Recent Advances in Quantum Metrology



Precision limits for frequency estimation in open quantum systems

Andrea Smirne & Susana Huelga



ulm university universität **UUUM**

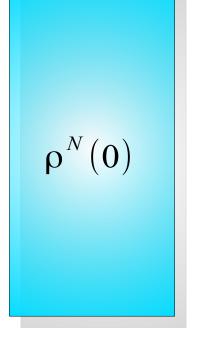
In collaboration with: R. Demkowicz-Dobrzański, Univ. Warsaw J. Kołodyński, ICFO-Barcelona

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Introduction

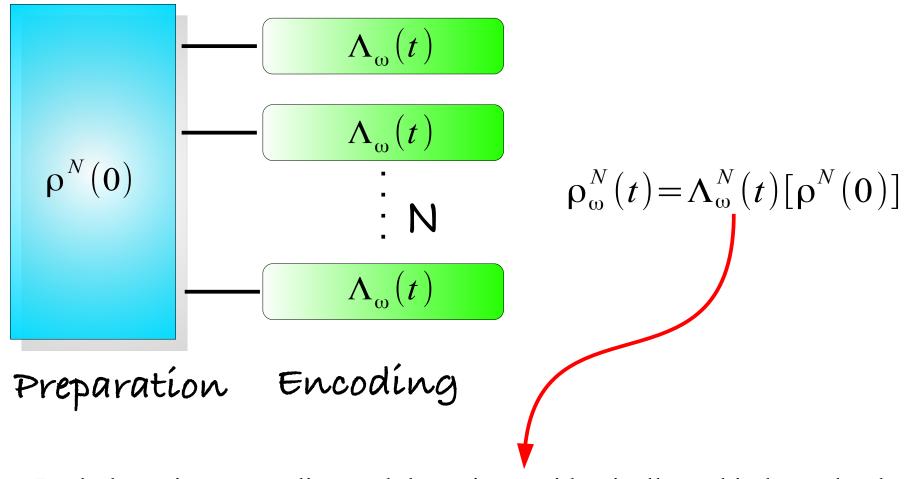
- General framework for frequency estimation
- SQL vs HL in the noiseless scenario
- Recent no-go theorems for noisy estimation

Noisy frequency estimation



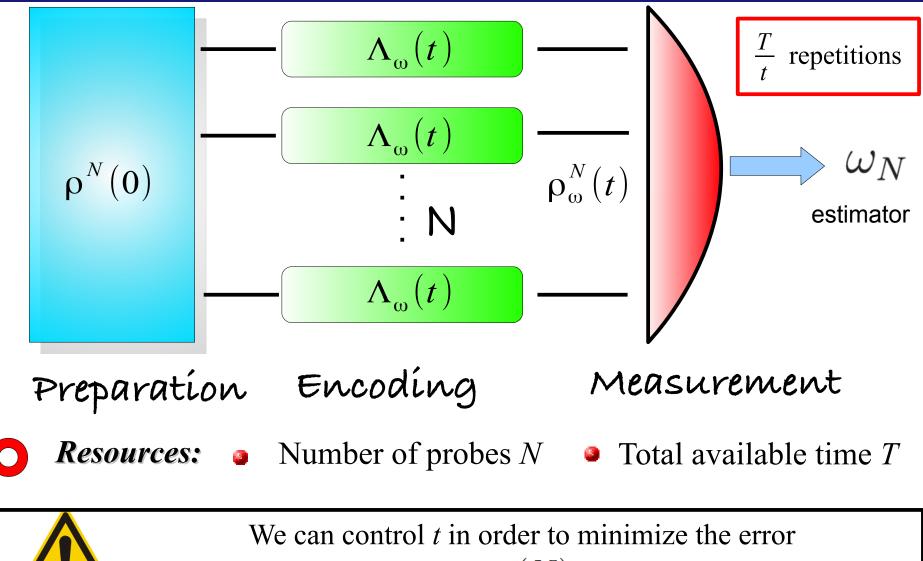
Preparation

Noisy frequency estimation



• Both the unitary encoding and the noise act identically and independently on the N probes: CPTP maps $\left\{\Lambda_{\omega}^{(N)}(t) = [\Lambda_{\omega}(t)]^{\otimes N}\right\}_{t \ge 0}$

Noisy frequency estimation



The optimal evaluation time $t_{opt}(N)$ will generally depend on N!!

