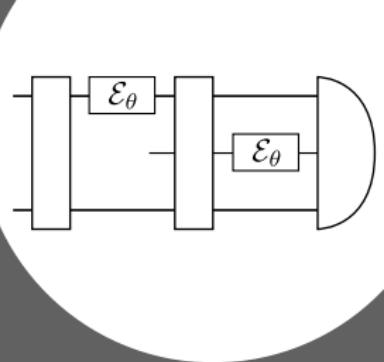
$$\begin{aligned} |\psi\rangle_{opt} = & \sqrt{\frac{x_{opt}}{2}}(|00\rangle_Q|00\rangle_S + |11\rangle_Q|11\rangle_S) \\ & + \sqrt{\frac{1-x_{opt}}{2}}(|01\rangle_Q|01\rangle_S + |10\rangle_Q|10\rangle_S) \end{aligned}$$

The corresponding QFI

$$\mathcal{F} = \begin{cases} -\frac{(p-2)^2 p}{2(p-1)} & p \leq \frac{2}{3} \\ 4p^2 & otherwise. \end{cases}$$

Prepare the first qubit

$$|\psi\rangle_1 = \sqrt{\frac{1}{2}}(|0\rangle_{Q_1}|0\rangle_A + |1\rangle_{Q_1}|1\rangle_A)$$



Read out the error syndrome

E: Prepare the same state
for the second qubit.

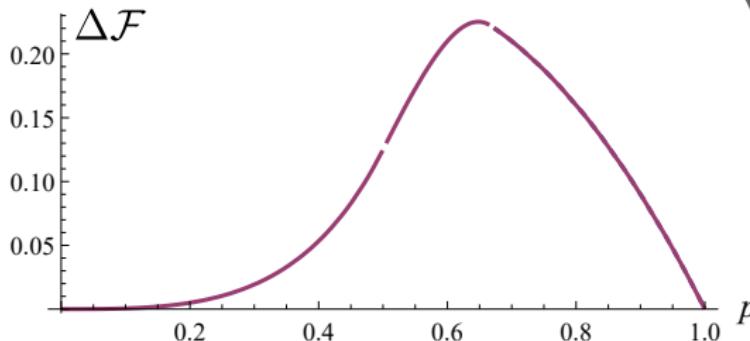
$$|\psi\rangle_2 = \sqrt{\frac{1}{2}}(|0\rangle_{Q_2}|0\rangle_A + |1\rangle_{Q_2}|1\rangle_A)$$

C: Entangle the second qubit
with the first one.

$$\begin{aligned} &\sqrt{\frac{1}{2}} \left(e^{-i\frac{\theta}{2}} |0\rangle_{Q_1} (\sqrt{y}|00\rangle_{Q_2,A} + \sqrt{1-y}|11\rangle_{Q_2,A}) \right. \\ &\quad \left. + e^{i\frac{\theta}{2}} |1\rangle_{Q_1} (\sqrt{y}|11\rangle_{Q_2,A} + \sqrt{1-y}|00\rangle_{Q_2,A}) \right) \end{aligned}$$

Prepare ψ'

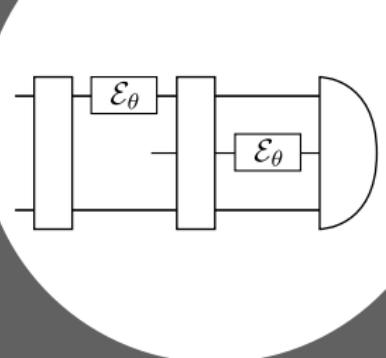
$|\psi\rangle_1 =$



$|\psi\rangle_2 =$

angle the second qubit
with the first one.

$$\left(\sqrt{y}|00\rangle_{Q_2,A} + \sqrt{1-y}|11\rangle_{Q_2,A} \right) \\ + e^{-i\theta} |1\rangle_{Q_1} \left(\sqrt{y}|11\rangle_{Q_2,A} + \sqrt{1-y}|00\rangle_{Q_2,A} \right)$$



1. Scaling of the QFI in presence of noise. Implications for precision.
2. Role of FFQC for metrology with limited resources.
3. Role of intermediate control for phase estimation.