Semigroup noise: back to the SQL

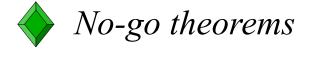
Noiseless scenario
$$\Delta^2 \omega_N T = \frac{1}{Nt}$$
 vs $\Delta^2 \omega_N T = \frac{1}{N^2 t}$
Giovannetti, Lloyd & Maccone SQL HL HL
Science 306, 1330 (2004)

Semigroup noise $\dot{\rho}_{\omega}(t) = i \frac{\omega}{2} \left[\hat{\sigma}_z, \rho_{\omega}(t) \right] + \gamma \left(\hat{\sigma}_z \rho_{\omega}(t) \hat{\sigma}_z - \rho_{\omega}(t) \right)$ Huelga, et.al PRL 79, (1997)

• Recent techniques to evaluate QFI Demkowicz, Kolodynski & Guta Nat. Comm. 3, (2012) • QCRB • Lower bound to $\Delta^2 \omega_N$ $\max_{\rho} F_Q[\Lambda_{\omega}(\rho)] \leq 4N \min_{\{K_i\}} (\|A\| + (N-1)\|B\|^2)$

Can be evaluated by means of SDP !!

Kolodynski &Demkowicz NJP 15, 073043 (2013)

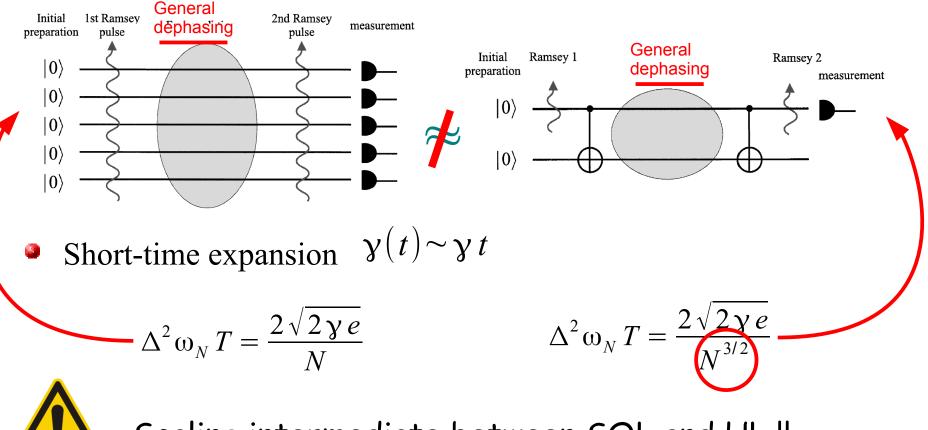


$$\frac{\Delta \omega_N|_{ent}}{\Delta \omega_N|_{sep}} = C > 1 \quad --- \quad \text{Independent} \\ \text{from N}$$

Beyond semigroup:a new limit for metrology?

•
$$\gamma \longrightarrow \gamma(t) = \int_0^\infty d\omega J(\omega) \coth\left(\frac{\beta\omega}{2}\right) \frac{\sin(\omega t)}{\omega}$$

Chin, Huelga & Plenio PRL 109, 233601 (2012)



Scaling intermediate between SQL and HL !!

How general is this limit ? Can we go beyond it?

- Initial state preparation
- Measurement procedure
- For which open system's dynamics ?
- Beyond the short-time regime: any role of *proper* non-Markov?

A. Smirne, J. Kolodynski, S. Huelga & R. Demkowicz-Dobrzanski ArXiv: 1511.02708 (2015); to appear in PRL

Phase covariant dynamical maps

I.I.C. noise
$$\Lambda^{(N)}(t) = (\mathcal{U}_{\omega}(t) \circ \Gamma(t))^{\otimes N}$$
$$e^{-\frac{i}{2}\omega\sigma_{z}t} \bullet e^{\frac{i}{2}\omega\sigma_{z}t} \quad [\mathcal{U}_{\omega}(t), \Gamma(t)] = 0 \quad \forall t$$

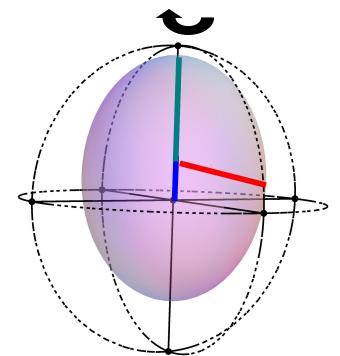
Unitary frequency encoding

 $-\omega$ - independent noise map

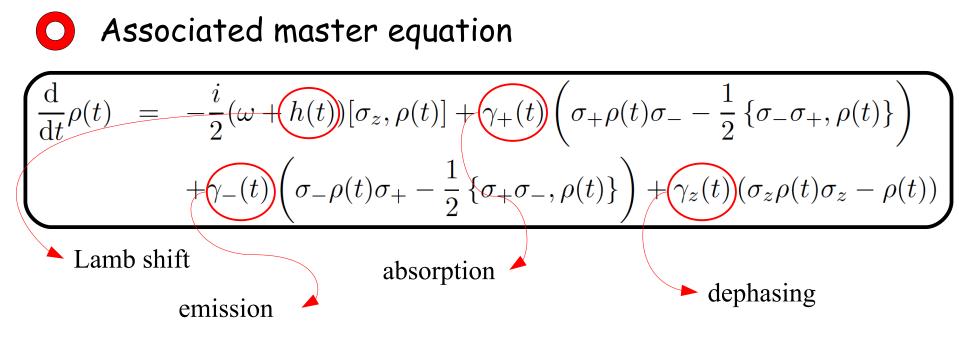
Key property to have SQL with semigroup noise

Hilbert-Schmidt matrix representation

$$\Lambda^{\mathsf{C}}_{\omega} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \eta_{\perp} \cos \psi & -\eta_{\perp} \sin \psi & 0 \\ 0 & \eta_{\perp} \sin \psi & \eta_{\perp} \cos \psi & 0 \\ \kappa & 0 & 0 & \eta_{\parallel} \end{pmatrix}$$
$$\mathsf{CP} \begin{array}{l} \eta_{\parallel} \pm \kappa \leq 1 \\ 1 + \eta_{\parallel} \geq \sqrt{4\eta_{\perp}^{2} + \kappa^{2}} & \omega t + \theta \end{array}$$



Physical meaning



- Commutation of *linear maps*
- Broken by counter-rotating terms, transversal noise Chaves & al. PRL 111, 120401 (2013)
- U(1) covariant semigroups B. Vacchini, Lect. Notes Phys. 787, 39 (2010)



Fully general time-inhomogeneities and memory effects *are included*

Metrological limit for IIC dynamics

Given any N-qubit IIC dynamics, if

$$\eta_{\perp}(t) \neq 1 \qquad \forall t > 0$$
the uncertainty on the estimated frequency satisfies

$$\lim_{N \to \infty} \frac{\Delta^2 \omega_N T}{N^{-(2\beta_{\perp} - 1)/\beta_{\perp}}} \ge D$$

- Scaling fixed by the short-time expansion $\eta_{\perp}(t) = 1 c_{\perp}t^{\beta_{\perp}} + o(t^{\beta_{\perp}})$
- From the SQL ($\beta_{\perp} = 1$) toward the HL with the growing of $\beta_{\perp} \begin{vmatrix} D N^{-3/2} \\ \text{for } \beta_{\perp} = 2 \end{vmatrix}$
- Constant D > 0 fixed by the expansions of all the coefficients

$$D = \frac{c^{1/\beta_{\perp}}\beta_{\perp}}{(\beta_{\perp}-1)^{(\beta_{\perp}-1)/\beta_{\perp}}} \qquad c = \begin{cases} 2c_{\perp} & \beta_{\perp} < \beta_{\parallel};\\ 2c_{\perp}-\frac{c_{\parallel}}{2} & \beta_{\perp} = \beta_{\parallel} < \beta_{\kappa};\\ \max\left\{2c_{\perp}-\frac{c_{\parallel}}{2}-\frac{|c_{\kappa}|}{2},\frac{|c_{\kappa}|}{4}\right\} & \beta_{\perp} = \beta_{\parallel} = \beta_{k}. \end{cases}$$

Metrological limit for IIC dynamics

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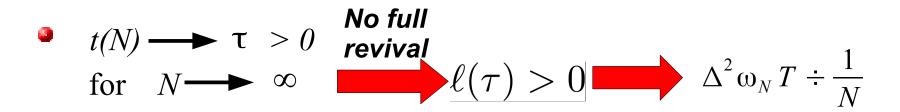
- Scaling fixed by the short-time expansion $\eta_{\perp}(t) = 1 c_{\perp} t^{\beta_{\perp}} + o(t^{\beta_{\perp}})$
- From the SQL ($\beta_{\perp} = 1$) toward the HL with the growing of β_{\perp}
- Constant D > 0 fixed by the expansions of all the coefficients

No full revivals $\# \eta_{\perp}(t) = 1$ implies (due to CP) $\eta_{\parallel}(t) = 1 \kappa(t) = 0$ *Rotation by a generic angle* $\psi(t)$ *about the z-axis : noiseless HL!!*

Mini sketch of the proof

Unital dynamics *k(t)=0,* i.e. no translation of the Bloch sphere

$$\Delta^2 \omega_N T \ge \min_t \frac{1 + N\ell(t)}{tN^2} \xrightarrow{1 + \eta_{\parallel}(t) - 2\eta_{\perp}(t)^2}{2\eta_{\perp}(t)^2}$$



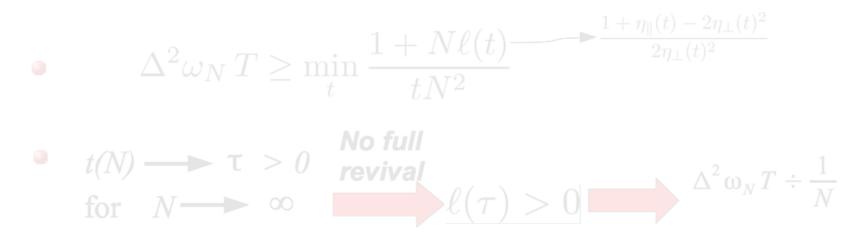
Mini sketch of the proof

- **Unital** dynamics *k(t)=0,* i.e. no translation of the Bloch sphere
 - $\Delta^{2}\omega_{N} T \geq \min_{t} \frac{1 + N\ell(t)}{tN^{2}} \xrightarrow{1 + \eta_{\parallel}(t) 2\eta_{\perp}(t)^{2}}{2\eta_{\perp}(t)^{2}}$ $t(N) \longrightarrow \tau > 0$ for $N \longrightarrow \infty$ No full revival $\ell(\tau) > 0$ $\Delta^{2}\omega_{N} T \div \frac{1}{N}$
 - We can beat the SQL only in the short-time regime: leading order expansion plus CPTP constraints

$$t_{\rm opt}(N) = (\mathbf{C} (\beta_{\perp} - 1)N)^{-1/\beta_{\perp}}$$

Mini sketch of the proof

Unital dynamics *k(t)=0,* i.e. no translation of the Bloch sphere



We can beat the SNL only in the short-time regime: leading order expansion plus CPTP constraints

 $t_{\rm opt}(N) = (\mathbf{c}(\beta_{\perp} - 1)N)^{-1/\beta_{\perp}}$

General case: convexity of the bound on the QFI for any N

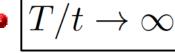
$$\Lambda_{\eta_{\parallel},\eta_{\perp},\kappa} = p\Lambda_{\tilde{\eta}_{\parallel},\tilde{\eta}_{\perp}} + (1-p)\Lambda_{\tilde{\kappa}}$$

generic covariant

unital

amplitude damping

Attainability of the bound



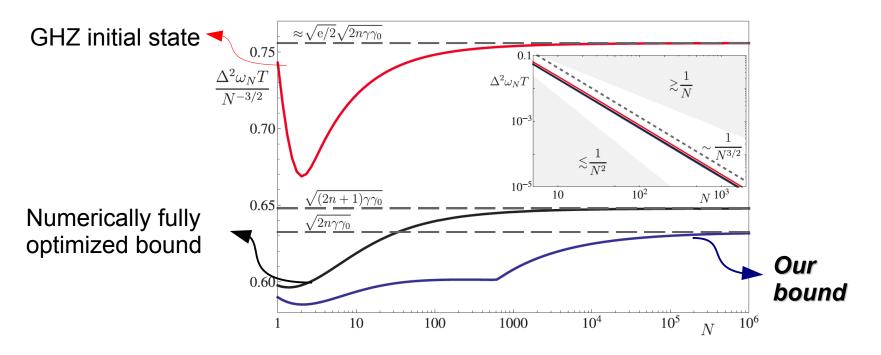
QCRB is saturable



Asymptotically always attainable, at worst up to a constant factor !

QFI for GHZ derived

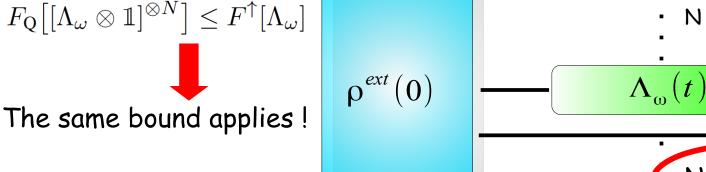
- Shabani-Lidar post-Markovian model: general covariant dynamics Phys. Rev. A 71, 020101 (2005)
 - γ dissipation constant γ_0 memory rate n excitations in E



Generalization to single-step EC

Pure dephasing: proof of the conjecture of Chin, Huelga & Plenio PRL 109 (2012) k=0; $n_{\parallel}=1$ recently verified in Macieszczak PRA 92, 010102 (R) (2015)

Single-step error correction





What happens with multi-step EC?

Semigroup: Demkowicz & Maccone PRL 113 (2014)

N ancillas

 $\Lambda_{\omega}(t)$

Beyond: open question!

Non-Markovíaníty and Zeno regime-

Non-Markovianity of quantum dynamics

O Several definitions, based on different *divisibility properties*

$$\Lambda(t) = \Lambda(t, s) \Lambda(s) \qquad t \ge s \ge 0$$

propagators (in general, not even P!)

• $\Lambda(t,s)$ are CP \longleftrightarrow the dynamics is Markovian • TLME with positive rates at any time Rivas, Huelga, Plenio PRL 105, 050403 (2010)

- $\Lambda(t,s) = \Lambda(t-s)$ *time homogeneous dynamics* Semigroup composition of CP maps! Lindblad,...
- Witnesses (i.e. sufficient conditions) for non-Markovianity
 Breuer, Laine, Piilo PRL 103, 210401 (2009)
 NM related to a *back-flow of information* to S

(No) role of non-Markovianity



Can the back-flow of information about ω lead to an improved precision scaling?



$$t_{opt}(N) \rightarrow 0 \quad (as \ N^{-1/\beta_{\perp}})$$

$$\bigcirc \text{ The best strategy calls for measurement on the short-time scale}$$

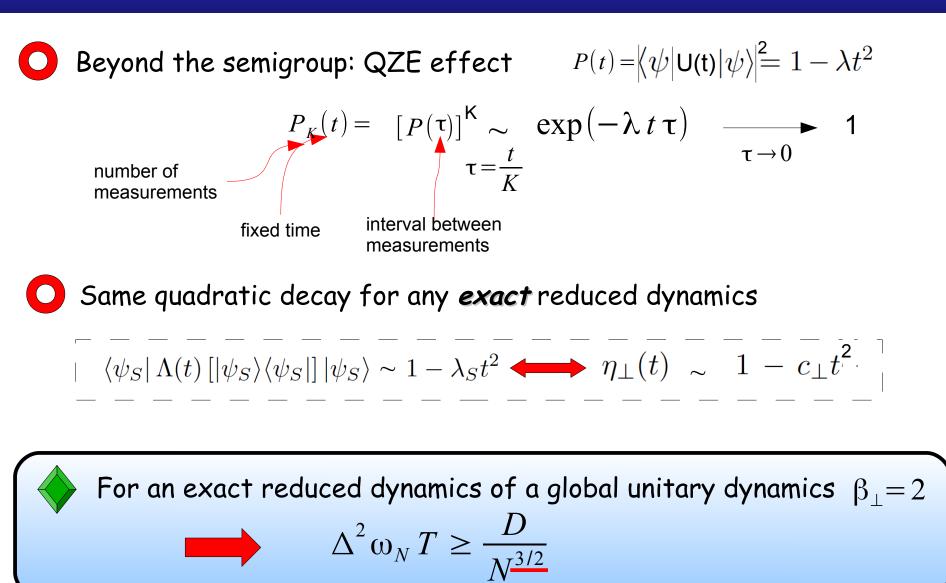
$$\bigcirc \text{ On longer times, necessarily SQL } 1/N$$

The crucial feature to beat the SQL with IIC dynamics is **violation of semigroup (i.e. time inhomogeneity)** $\Lambda(t+s) \neq \Lambda(t)\Lambda(s)$

at short time-scales

This is the case also in the *finite-N* regime

Zeno regime



Conclusions and outlooks

- We derived a *general bound* to the precision in the frequency estimation for a wide and well-defined class of dynamics (*I.I.C.*)
- Attainability: entanglement of the probes allows to beat the SQL also in the presence of realistic noise, which nevertheless limits the precision below the HL
- Emergence of super-classical scaling due to *time-inhomogeneity* (non-exponential decays); NM does not allow further improvement
- Inclusion of NM non phase-covariant noise and general (multi-steps) error-correction techniques, where NM could play a relevant role
- O Detailed analysis of the *small-N regime*, also in view of possible experimental realizations



Permanent Staff Prof. Martin Plenio Prof. Susana Huelga

Visiting Professors

Prof. Jochen Rau Prof. Luca Turin

Postdocs

Dr Martin Bruderer Dr Jorge Casanova Dr Felipe Caycedo Dr Qiong Chen Dr Marcus Cramer Dr Myung-Joong Hwang Dr Nathan Killoran Dr Kero Lau Dr Jaemin Lim Dr Mauricio Matera Dr Andrea Smirne Dr Bobo Wei Dr Cheng-Yu Wang

PhD students Mr Pelayo Fernandez-Acebal Mr Dario Egloff Mr Jan Haase Mr Milan Holzäpfel Mr Matthias Kost Mr Andreas Lemmer Mr Oliver Marty Mr Santiago Oviedo Mr Ricardo Puebla-Antunes Mr Robert Rosenbach Mr Joachim Rosskopf Mr Chris Schröder Mr Ilai Schwarz

Master Students Mr Fabian Frie Mrs Maria Garcia

Mrs Maria Garcia Mr Matthias Kost Mr David Ing Mr Kike Miralles Mr Alexander Nüsserl

Academic Visitors

Dr Filippo Caruso (LENS, Florence) Dr Alex Chin (DAMTP, Cambridge) Prof. Mauro Paternostro (Queens, Belfast) Dr Javier Prior (UPC, Cartagena) Dr. Alex Retzker (Hebrew, Jerusalem) Dr Dario Tamascelli (Milan)

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